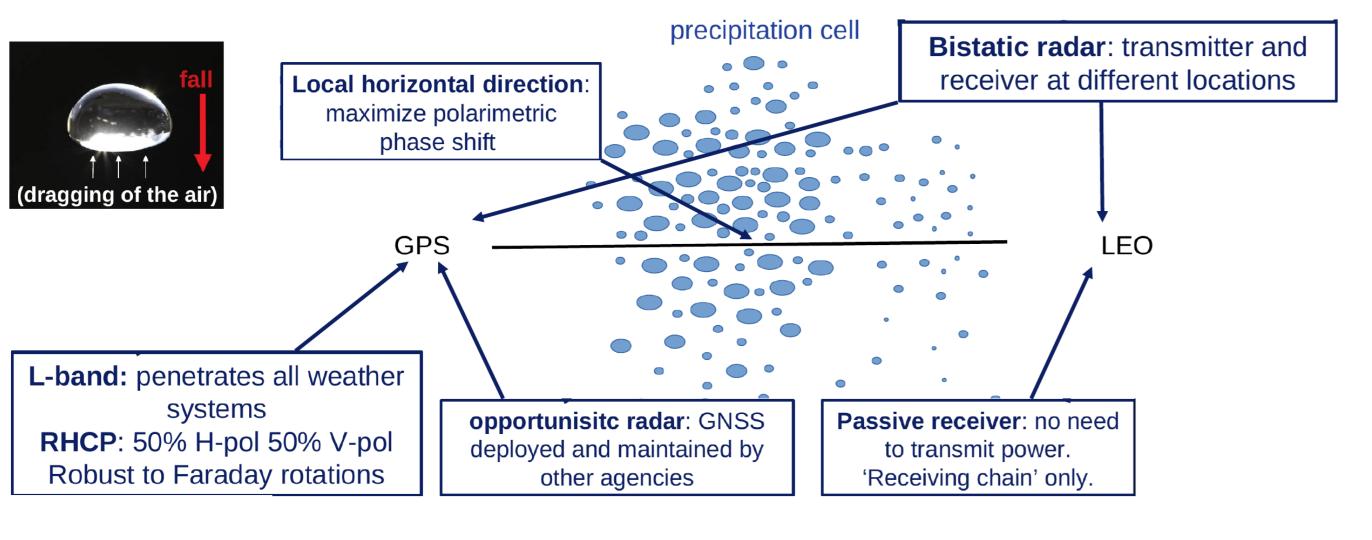
New precipitation and cloud ice observations with polarimetric GNSS RO aboard the PAZ satellite

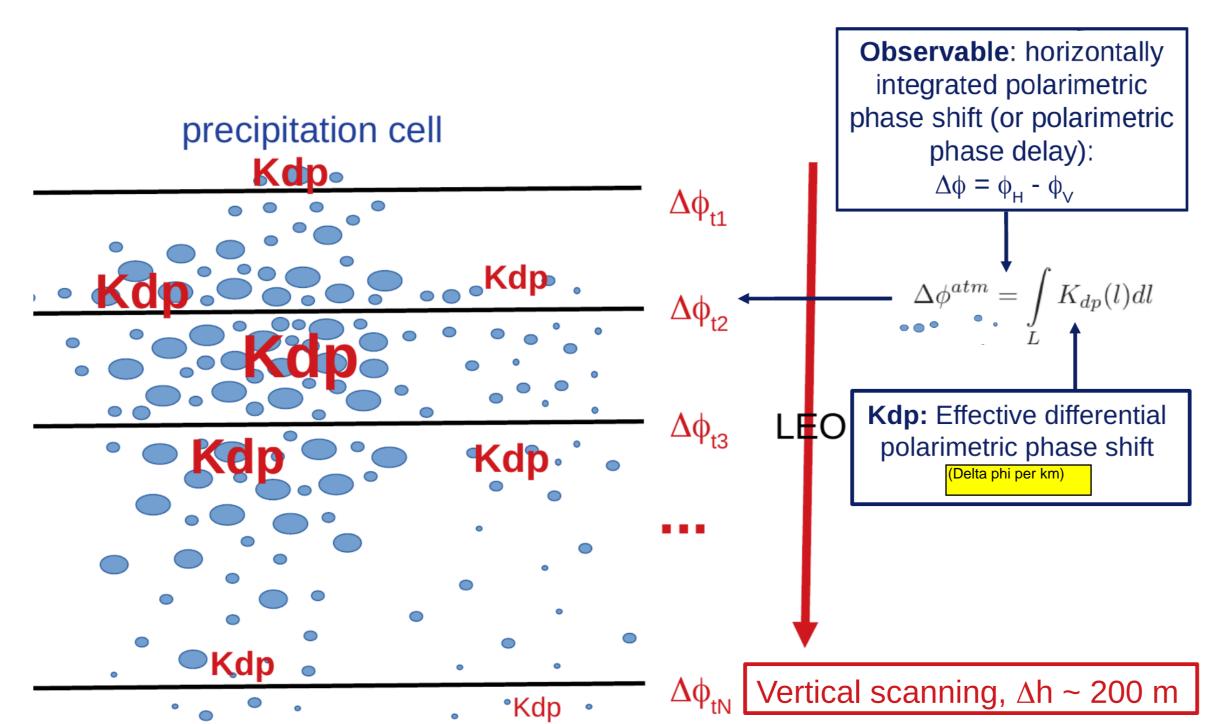
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1- GNSS POLARIMETRIC RADIO OCCULTATIONS (PRO): BENDING OF THE RADIO-LINKS Right-Hand Circular Polarization

