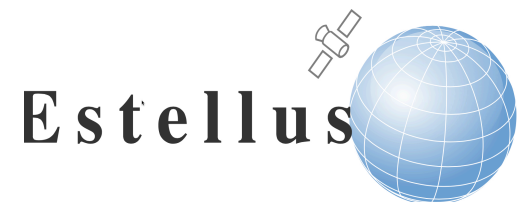


NN retrieval of soil moisture

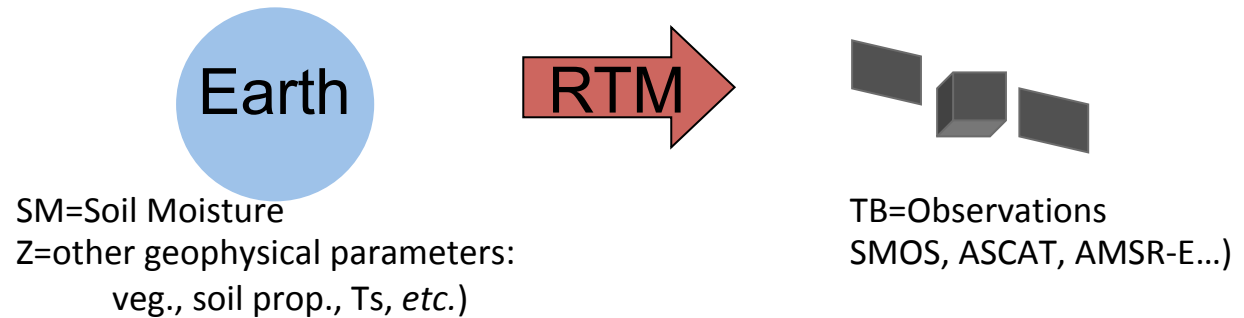
F. Aires, C. Prigent, N. Rodriguez-Fernandez,
J. Kolassa, C. Jimenez, P. De Rosnay, C.
Albergel, Y. Kerr

and co-authors...



Physical retrieval algorithm

- **Inverse problem:**



→ For each observation TB, we search SM such that: $RTM(SM,Z) = TB$
where RTM is Radiative Transfer Model

- **Classical approaches:** Iterative, Optimal Interpolation, Bayesian, etc.

$$SM^* = SM_{fg} + [A^t S_{\epsilon}^{-1} A + S_{fg}^{-1}]^{-1} A^t S_{\epsilon}^{-1} (TB_{\epsilon} - A \cdot SM_{fg})$$

- **Limitations:** requires simulations $RTM(X,Z)$ but uncertainties on:

- *A priori* information on surface parameters Z
- Radiative Transfer Model (RTM)

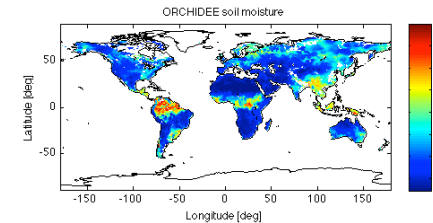
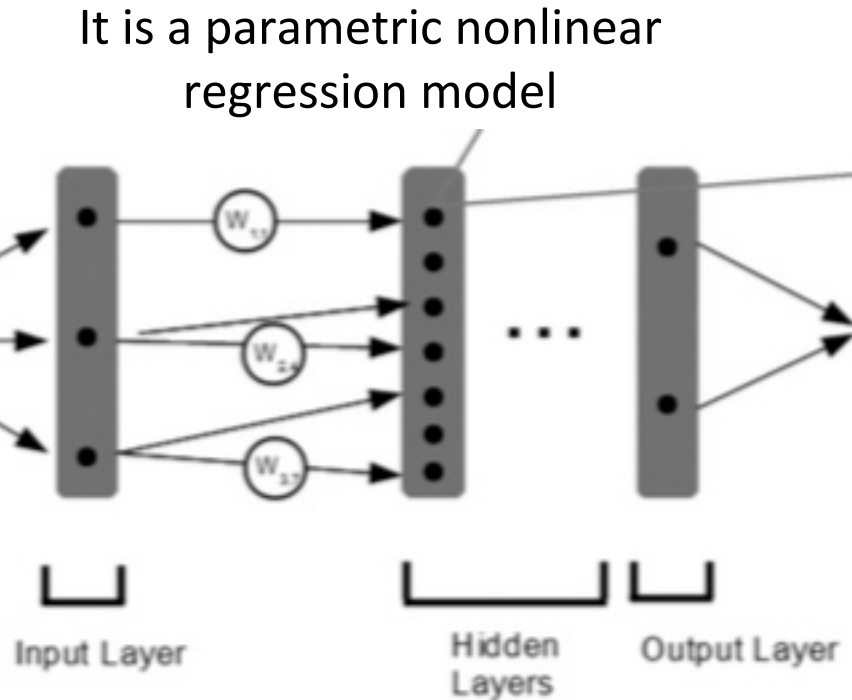
- **Question:** RTM modeling not satisfactory. Other solution?

Neural networks retrieval



Satellite
Observ.

Pre-
processing



SM
Retrieval

Remark: The NN model is applied at pixel level, not as image processing (≠deep learning)

Advantages/inconvenients

Advantages of NNs:

