



Developing Weather and Climate Models in Python

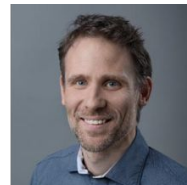
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AI2 Climate Modeling: Who We Are

ML group



Chris Bretherton



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DSL group



Noah Brenowitz



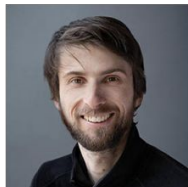
Anna Kwa



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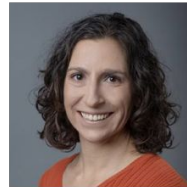
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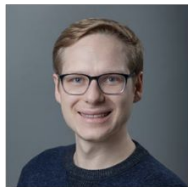
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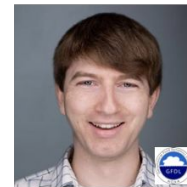
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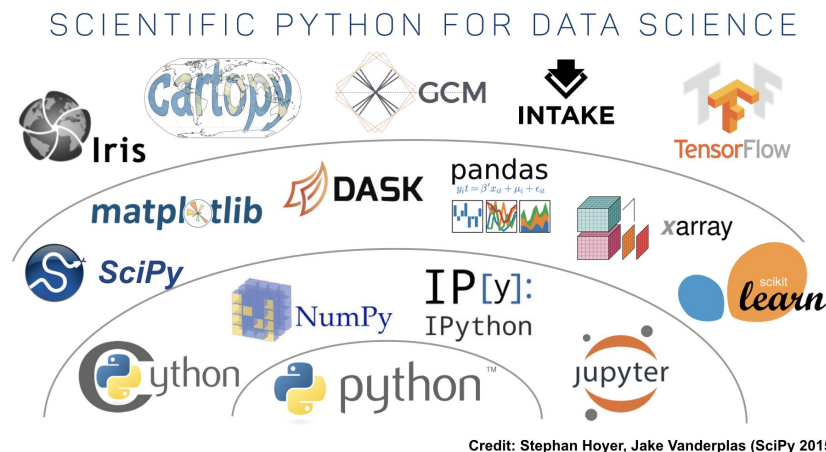