Left: sketch of a 'standard' GNSS Radio Occultation (RO), where a circularly polarized antenna receives signals in occulting geometry, the receiver measures the additional Doppler effects induced by the vertical gradients in the refractive index of the atmosphere to finally generate vertical profiles of thermodynamic variables (T, p, q). Right: The only modification in the GNSS PRO is the replacement of the circular antenna by a dual-polarized one: horizontally + vertically polarized. The hypothesis of the experiment is that hydrometeors, especially big rain droplets associated to heavy rain, will increase the phase delay of the horizontal propagation w.r.t. the vertical one.

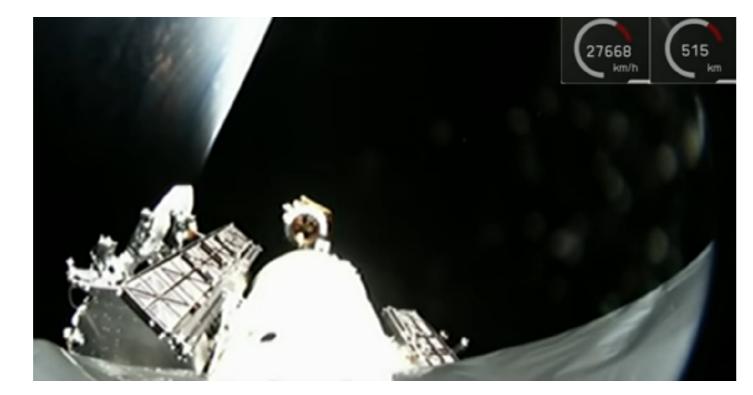




2- THE ROHP-PAZ EXPERIMENT:

This new measurement concept is being proved aboard the satellite PAZ Low Earth Orbiter: the Radio Occultation and Heavy Precipitation experiment aboard PAZ (ROHP-PAZ) https://paz.ice.csic.es





Sucessful launch on February 22, 2018, by SpaceX (Falcon9) into a polar orbit (97.4°) at ~514 km altitude, sun-synchronous dusk/dawn. GNSS RO∭● New measurement concept: thermodynamics + heavy rain. experiment activated on May 10, 2018.

3- FIRST POLARIMETRIC RESULTS (I): Strategy

- Published in GRL Jan'19 [https://doi.org/10.1029/2018GL080412].
- Co-located with IMERG 2D rain products + successful QC: 14,297 with 4,338 rainy cases.
- IMERG provides 2D rain rate combined from different sources, in 30 minute interval, but ~14% detection failures.
- Co-location by averaging wide areas of IMERG rain around the GNSS-PRO central point.

IMERG co-location not perfect, invalid set of data for one-to-one validation, but valid approach to statistically check the response of GNSS-PRO to hydrometeors

4- FIRST POLARIMETRIC RESULTS (II): Sensing rain Rain-free: Rain: $R_{2\times 2} = 0 \,\text{mm h}^{-1}$ **RAIN FREE:** $R_{2\times 2} > 2 \,\text{mm h}^{-1}$ - average → 0 \square R_{2×2} > 4 mm h⁻¹ - bias ~ 1° (bottom) - dispersion: <2º @ h>4.5km <40 @ surface **RAIN-FREE** events: 98.4% with $<\Delta\phi>_{0km-20km}<2^{\circ}$ 99.97% with $<\Delta \phi>_{0 \text{km-20 km}} < 4^{\circ}$ **RAIN EVENTS:** 'false intense rain positives': - clear positive mean (<~10km) for $\langle \Delta \phi \rangle_{\text{0km-20km}} \rangle 4^{\circ} \rightarrow 0.96\%$ - mean > rain-free dispersion (except bottom) dispersion larger: diversity of rain rate inaccuracy co-location ΔΦ (deg) All cases with R₂₀>1mm/h 17.5 2° × 2° cth < 6 km</p> From RO thermodynamic 6 km < cth < 9 km</p> 15.0 profiles, same 4 sets: 9 km < cth < 13 km 13 km < cth</p> 15.0 **₫** 12.5 · ± 10.0 -ΔΦ (deg) Water vapor density (mg \cdot m⁻³)

5- FROZEN PARTICLES?