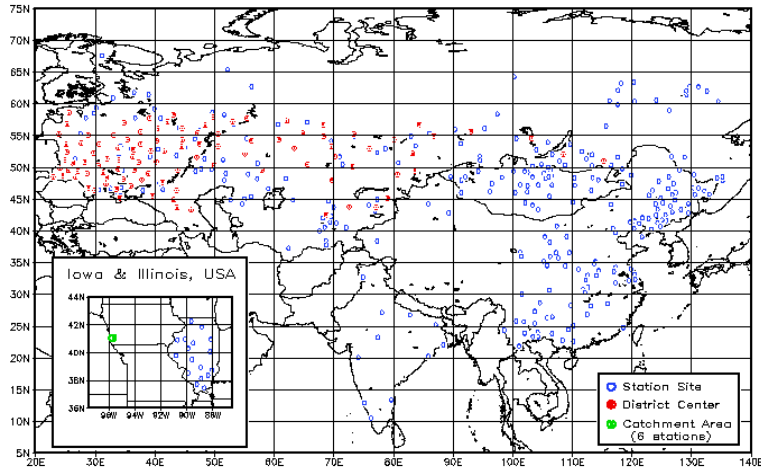
- *Fast* in operational mode, low memory required
- Multivariate, *high-dimension* space
- *Nonlinear*: situation-dependent, saturation effects
- *Flexible*: No rigid assumptions, can take realistic and complex specifications (FG, instr. noise, model errors, etc.) and various ways to introduce *a priori* information
- Global inversion model, no need for further inversion scheme
- Exploit *synergy*
- *Information content* tool to quantify the impact of: FG, noise, regime-dependence, number and location of channels, compression errors, fusion of information, *etc.*

Limitations of NNs:

- Needs to be *re-trained* if conditions change (new instrument, noise characteristics, etc.)
- **Need a high-quality *learning dataset***

Building a learning dataset: *in situ* solution

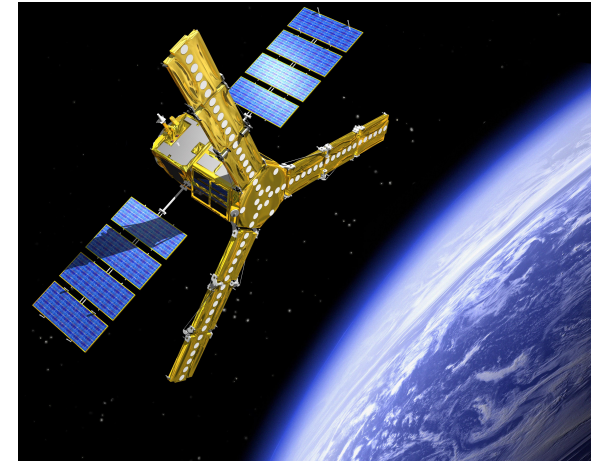
In situ measurements



Global Soil Moisture Data Bank
(Robock et al., BAMS, 2000)

Region	Stations	Surface	Frequency	Period	Depth
Illinois	19	grass	1-3/m	All year	10cm
Iowa	6	corn	2/m	Growing	7.8cm
Russia	171	cereal	3/m	All year	20cm
India	11	grass	4/m	All year	xxcm
Mongolia	42	Pasture	3/m	Spring	10cm
		Weat		summer	

Real satellite observations



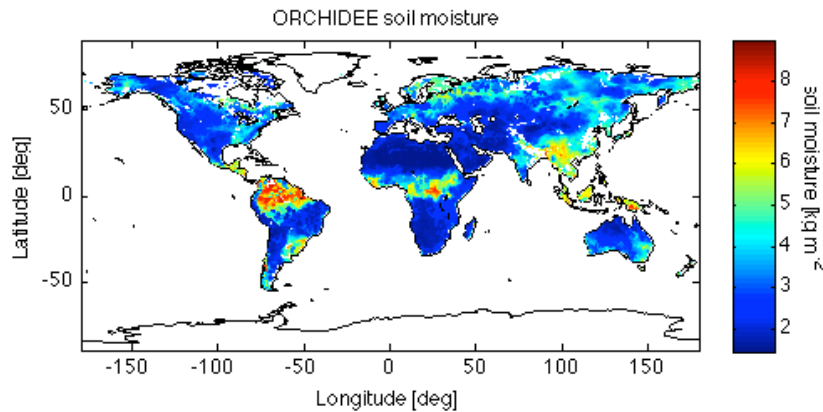
Coincidence

Problems:

- not enough *in situ* observations to represent well the spatial and temporal variability of soil moisture
- Spatial coherency of *in situ* data
- The measured SM might not be the same as what the satellite observes
- After launch only

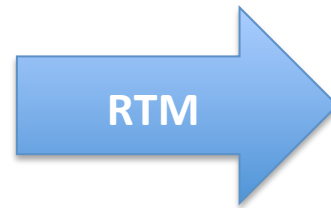
Building a learning dataset: RTM simulations

Global SM from model



- Multiple years
- Global coverage
- We choose the SM we want from the model

Simulated Observations



Advantage:

- Can be done before launch

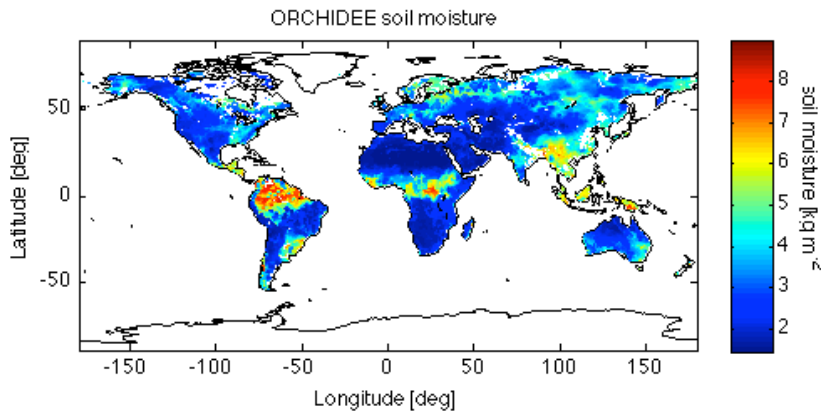
Problem:

- What is our confidence on the Radiative Transfer Model?

