



Studying a new GPU treatment for chemical modules inside CAMP

Christian Guzman Ruiz, Mario C. Acosta, Guillermo Oyarzun, Matthew Dawson*, Oriol Jorba, Carlos Pérez García-Pando, Kim Serradell

Barcelona SuperComputing Center*National Center for Atmospheric Research (NCAR)

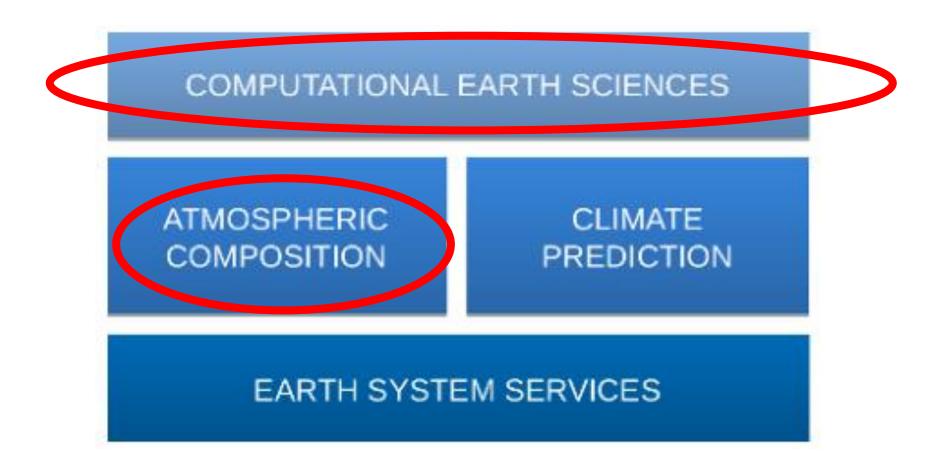
19th workshop on HPC in meteorology

Outline

- Introduction:
 - Motivation
 - Related works
- Multi-cells strategy
- GPU Linear solving
- Hardware and Software configuration
- Results
- Conclusions and future work

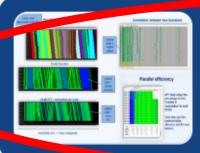


Earth Sciences





Computational Earth Science



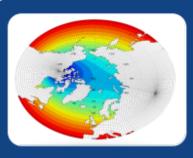
Performance Team

- Provide HPC Services (profiling, code audit, ...) to find main bottlenecks of our operational models
- Research and apply new computational methods for current and new platforms



Models and Workflows Team

- Development of HPC user-friendly software framework
- Support the development of atmospheric research software



Data and Diagnostics Team

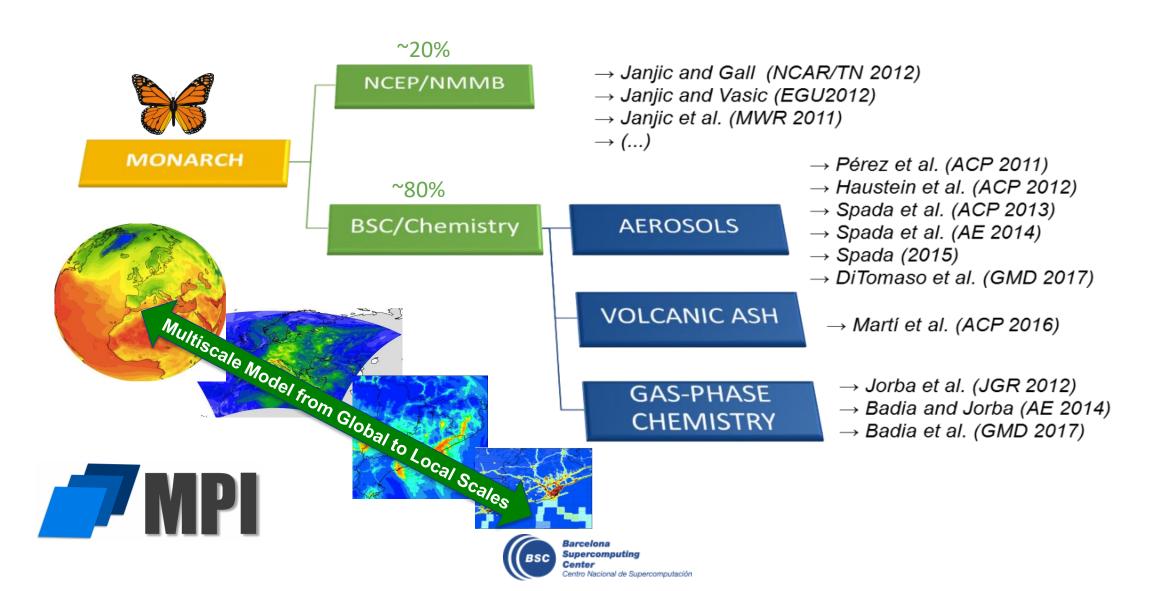
- Big Data in Earth Sciences
- Provision of data services
- Visualization



