#### WG4: Random errors

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 $(x-x) + (x - H[x])^{T}R^{-1}(y - H[x])$ 

### Overview

- This meeting was hugely interesting and beneficial!
- We all agree that we need to better understand observation uncertainties.
- We should continue to collaborate and share are progress and ideas on a regular basis.
- Top priorities:
  - Situation dependence
  - Horizontal correlations

 $T_{B^{-1}(x, x)} + (x - H[x])^{T} R^{-1} (y - \Lambda)$ 

• Understanding our tools.

#### What tools do we have to estimate observation errors and how well

- We have a variety of methods, but no one covers all our needs.
- Complex methods (e.g. metrological approach) provide great insight into error sources, but are time consuming we may not be able to use full estimates in assimilation.
- Desrozirers is easy to use but very approximate. It is not going to disappear! Therefore better theoretical understanding would be good:
  - Does forward model error end up in R or  $\mathsf{HBH}^{\mathsf{T}}$
  - What do we know about sampling error

 $(y - 1) + (y - H[x])^{T} R^{-1} (y - 1)$ 

- We should use more than one method for estimation and compare to give confidence in our estimates.
- We should routinely monitor our uncertainties using Desroziers, but use other methods intermittently to sanity check our routine estimates.
- How do we determine what level of sophistication is needed?

## What is the status of accounting for inter-channel observation error correlations?

- Vast majority are using inter channel correlated error for IR (hyperspectral, geo), less so for other observation types.
- Discussion on why does all-sky work well using a diagonal R. Understanding this is a priority.
  - Will include testing correlation in all-sky.
  - Is it simply because variances are high?

 $V^{T}B^{-1}(x-x) + (x - H[x])^{T}R^{-1}(y - H[x])$ 

#### What is the status of accounting for spatial observation error correlations?

- Only Met Office radar are operationally assimilated with horizontal error correlations.
- In general we would like to use these uncertainties, but we do not have the technology/algorithms in place.
- There is work on possible methodologies, and it likely that we will need to use different methods for different observation types.
- Can we assess the relative importance of for inter-channel and spatial correlations or do we need to account for them simultaneously, if so how?
- Different systems may see different benefit from using spatial correlations.
- Can we learn from the modelling of B.

 $(x_{1}^{T} B^{-1}(x_{1}, x_{2}) + (x_{1}^{T} H[x])^{T} R^{-1}(y - H[x])$ 

• There is emerging benefit from accounting for horizontal correlations. It is likely that the benefit will need to be proved in convective scale NWP before global/medium range systems see this as a priority.

#### Situation-dependence of observation errors

- Considered most important area to develop
- All-sky systems already use situation dependent variances, using cloud predictors and situation dependent correlations have been tested
- Variances also tuned using 1D-Var outputs

 $y^{T} R^{-1} (y - H[x])^{T} R^{-1} (y - H[x])$ 

- Discussion on flow dependence vs situation dependence (e.g seasonal variation)
- Challenges are very specific to observation types, so its hard to compare experiences

#### Discussion on use of observation errors in deterministic analysis, 1D-Var, Ensemble initialisation

- Already some differences in use of R in different systems
- Judgement is this isn't an issue
- No strong view from the group

 $T_{B^{-1}(x-x-y)} = (x - H[x])^{T} R^{-1}(y - H[x])$ 

#### **Pre-conditioning aspects, convergence issues**

- Conventional wisdom is adding correlations makes convergence worse but this is not always case
- Discussion on interpretation of small eigenvalues (physical, mathematical)
  - Are they trustworthy if no physical understanding?

 $\sum_{k=1}^{T} (x - x_{k}) + (x - H[x])^{T} R^{-1} (y - H[x])$ 

- View is both eigenvalue floor and ridge regression methods work well in an operational context
  - interesting to study further, not an operational priority.

Coupled data assimilation/Earth System assimilation: What may become more important for observation error specification?

- R that works for coupled may not be optimal representation in coupled DA framework (resolution requirement may change, making spatial correlation more important to address)
- Recognised as an interesting topic, but not a priority

 $TB^{-1}(\mathbf{x},\mathbf{x}) + (\mathbf{x},\mathbf{H}[\mathbf{x}])^{T}\mathbf{R}^{-1}(\mathbf{y}-\mathbf{H}[\mathbf{x}])$ 

### What role can we see for machine learning approaches and observation error specification?

• For random error no obvious role

 $T_{B^{-1}(x-x)} = (x - H[x])^{T} R^{-1}(y - H[x])$ 

- However possible use could be studied for observations with little or no meta data
- General sceptical view of usefulness in this area

# Where do we see further scope for improving observation error specifications?

- Independence of background and observation errors can this assumption be relaxed, or what is the impact of errors in this assumption?
  - Could be studied using simplified models (maybe with OOPS)
  - But a low priority

 $(x_{1})^{T} B^{-1}(x_{1},x_{2}) + (x_{2} - H[x])^{T} R^{-1}(y - H[x])$ 

- Temporal errors?
  - Geo radiances work has shown going down to 20m showed benefit without treating temporal correlation, but down to 10m issues occurred (solved through inflation)
  - Priority in this area seems lower than situation dependent and spatial correlation error modelling
- Are correlated errors more important for very accurate observations? Is this true? Link to all-sky, reconstructed radiances. Worth studying this question.