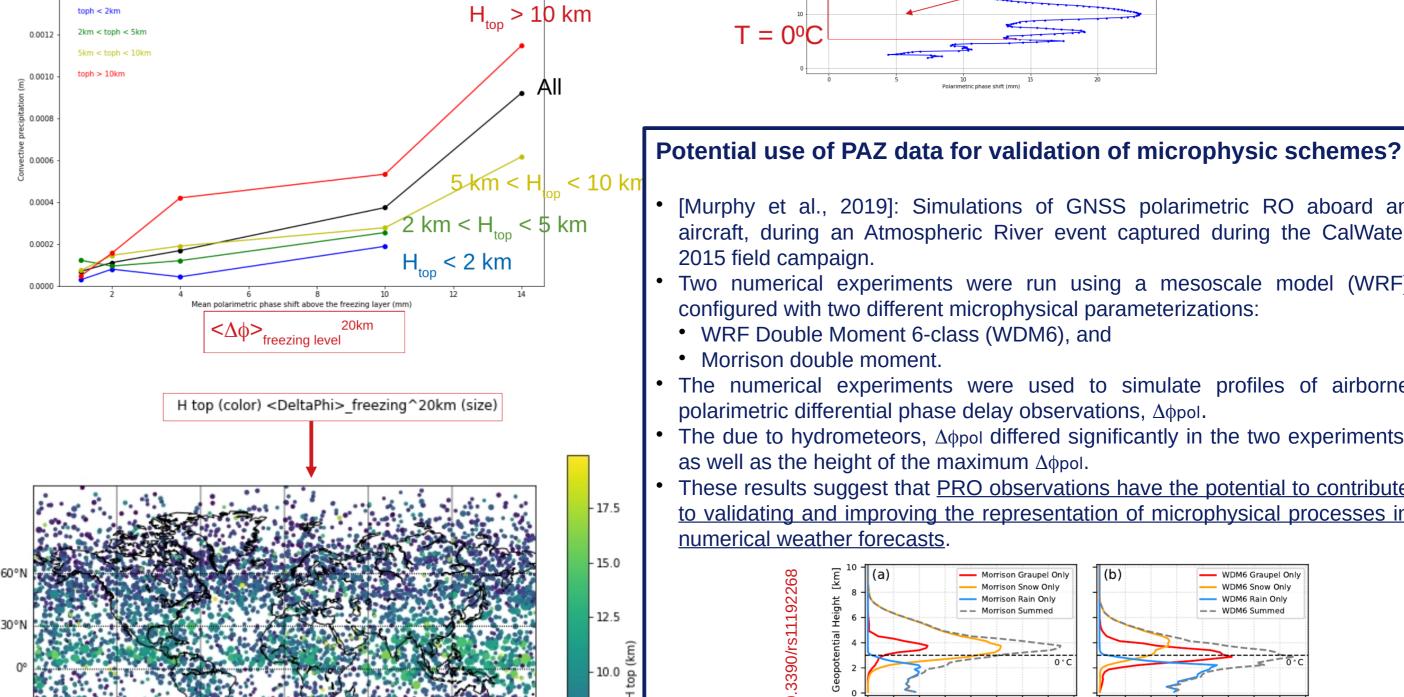
- No cirrus cloud ice detected (layer too thin?).
- $\Delta \phi_{\text{pol}}$ signals above the freezing layer are analyzed in terms of its average signal, $<\Delta\phi_{pol}>_{freezing\ level}$ 20km, and the maximum altitude at which $\Delta\phi_{pol}$ is found (Htop).

Vertical structures consistent with the cloud, not directly linked to the water

vapor, and with high sensitivity to <u>frozen particles</u> (cloud ice, mixed phase)

Strong $\Delta \phi_{pol}$ signals above the freezing layer found in convective systems:

Convective precipitation from ERA-5:



 $<\Delta \phi>_{\text{freezing level}}$

[Murphy et al., 2019]: Simulations of GNSS polarimetric RO aboard an aircraft, during an Atmospheric River event captured during the CalWater 2015 field campaign Two numerical experiments were run using a mesoscale model (WRF)

configured with two different microphysical parameterizations: • WRF Double Moment 6-class (WDM6), and Morrison double moment. The numerical experiments were used to simulate profiles of airborne polarimetric differential phase delay observations, $\Delta \phi pol.$

The due to hydrometeors, $\Delta \phi pol$ differed significantly in the two experiments, as well as the height of the maximum $\Delta \phi_{pol}$. These results suggest that PRO observations have the potential to contribute to validating and improving the representation of microphysical processes in numerical weather forecasts

6- CONCLUSIONS:

- PAZ carries a polarimetric RO payload, to prove the GNSS-PRO concept.
- Launched: Feb 22, 2018. RO activated on May 10, 2018.
- Polarimetric phase shift linked to precipitation, larger signals for more intense rain.
- Vertical features in polarimetric phase shift consistent with storms at reaching different altitudes.
- Strong signals induced by frozen particles above the freezing layer.
- Use of other derived-observables (top height, signal above freezing level, ...) → potential for **convection products?**
- Use of PAZ $\Delta \phi_{POI}$ and PAZ RO moisture profiles \rightarrow Direct use of PAZ data for better understanding of deep convection systems?
- Use of PAZ ΔφροΙ to validate or improve micro-physics schemes in NWP?

DATA PUBLICLY AVAILABLE