Building a new learning dataset for historical measurements

Global SM from retrieval

Real SMOS observations



- Multiple years
- Global coverage

Advantage:

- Independent from Surface Model

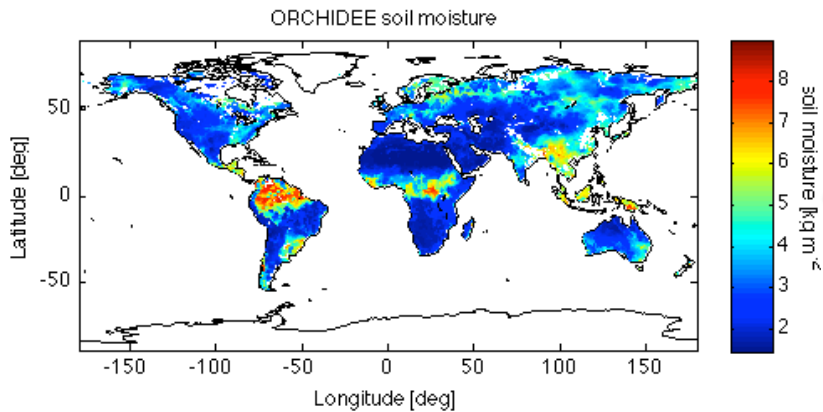
Problem:

- Need to rely on an *a posteriori* retrieval, which is based on a RTM

Building a learning dataset: Our approach

Global SM from model

Real satellite observations

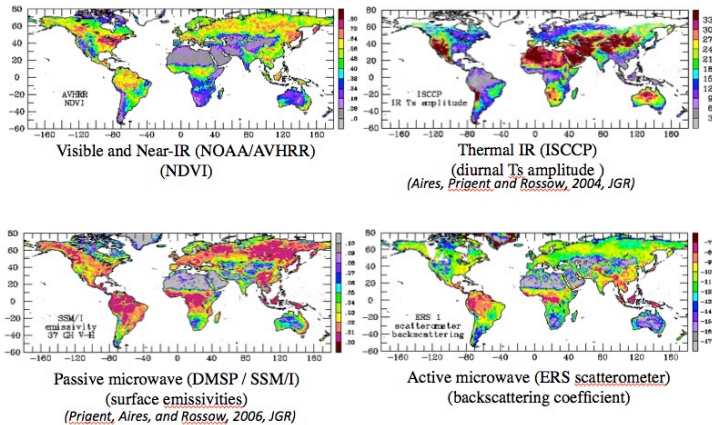


- Multiple years
- Global coverage
- We choose the SM we want from the model

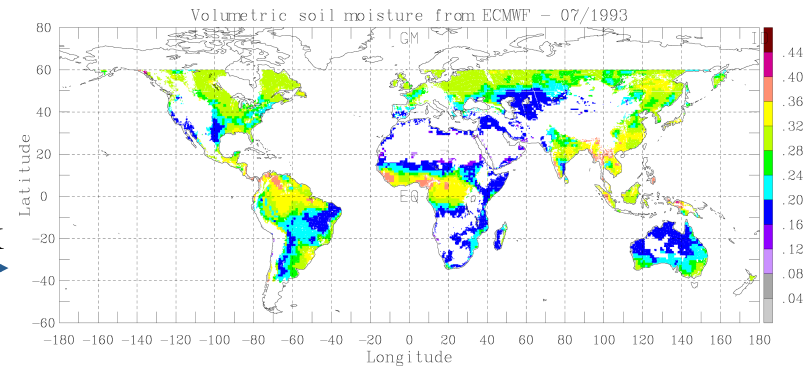
Problems/questions:

- Is the land model SM good enough?
- Are the SM really related to the Obs?
- Are we just reproducing the SM from the model when teaching the retrieval with this dataset?
- After launch only

NN approach



Neural Network



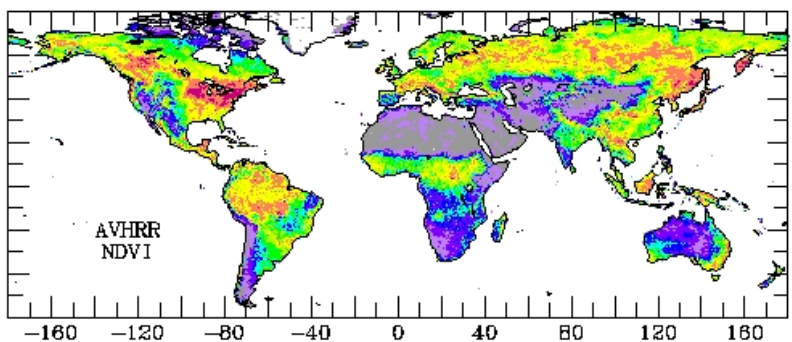
All available SM- information: visible, passive and active MW, thermal IR

Soil moisture from model (NCEP or ECMWF)

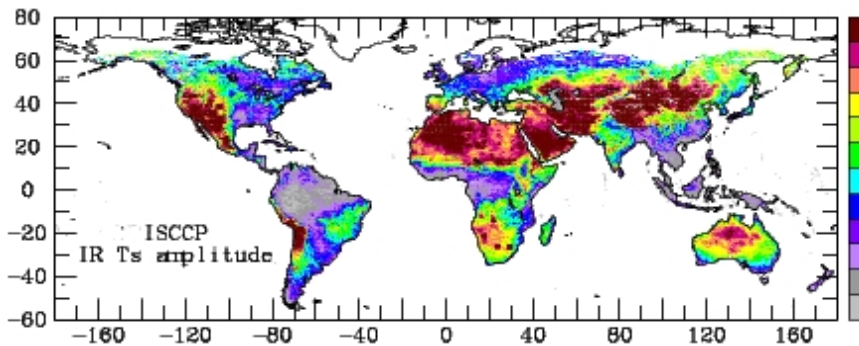
Applications:

- 1) **Information content analysis, and synergy**
- 2) **Remote sensing:** No need of RTM, or *in situ* measurements
- 3) **Consistency checking method:** Check consistency of model output with satellite observations, help model development
- 4) **Variational assimilation applications:** Define a link between observations and model (link coherent with model) but need to specify uncertainties