Tobias Wicky

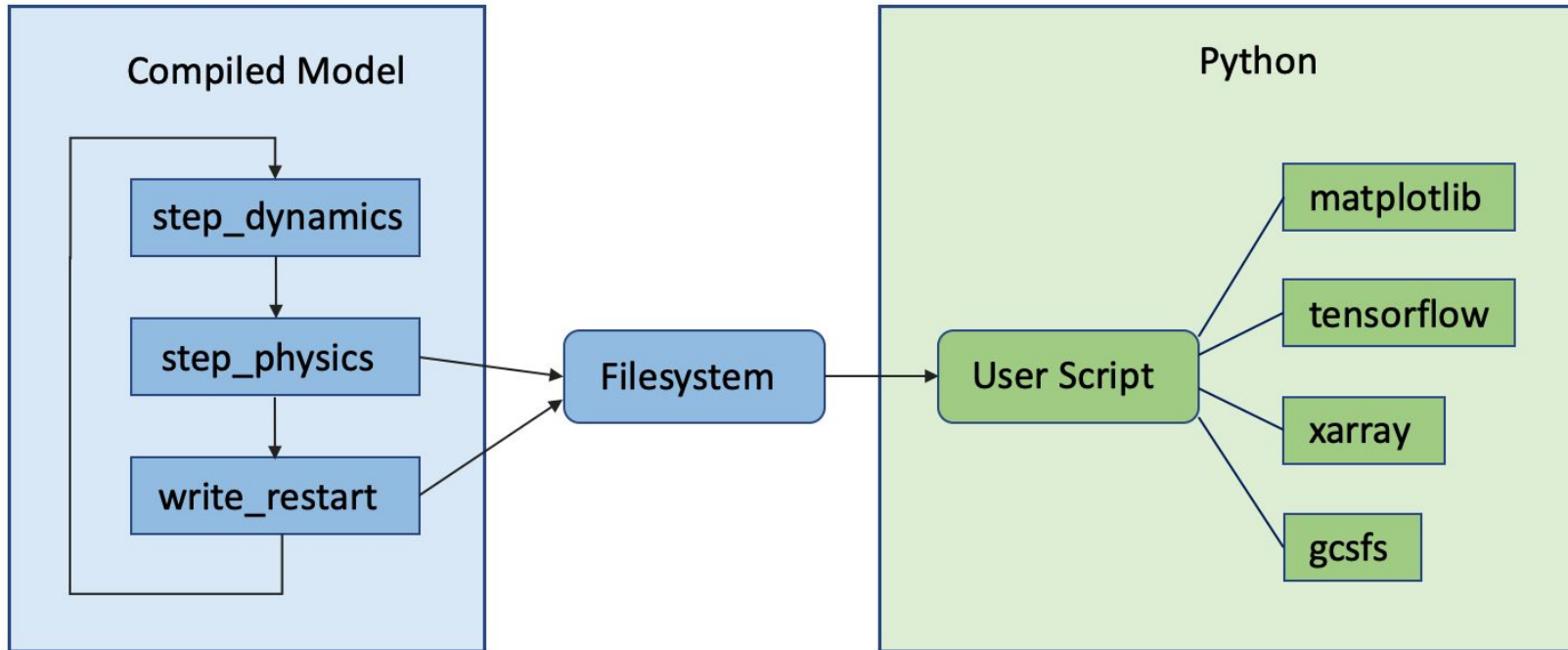
Atmospheric Models in Python

Why do we use Python?

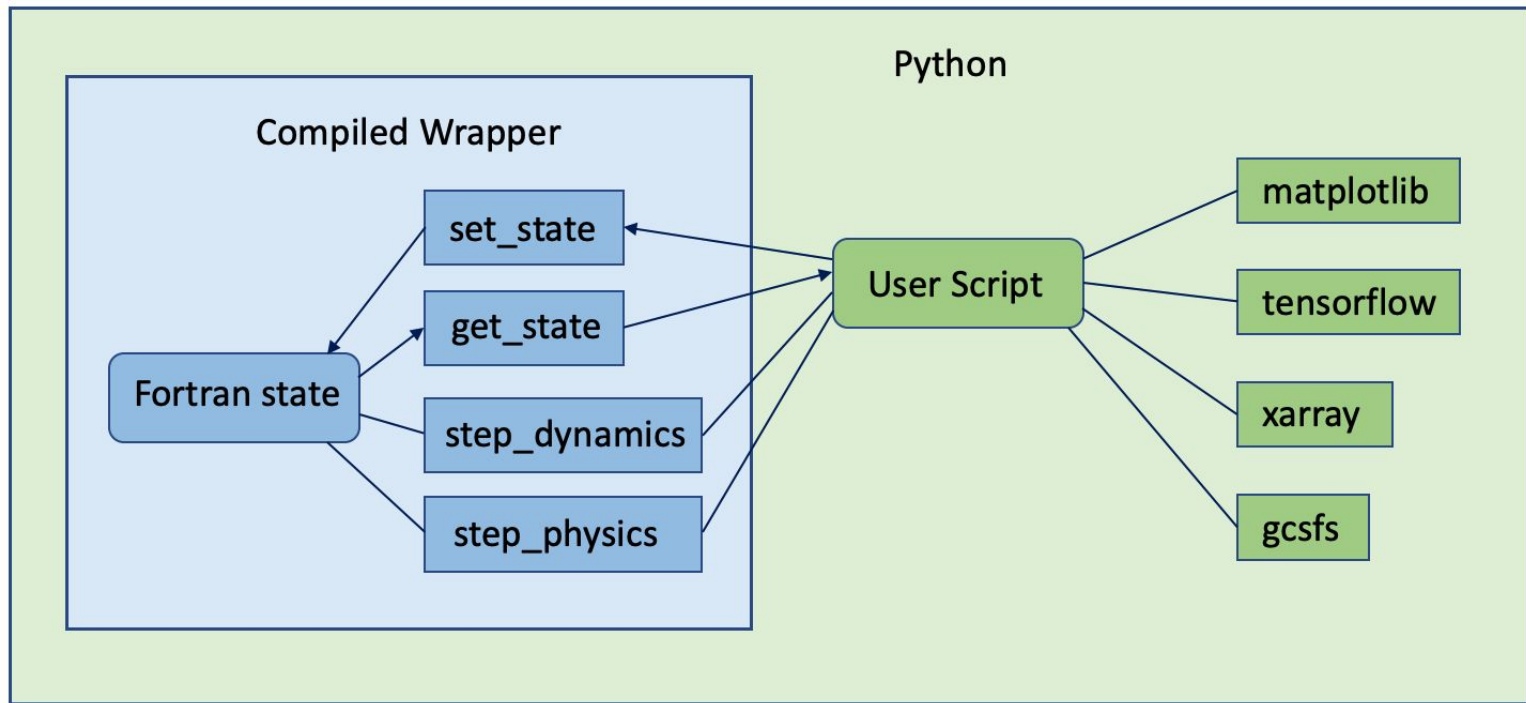
- Machine learning libraries
- Cloud file storage libraries
- Comfortable for all of our scientists
- Interactive execution
- Built-in introspection libraries