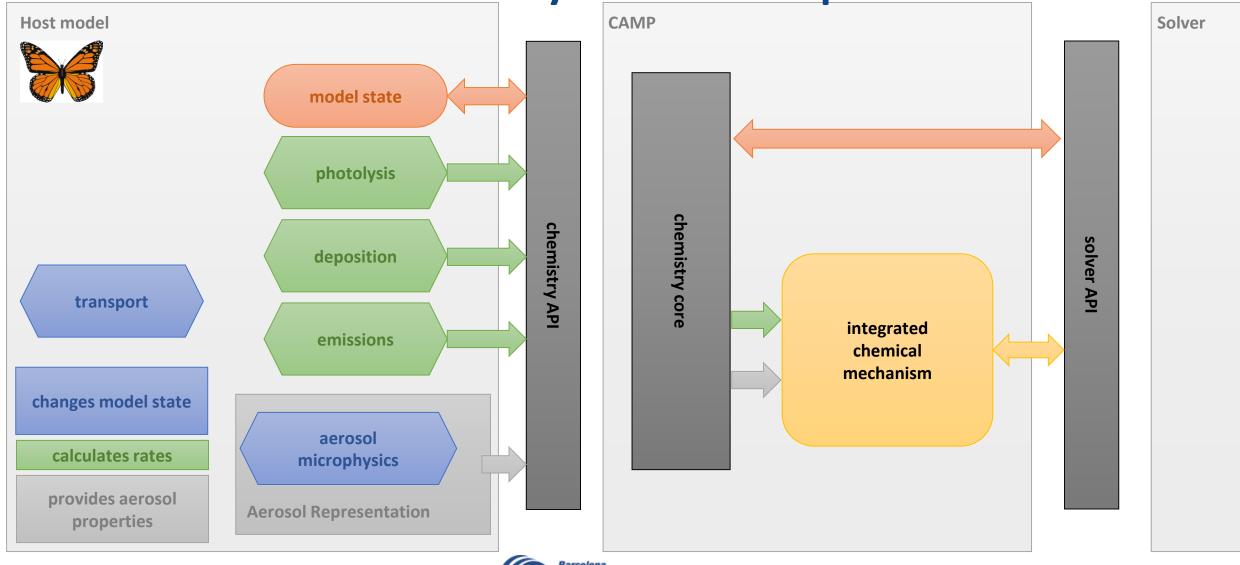
Motivation



MONARCH: Multiscale On-line Atmosphere Chemistry Model

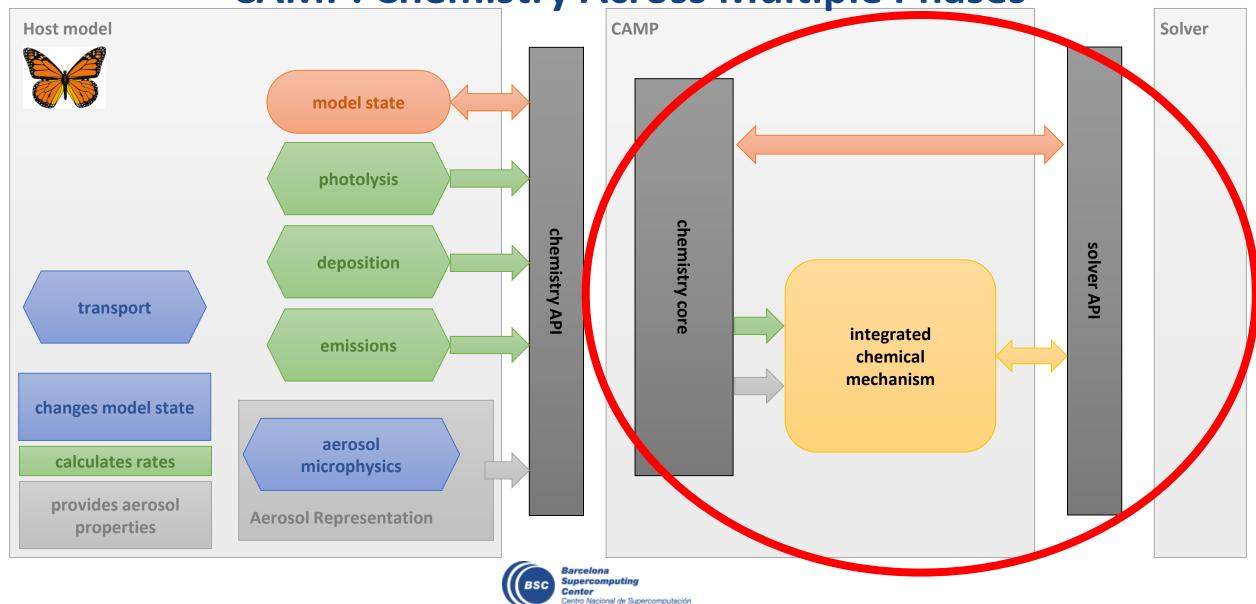


CAMP: Chemistry Across Multiple Phases

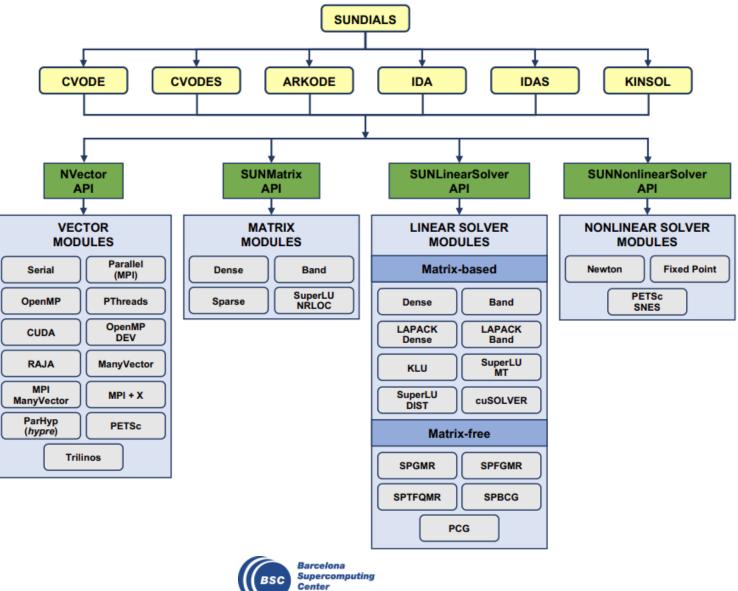


Centro Nacional de Supercomputación

CAMP: Chemistry Across Multiple Phases

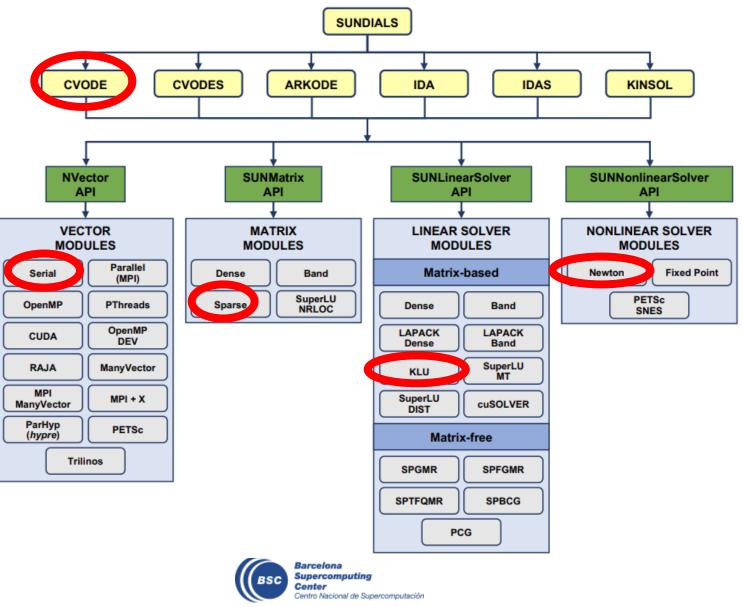


ODE Solvers



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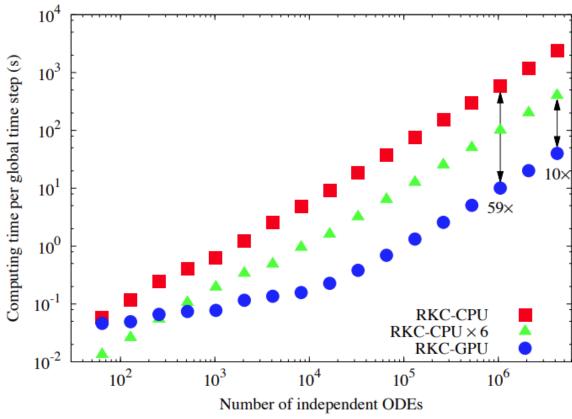
ODE Solvers



Related works



Chemistry in the GPU: CUDA



Kyle E. Niemeyera,b,1, Chih-Jen Sungb, Accelerating moderately stiff chemical kinetics in reactive-flow simulations using GPUs, 2018