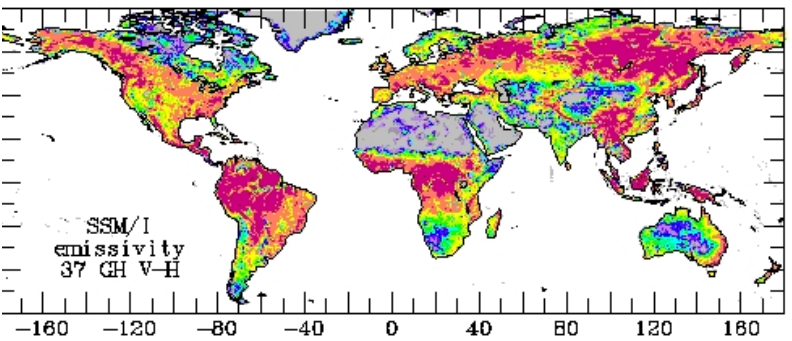
Application 1) – Information content & synergy



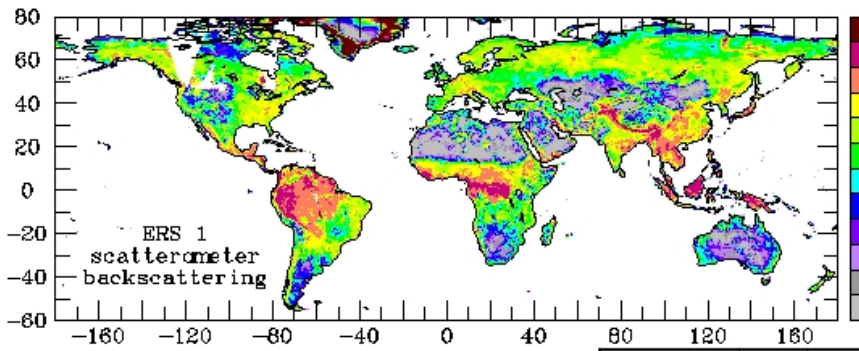
Visible and Near-IR (NOAA/AVHRR)
(NDVI)



Thermal IR (ISCCP)
(diurnal Ts amplitude)
(Aires, Prigent and Rossow, 2004, JGR)



Passive microwave (DMSP / SSM/I)
(surface emissivities)
(Prigent, Aires, and Rossow, 2006, JGR)



Active microwave (ERS scatterometer)
(backscattering coefficient)

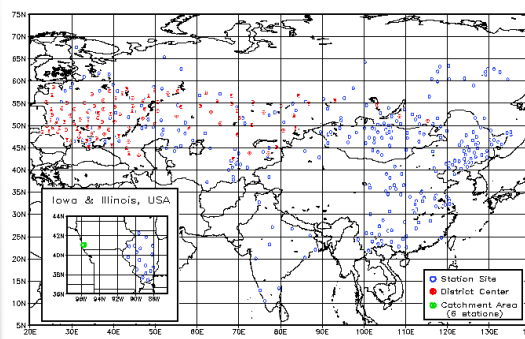
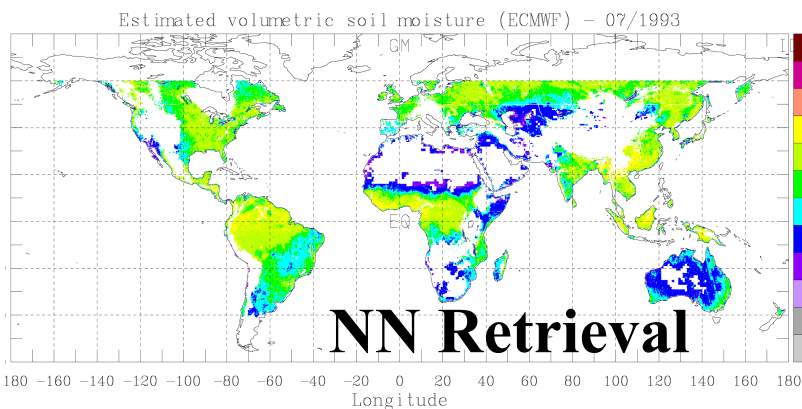
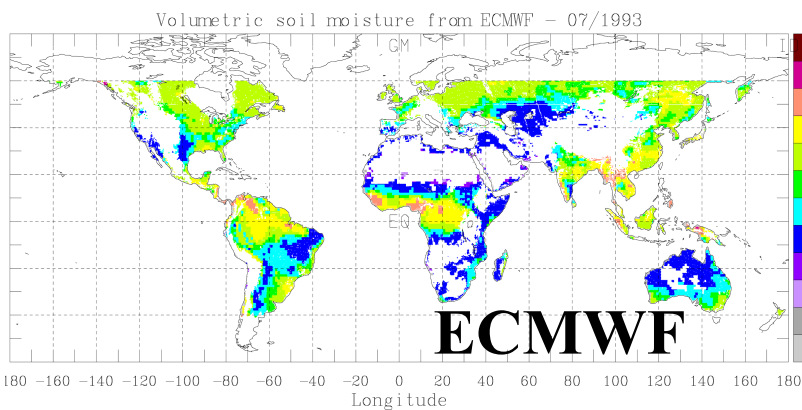
	RMS	CORR.	RMS	CORR.
Predictors	NCEP	NCEP	ECMWF	ECMWF
IR Norm Ts Amp.	0.059	0.753	0.057	0.633
ERS small ang.	0.055	0.792	0.054	0.676
NDVI	0.052	0.819	0.052	0.704
ERS large ang.	0.050	0.830	0.051	0.724
SSMI E37V-H	0.050	0.832	0.050	0.735
SSMI E19V-H	0.050	0.832	0.050	0.737
SSMI E19V	0.050	0.833	0.050	0.738
SSMI E85V-H	0.050	0.833	0.050	0.739