Many model users use Python



Online Python Modeling



fv3gfs-wrapper

Simple Python main loops
provide a clear way to
modify the model

```
import fv3gfs.wrapper

if __name__ == "__main__":
    fv3gfs.wrapper.initialize()
    for i in range(fv3gfs.wrapper.get_step_count()):
        fv3gfs.wrapper.step_dynamics()
        fv3gfs.wrapper.step_physics()
        fv3gfs.wrapper.save_intermediate_restart_if_enabled()
    fv3gfs.wrapper.cleanup()
```

Examples

Random forest

Can add online
functionality by getting
and setting the Fortran
model state

```
import fv3gfs.wrapper
import fv3gfs.wrapper.examples
import f90nml
from datetime import timedelta

if __name__ == "__main__":
    # load timestep from the namelist
    namelist = f90nml.read("input.nml")
    timestep = timedelta(seconds=namelist["coupler_nml"]["dt_atmos"])
    # initialize the machine learning model
    rf_model = fv3gfs.wrapper.examples.get_random_forest()
    fv3gfs.wrapper.initialize()
    for i in range(fv3gfs.wrapper.get_step_count()):
        fv3gfs.wrapper.step_dynamics()
        fv3gfs.wrapper.step_physics()

        # apply an update from the machine learning model
        state = fv3gfs.wrapper.get_state(rf_model.inputs)
        rf_model.update(state, timestep=timestep)
        fv3gfs.wrapper.set_state(state)

    fv3gfs.wrapper.save_intermediate_restart_if_enabled()
    fv3gfs.wrapper.cleanup()
```

MPI-Enabled

MPI for Python (mpi4py)
for distributed-memory
parallelism

```
import fv3gfs.wrapper
import numpy as np
from mpi4py import MPI

ROOT = 0

if __name__ == "__main__":
    fv3gfs.wrapper.initialize()
    # MPI4py requires a receive "buffer" array to store incoming data
    min_surface_temperature = np.array(0.0)
    for i in range(fv3gfs.wrapper.get_step_count()):
        fv3gfs.wrapper.step_dynamics()
        fv3gfs.wrapper.step_physics()

        # Retrieve model minimum surface temperature
        state = fv3gfs.wrapper.get_state(["surface_temperature"])
        MPI.COMM_WORLD.Reduce(
            state["surface_temperature"].view[:].min(),
            min_surface_temperature,
            root=ROOT,
            op=MPI.MIN,
        )
        if MPI.COMM_WORLD.Get_rank() == ROOT:
            units = state["surface_temperature"].units
            print(f"Minimum surface temperature: {min_surface_temperature} {units}")

    fv3gfs.wrapper.save_intermediate_restart_if_enabled()
    fv3gfs.wrapper.cleanup()
```

Overhead is minimal

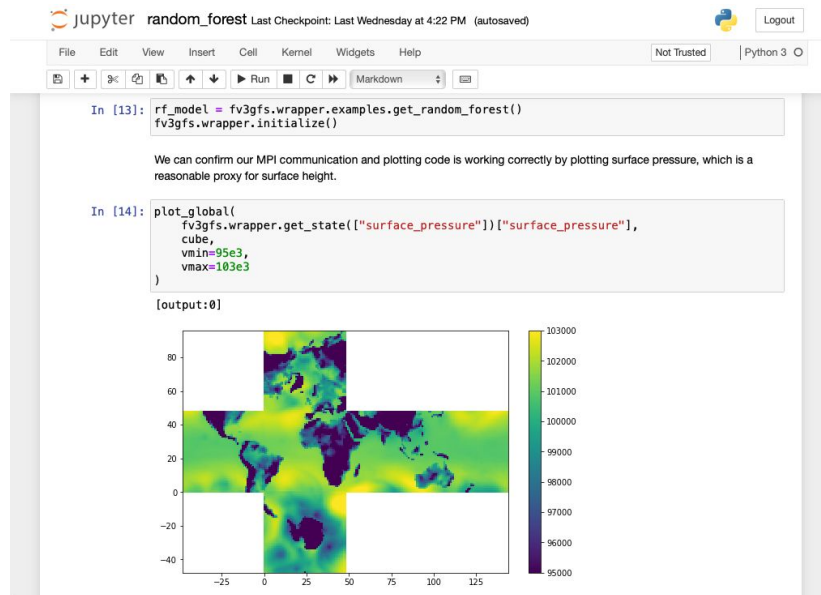
Example	Runtime (s)
Fortran baseline	110
Wrapper baseline	110
Random forest	116
Minimum surface pressure	110