Configuration	ration Median CPU Med exec time ler (s)		Performance over CPU
Intel Xeon X5650 + M2070	4.502	0.999	4.50×
Intel Xeon E5-2680 $v3 + K80$	1.476	0.283	5.21×
IBM POWER8 + P100	3.040	0.149	20.40×

Configuration	MPI Processes	CPU exec time (s)	Accelerated exec time (s)	Performance over CPU
2 × 6-core Intel Xeon X5650 +	2 MPI processes	5199	2358	2.27 ×
2 × NVIDIA M2070	12 MPI processes	1388	1368	1.01 ×
2 × 12-core Intel E5-2680 v3 + 2 × NVIDIA K80	4 MPI processes	7362	3384	2.17 ×
	24 MPI processes	1756	1473	1.19 ×
2 × 10-core IBM POWER8 +	4 MPI processes	2294	918	2.50 ×
4 × NVIDIA P100	20 MPI Processes	814	437	1.86 ×

Michail Alvanos and Theodoros Christoudia, GPU-accelerated atmospheric chemical kinetics in the ECHAM/MESSy (EMAC) Earth system model, 2017

...and more



Our contribution

Development on CAMP

- Allow integration of GPU kernels (as a library) without developing an entire chemical module to GPU
 - A novel approach computing multiple cells simultaneously

- Performance evaluation of GPU algorithms over CPU
 - Linear solver scheme
 - Adapted to avoid unnecessary delays with synchronization between GPU blocks



Multi-cells strategy

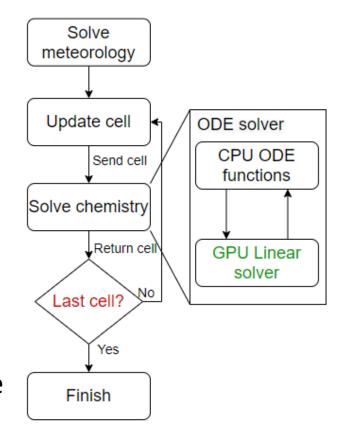


Background:

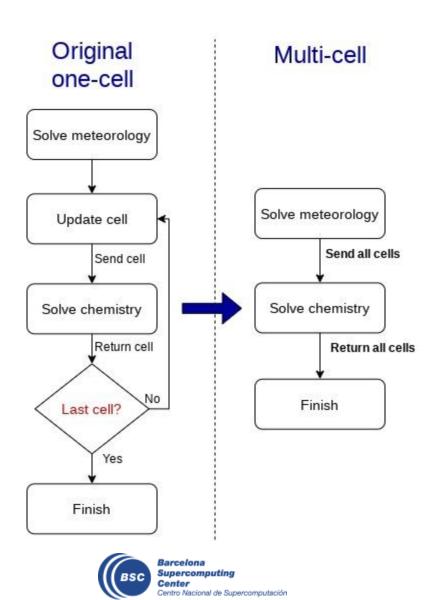
- Domain decomposition results in multiple cells per MPI process, computed in a loop
- These cells can be solved in parallel with the GPU
- A GPU kernel needs to receive all the cells at once in order to compute them simultaneously

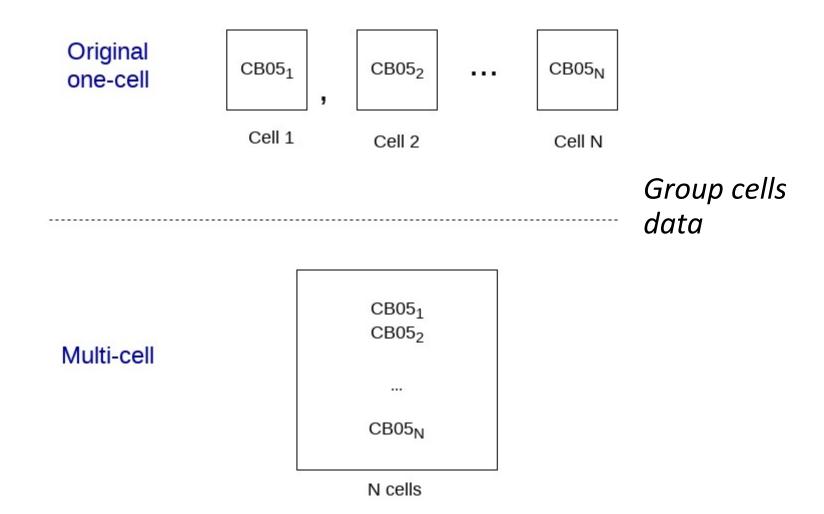
Our approach:

 Adapt the chemical module to solve multiple cells in the base CPU single thread implementation

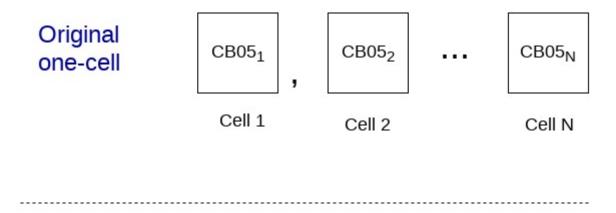




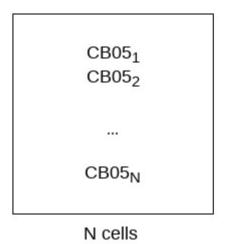








Multi-cell



- Species "replication":
 O3₁, O3₂.. O_N
- Common ODE solver parameters.
- More sensitive to different convergence speeds.



GPU Linear solving



Algorithms

- KLU Sparse (CPU)
 - Integrated in CVODE
 - Dependency on CVODE and SuiteSparse routines
 - Direct solver
- Biconjutage Gradient (GPU)
 - Developed in house.
 - Based from CUBLAS library.
 - Iterative solver



GPU Linear solving

Background:

- Solve a big linear system composed of multiple cells
- Each cell contains multiple unknowns (species), solved by one-thread each (Number of Threads == Number of Species)
- Base algorithm solves a single system, working over all the present unknowns (e.g. reducing an array to a single variable)
- Expensive communication between GPU blocks (>= 50% overall execution time)

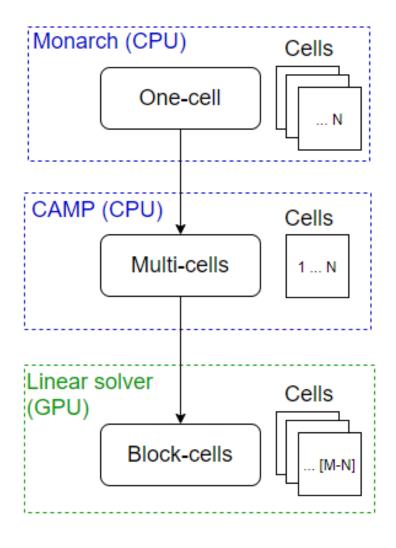
Our approach:

Compute cells independently of the others



GPU Block-cells

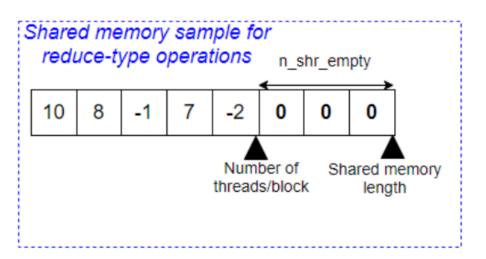
- One-cell and Multi-cells are designed for CPU
 - One-cell computes the cells independently of each other
 - Multi-cells groups the cells into an unique system to solve
- Block-cells is used in GPU to avoid communication between GPU blocks
 - Cells are divided in blocks, containing X cells each block
 - The number of cells per block depends on the number of threads per block available in the GPU





Kernel configuration: GPU blocks cells (N)

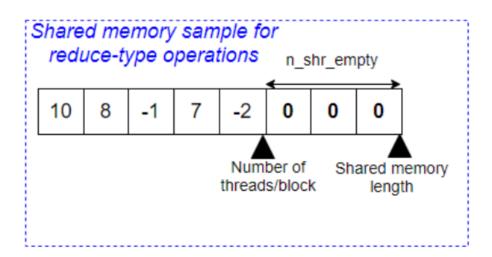
- GPU Block contains multiple cells
 - Chemical mechanism ⇒ 156 species (CB05)
 - GPU block ⇒ Max. threads/block (1024)
 - Cells per block \Rightarrow 1024/156 = 6.56 -> 6
 - Shared memory ⇒ 1024 variables (Empty slots from 936 to 1024)





Kernel configuration: GPU Block-cells (1)

- GPU Block contains 1 cell
 - Chemical mechanism ⇒ 156 species (CB05)
 - GPU block ⇒ 156 threads
 - Shared memory ⇒ 256 variables (Empty slots from 157 to 256)





Hardware and Software configuration



Hardware

- CTE-POWER cluster:
 - 2 x IBM Power9 8335-GTH @ 2.4GHz (3.0GHz on turbo, 20 cores and 4 threads/core, total 160 threads per node)
 - 512GB of main memory distributed in 16 dimms x 32GB @ 2666MHz
 - 2 x SSD 1.9TB as local storage
 - 4 x GPU NVIDIA V100 (Volta) with 16GB HBM2.
 - Compilers: GCC version 6.4.0 and NVCC version 9.1



Software configuration

*Chemical mechanism	Species	Cells	Time-steps
CB05+chlor ine	156	100 - 10,000	5

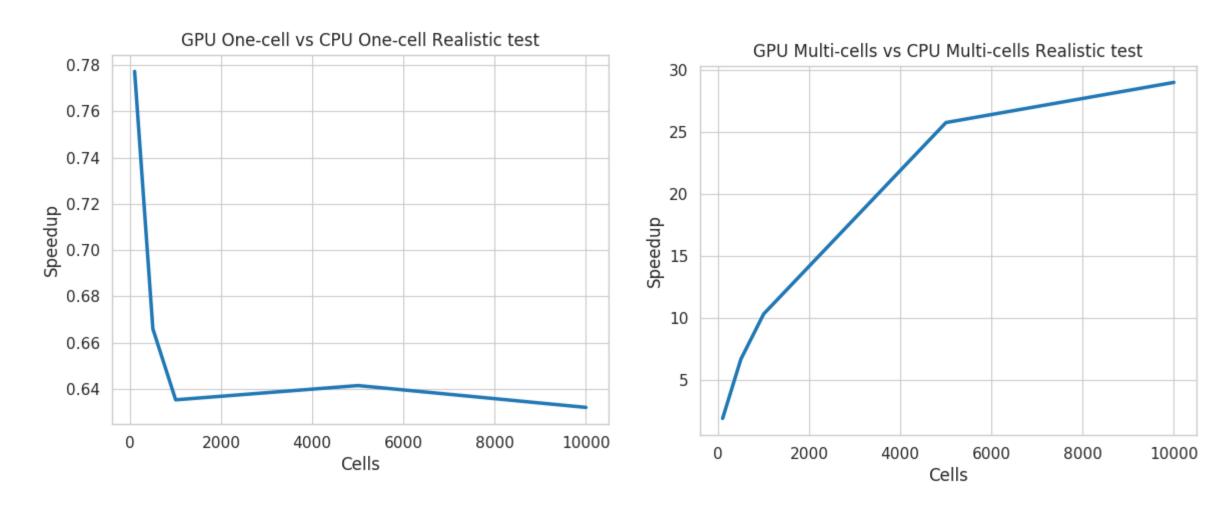
 *Based in a configuration for realistic tests for atmospheric models taken from CAMP paper (publication in progress)