• Information content
• Data fusion and synergy

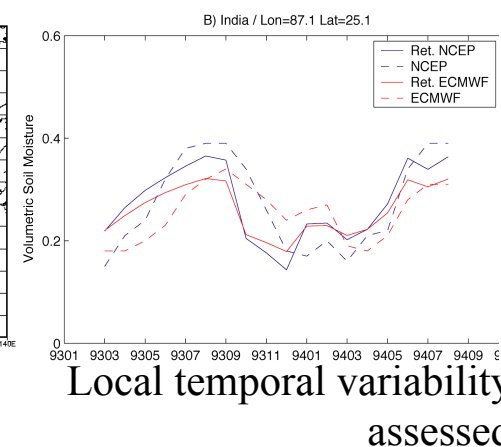
- Soil moisture at a global scale I, Prigent, Aires, Rossow, JGR, 2005
- Soil Moisture retrieval from multi-instrument observations: information content and retrieval methodology, Kolassa, Aires, Polcher, Prigent, Jimenez, Pereira, JGR, 2013
- Soil moisture retrieval from **AMSR-E and ASCAT** microwave observations synergy Part 1: Satellite data analysis, Kolassa, Gentine, Prigent, Aires, RSE, 2016

Application 2) - Soil moisture retrieval

Evaluation



Global Soil Moisture Data Bank, Robock et al., 2000



Network	spatial			temporal		
	NN	WACMOS	HTESSEL	NN	WACMOS	HTESSEL
ARM	0.65	0.59	0.48	0.09	0.49	0.71
CHINA	-	-	-	0.60	0.55	0.67
ICN	-	-	-	-0.46	0.50	0.70
MONGOLIA	0.62	0.14	0.50	0.51	0.43	0.46
SCAN	0.51	0.56	0.67	0.19	0.64	0.72
SNOTEL	-	-	-	0.46	0.61	0.70

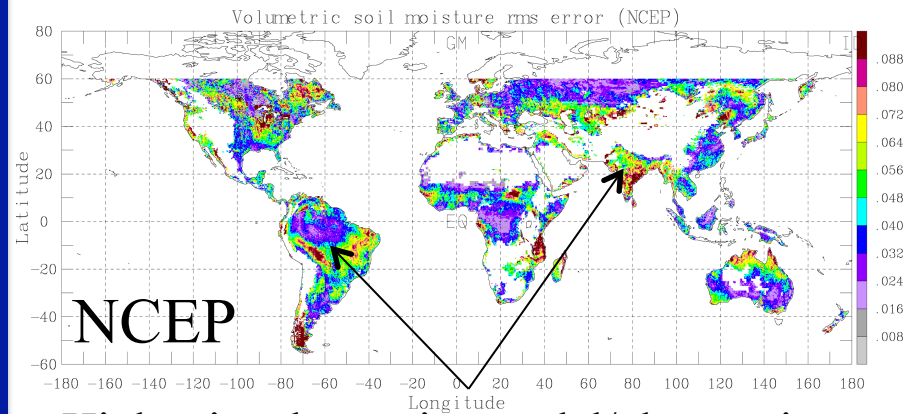
Local temporal variability assessed

Dataset	RMSE [kg m^{-2}]	σ [kg m^{-2}]	ρ_{spatial}	ρ_{seasonal}	$\rho_{\text{interannual}}$
σ_{40}	0.95	1.07	0.76	0.66	0.56
T_S	0.96	1.1	0.79	0.64	0.47
e_h, e_v	1.00	1.14	0.74	0.46	0.39
NDVI	1.05	1.25	0.68	0.54	0.38
BTI	1.22	1.59	0.39	0.68	0.57

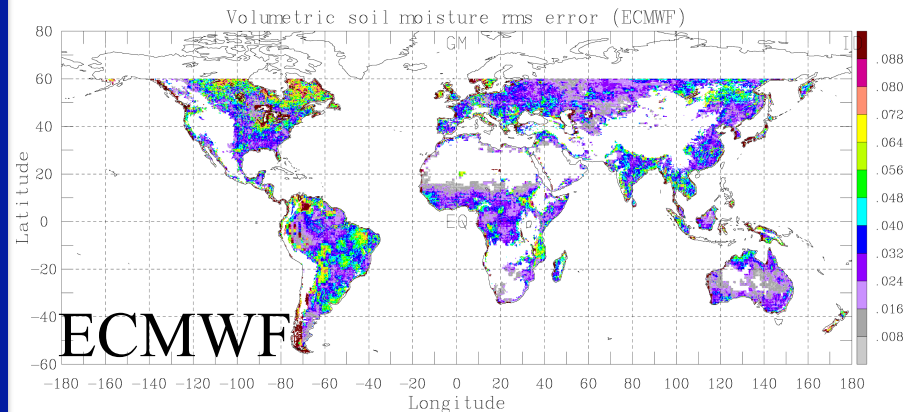
Several spatial/temporal **metrics** are used

- Spatial and temporal variability of the retrieval is based on the observations
- The NN retrieval does not reproduce the model patterns, it can even correct it!

Application 3) - Consistency checking



Higher incoherencies model/observations

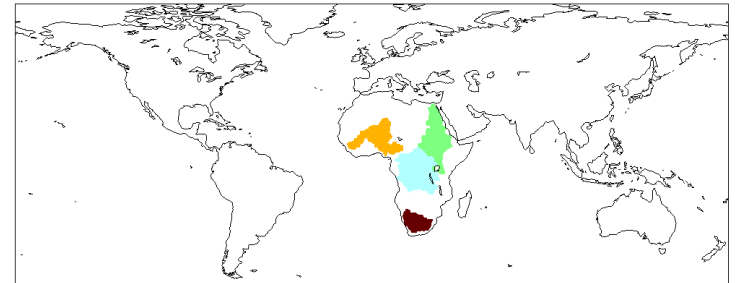


→ Consistency checking between model output and satellite observations:

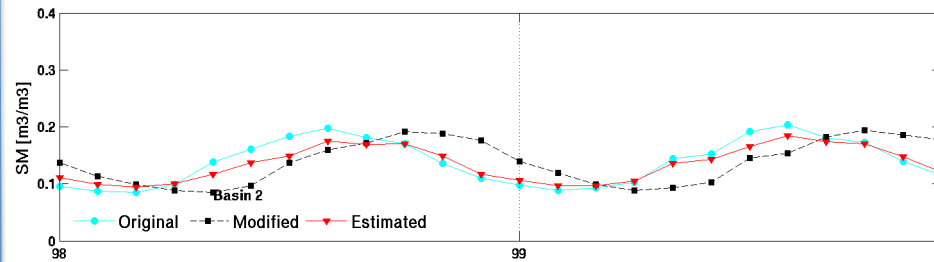
- ECMWF closer to EO observations
- This tool can help model development

Aires, Prigent, Rossow, Soil moisture at a global scale. II – Global Statistical relationships, JGR, 2005)

Synthetic tests:



Shifting the SM seasonal cycle in some basins



→ NN retrieval is able to correct season where necessary

Jimenez, Clark, Kolassa, Aires, Prigent & Blyth, A joint analysis of modelled SM fields and satellite obs., JGR, 2013.

Application 4) - Variational assimilation

- Assimilation in NWP centres of:
 - (1) Raw observations: need a RTM, good auxiliary parameters
→ Ask to the system to “perform” the retrieval, data fusion
 - (2) Retrieved SM: need uncertainty characterization R_i
- Solution (1) has been privileged because easier to specify errors in raw observations (supposed to be constant) than on retrieved products (state-dependent). But difficulty to rely on the RTM...

$$(2) \quad J(x_0) = \frac{1}{2}(x_0 - x_0^b)^T \mathbf{B}^{-1}(x_0 - x_0^b) + \frac{1}{2} \sum_{i=0}^n (x(t_i) - x_i^r)^T \mathbf{R}_i(x(t_i))^{-1}(x(t_i) - x_i^r)$$

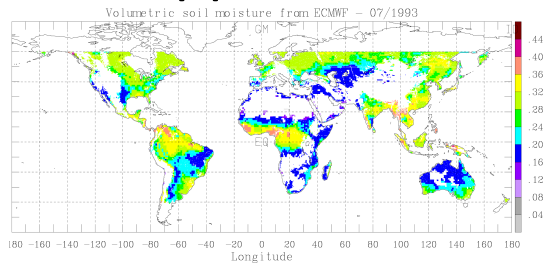
Advantages of (2):

- Retrieval is coherent with model SM
- We can “help” the retrieval when necessary
- No need for aux. parameters

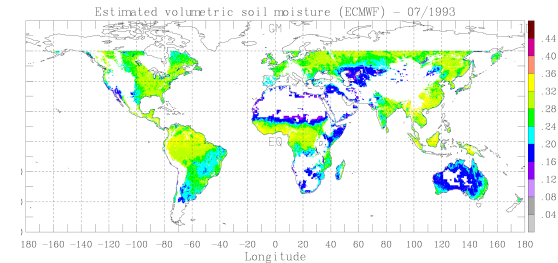
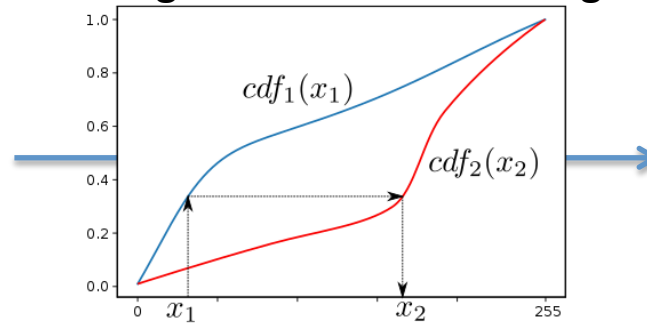
Application 4) - Variational assimilation

- Is NN retrieval independent enough from the model?

- Our approach:



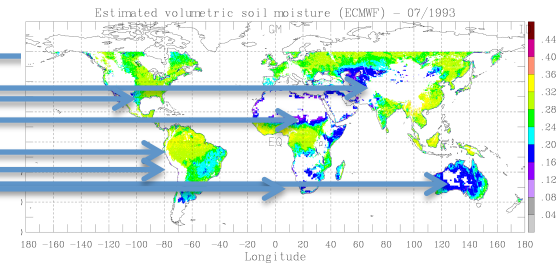
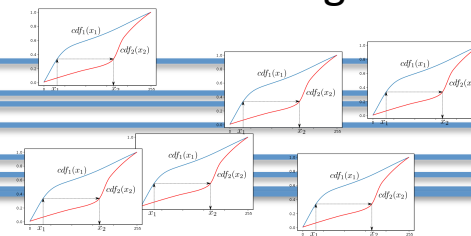
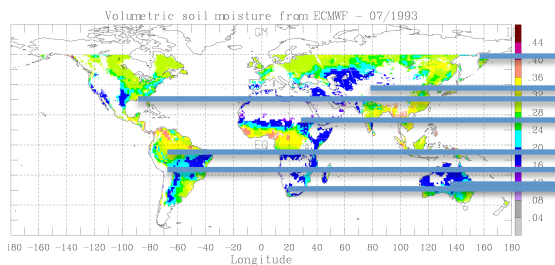
One general “CDF matching”



The NN retrieval is less model-dependent

- Classical approach:

One CDF matching for each pixel



Data assimilation to extract soil moisture information from SMAP observations, Kolassa et al., RS, 2017.

➔ Global bias-calibration better than localized ones for assimilation!