6h simulation time at C48 on 2019 Macbook Pro

Developing in Python

MPI-Parallel Jupyter Notebooks

- Everything we've seen can be run in a Jupyter notebook
- Useful for communicating/learning
- Scientifically evaluate model components



Pytest / unit tests

```
pytest test.py
```

```
pytest test.py --pdb
```

```
def test_nonnegative_model_outputs():
    hyperparameters = DenseHyperparameters(
        ["input"], ["output"], nonnegative_outputs=True
    )
    model = DenseModel("sample", ["input"], ["output"], hyperparameters,)
    batch = xr.Dataset(
        {
            "input": (["x"], np.arange(100)),
            # even with negative targets, trained model should be nonnegative
            "output": (["x"], np.full((100,), -1e4)),
        }
    )
    model.fit([batch])
    prediction = model.predict(batch)
    assert prediction.min() >= 0.0
```

Pytest / unit tests

pytest test.py

```
platform darwin -- Python 3.7.10, pytest-6.0.1, py-1.9.0, pluggy-0.13.1
Matplotlib: 3.2.2
Freetype: 2.6.1
rootdir: /Users/jeremym/python/fv3net, configfile: pytest.ini
plugins: typeguard-2.10.0, hypothesis-6.17.4, regtest-1.4.4, mpl-0.12
collected 14 items
```

```
tests/test_loss.py ..... [100%]

===== 14 passed, 5 warnings in 2.92s =====
```

```
def test_weighted_mae(weights, std, y_true, y_pred, reference):
    loss = _weighted_mae(weights, std)
    result = loss(y_true, y_pred)
> np.testing.assert_almost_equal(result, reference)
E   AssertionError:
E   Arrays are not almost equal to 7 decimals
E   ACTUAL: <tf.Tensor: shape=(), dtype=float32, numpy=8.0>
E   DESIRED: 7.0

tests/test_loss.py:177: AssertionError
===== short test summary info =====
FAILED tests/test_loss.py::test_weighted_mae[double_single_feature_loss] - Asser...
===== 1 failed, 13 passed, 5 warnings in 3.24s =====
```

```
pytest test.py --pdb
```



Pytest / unit tests

- Unit tests make debugging very fast
- Removes fear of breaking things, even with many developers
- Tests are examples of how to use the code
- Can add `--pdb` to get a debugging terminal whenever a test fails

```
def test_nonnegative_model_outputs():
    hyperparameters = DenseHyperparameters(
        ["input", "output", nonnegative_outputs=True]
    )
    model = DenseModel("sample", ["input", "output"], hyperparameters,)
    batch = xr.Dataset(
        {
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        }
    )
    model.fit([batch])
    prediction = model.predict(batch)
    assert prediction.min() >= 0.0
```

With Python, Google is your friend

Introspection tools

- Built-in libraries for code analysis (inspect, ast)
- Well-tested templating libraries developed for HTML generation can be used for code generation (e.g. Jinja)

```
import ast
import inspect

def func():
    a = 1
    return a

source = inspect.getsource(func)
# code -> abstract syntax tree
tree = ast.parse(source)
```

For more introspection magic:

<http://hackflow.com/blog/2015/03/29/metaprogramming-beyond-decency/>

Stay tuned: Pace

- Re-writing FV3/GFS/SHiELD in Python-based DSL gt4py
- Early results presented by Oliver Fuhrer earlier in this session
- Unified code base for CPU and GPU hardware
- Will be presented at AMS 2021 Annual Meeting



AMS101
101st Annual Meeting
VIRTUAL | 10-15 January 2021

Thank You!