Kernel setting	Linear solver	Threads per block	Cells per block	Shared memory
GPU Block (1)	BCG	156	1	256
GPU Block (N)	BCG	1024	6	1024

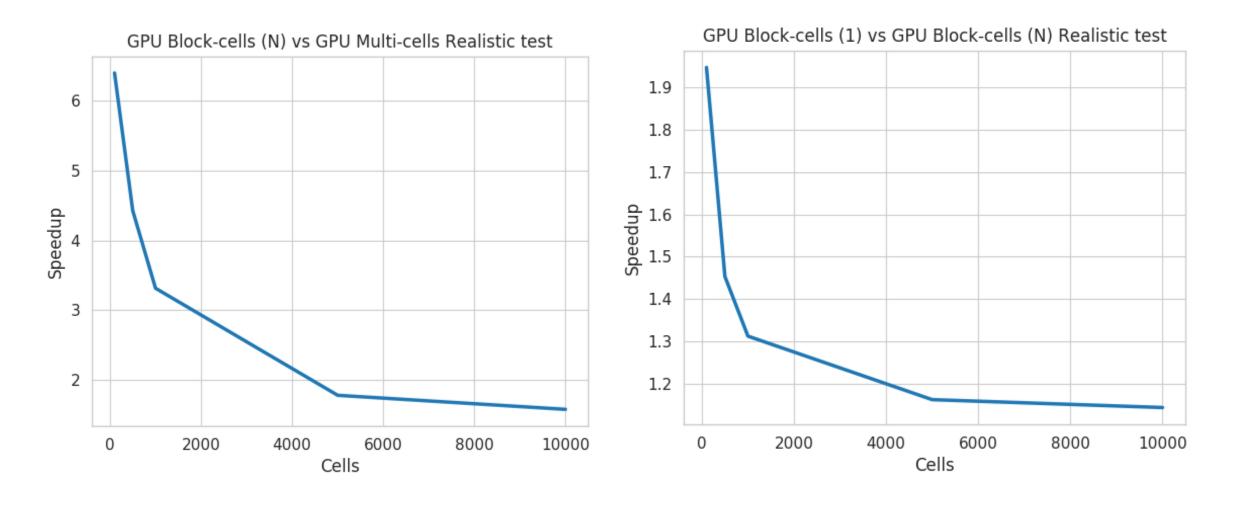
Linear solver	MPI processes	GPUs	Method
KLU	1, 40	0	One-cell, Multi-cells
BCG	1	1	One-cell, Multi-cells, Block-cells