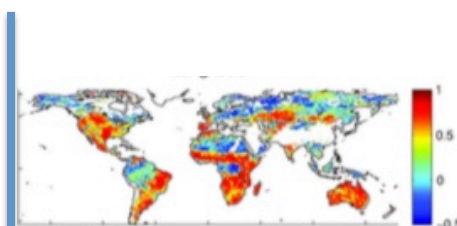
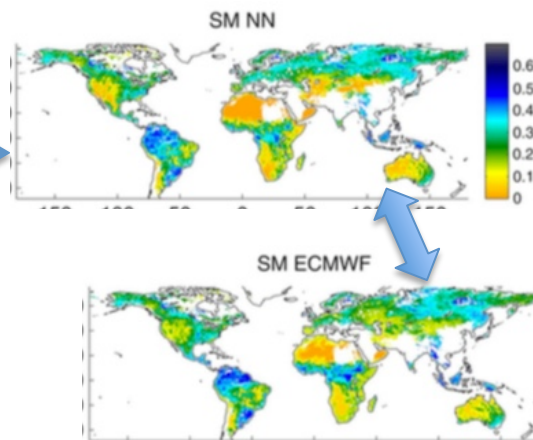
- Spatial pattern of EO data is changed
- Dynamic behaviour too

Assimilation experiments at ECMWF with SMOS

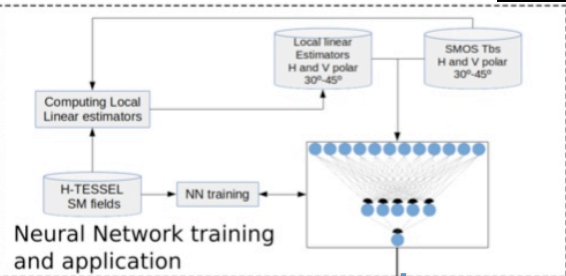
■ First retrieval:



NN



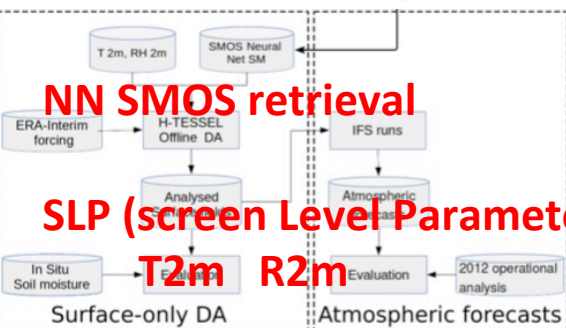
- Temporal correlation
- Spatial evaluation
- *In situ* measurements



SMOS data
NDVI
Soil texture...

SM retrieval using NN: Application to SMOS, Rodriguez-Fernandez, Aires, Richaume, Ker, Prigent, Kolassa, Cabot, Jimenez, Mahmoodi, Drush, IEEE TGRS, 2015

■ Assimilation:

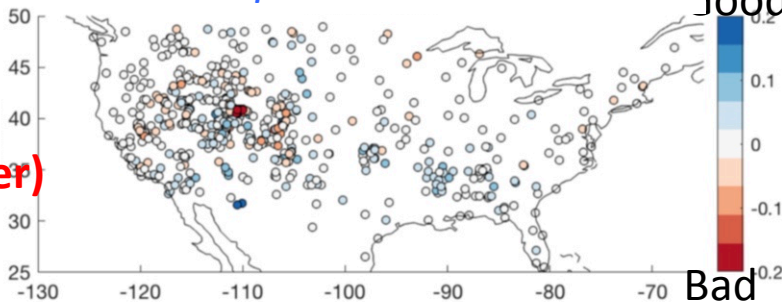


NN SMOS retrieval

SLP (screen Level Parameter)

T2m R2m

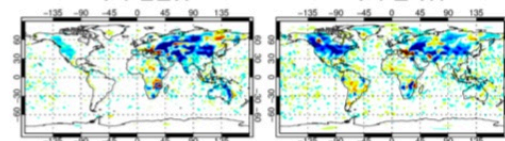
Cor. Improvement in situ SM



Forecast skills of T850

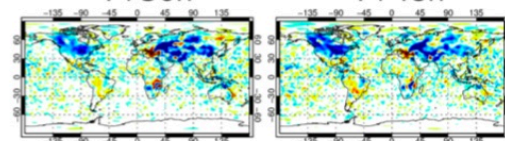
T+12h

T+24h



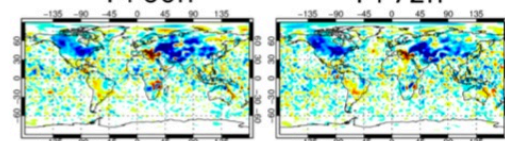
T+36h

T+48h



T+60h

T+72h



SMOS NN SM data assimilation in a land surface model & atmospheric impact, Rodriguez-Fernandez, de Rosnay, Albergel, Richaume, Aires, Prigent, Kerr, RS, 2019

■ In parallel, SMAP assimilation at NASA:

- Data assimilation to extract soil moisture information from SMAP observations, Kolassa et al., RS, 2017.
- Merging active & passive MW observations in SM data assimilation, Kolassa, Reichle, Draper, RSE 2017.

Downscaling of SM

NN downscaling scheme

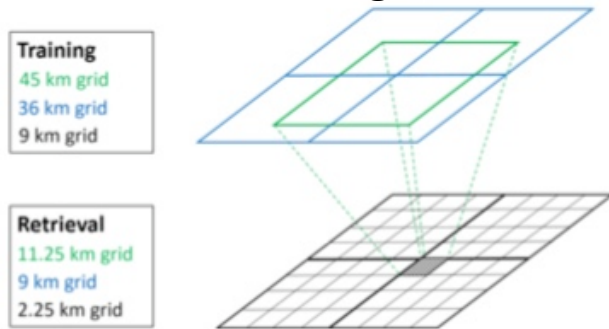
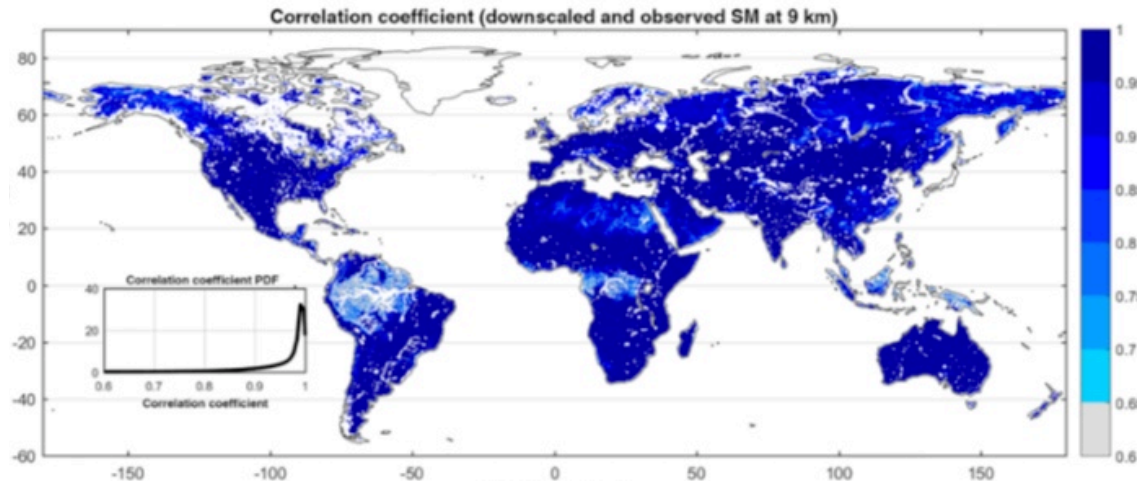


Figure 1. Two levels of spatial grids used for training and retrieval steps in the NN algorithm. While both steps have similar grid structures, the spatial resolutions are different as listed here.

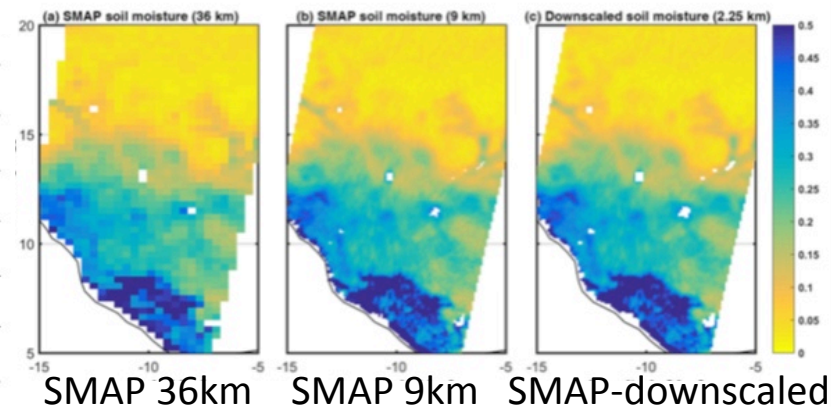


Cor. SMAP-observed SM at 9 km & NN-downscaled SM at 9 km.

tatjanavc@gmail.com

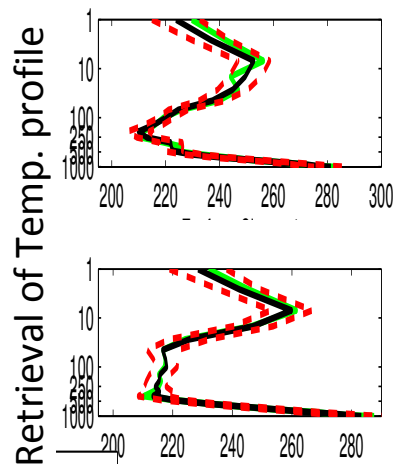
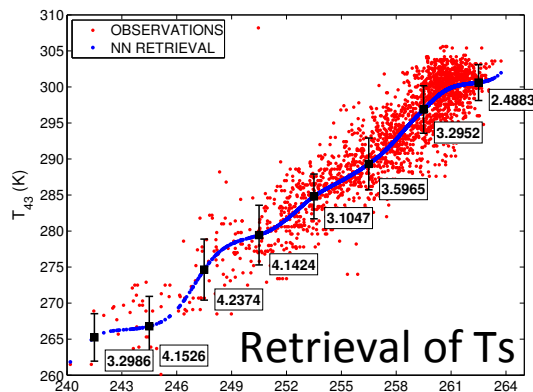
Inputs using in each of the downscaling scheme:

No.	Usage	Input 1	Input 2	Input 3	Input 4	Input 5	Input 6
R1	Training	SM at 45 km	NDVI at 45 km	NDVI at 9 km for target pixel	ASCAT SM (45 or 11 km)	-	-
	Retrieval	SM at 11.25 km	NDVI at 11.25 km	NDVI at 2.25 km for target pixel			
R2	Training	SM at 45 km	NDVI at 45 km	NDVI at 9 km for target pixel	ASCAT SM (45 or 11 km)	-	-
	Retrieval	SM at 11.25 km	NDVI at 11.25 km	NDVI at 2.25 km for target pixel	NDVI	-	-
R3	Training	SM at 45 km	NDVI at 45 km	NDVI at 9 km for target pixel	TI at 45 km	TI at 9 km for target pixel	-
	Retrieval	SM at 11.25 km	NDVI at 11.25 km	NDVI at 2.25 km for target pixel	TI at 11.25 km	TI at 2.25 km for target pixel	-
R4	Training	SM at 45 km	NDVI at 45 km	NDVI at 9 km for target pixel	TI at 45 km	TI at 9 km for target pixel	ϕ_{NDVI} at 45 km for all pixels at 9 km
	Retrieval	SM at 11.25 km	NDVI at 11.25 km	NDVI at 2.25 km for target pixel	TI at 11.25 km	TI at 2.25 km for target pixel	ϕ_{NDVI} at 11.25 km for all pixels at 2.25 km



Conclusion/Perspectives

- What we learned:
 - This is perfect technique to **build long-term record of SM**
 - Calibration over long time record
 - Technique flexible enough for all kind of instruments
 - Exploit synergy for better SM retrieval
 - Good approach for **SM assimilation** (& other surface products?)
- Assimilation in NWP centres:
 - ECMWF
 - NASA
- **Uncertainty characterization** to improve usability of SM product & facilitate assimilation



- State-dependency of retrieval errors
- Similar work should be done for SM

Thank you!