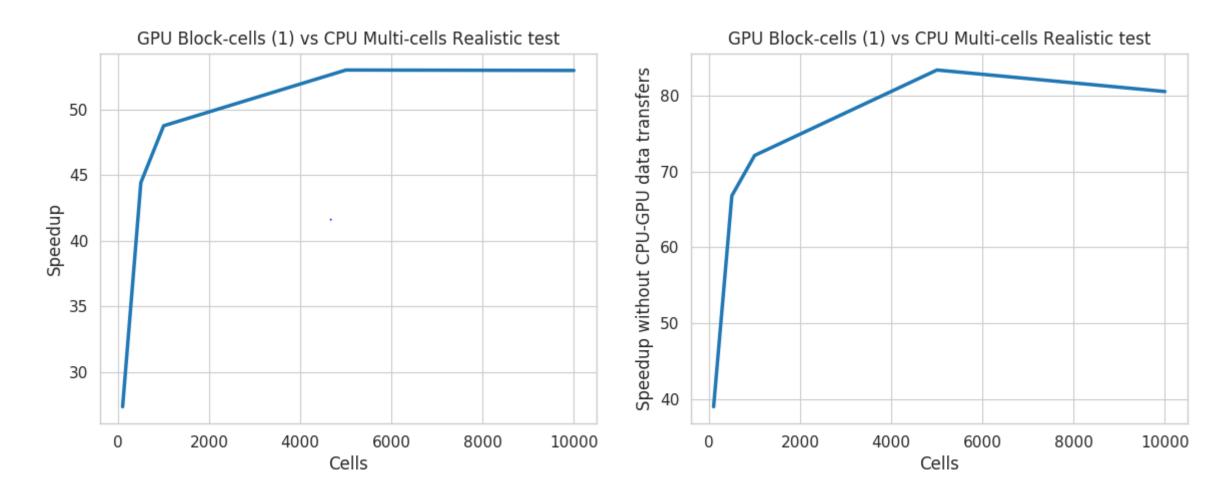






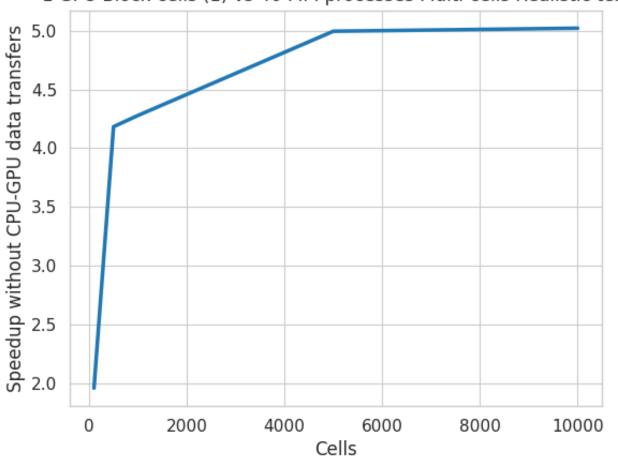








1 GPU Block-cells (1) vs 40 MPI processes Multi-cells Realistic test





Conclusions



Conclusions

 Adapted CAMP to integrate GPU libraries, facilitating the development of a GPU chemical solver in the future

- Added a GPU linear solver developed in house, improving the performance significantly from the CPU single-thread version (up to 50x speedup, 80x without CPU-GPU data transfers) and 5x times faster than using all the MPI process available
- The Multi-cells strategy allows the integration of GPU modules inside a CPU solver
- The best kernel settings for the Block-cells strategy is using 1 cell per GPU block, achieving from 1x to 3x speedup from computing multiple cells in a block.



Next steps

Use the 4 GPUs available

 Translate the rest of the chemical solving to GPU (minimizing communications CPU-GPU)

Evaluate more chemical configurations

Integrate into MONARCH (exploit an heterogeneous approach)



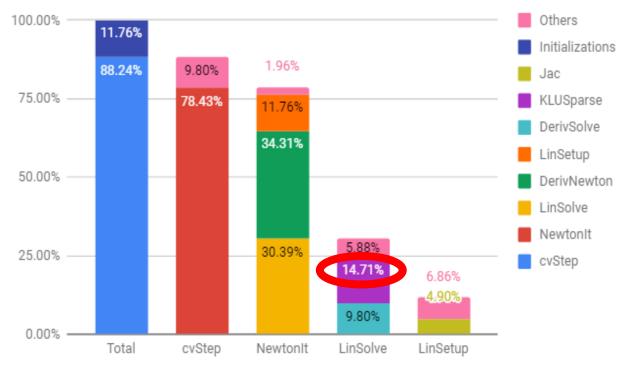


Thank you

christian.guzman@bsc.es

Performance improvement over CAMP

CAMP solving function time percentages with CPU KLU SPARSE using 10,800 cells



CAMP solving function time percentages with GPU Block-cells Biconjugate Gradient using 10,800 cells

