

# Neural networks for post-processing ensemble weather forecasts

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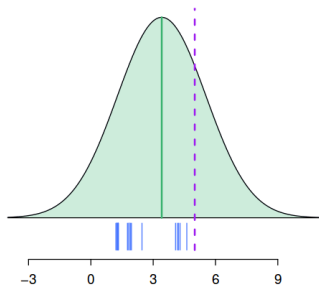
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# Post-processing with distributional regression models

NWP ensemble forecasts exhibit **systematic errors** (biases, lack of calibration, ...) that require correction via **post-processing**.

This is achieved via **distributional regression** models for **statistical post-processing** which produce forecast distributions.

**Example:** EMOS for temperature forecasting



Using ensemble predictions of temperature as input the **post-processed** forecast takes the form of a Gaussian distribution.

$$y|\mathbf{X}^{\text{t2m}} \sim \mathcal{N}_{(\mu, \sigma)},$$

$$\mu = a + b \cdot \text{mean}(\mathbf{X}^{\text{t2m}})$$

$$\sigma = c + d \cdot \text{sd}(\mathbf{X}^{\text{t2m}})$$

# Parametric distributional regression models

Model probability distribution of target variable  $y$  given input predictors  $\mathbf{X}$  by a parametric distribution  $F_{\theta}$ ,

$$y|\mathbf{X} \sim F_{\theta}, \quad \text{where} \quad \theta = g(\mathbf{X})$$

with a link function  $g : \mathcal{X} \rightarrow \Theta$  connecting predictors  $\mathbf{X}$  and distribution parameters  $\theta$ .

**Limitations** of fully parametric approaches:

- ▶ requires choice of **link function**  $g$ 
  - ▶ difficult to specify **functional form** of dependencies if many possible predictors are available
- ▶ requires **estimation** of parameters of  $g$ 
  - ▶ **global** (using all training data) or **local** (location-specific) models?
- ▶ requires choice of **parametric model**  $F_{\theta}$

# Neural networks for distributional regression

Novel semi-parametric approach to distributional regression:  
Estimate distribution parameters  $\theta$  directly as output of a neural network designed to

- ▶ learn arbitrary nonlinear relations between predictors and distribution parameters in an automated, data-driven manner,
- ▶ generate local adaptivity in globally estimated models,
- ▶ gain meteorological insight from trained models.

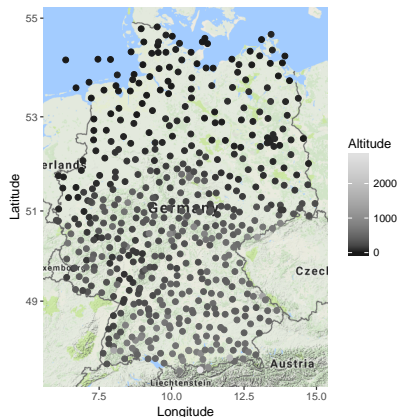
Rasp, S. and Lerch, S. (2018)

**Neural networks for post-processing ensemble weather forecasts,**  
*Monthly Weather Review*, 146, 3885–3900.

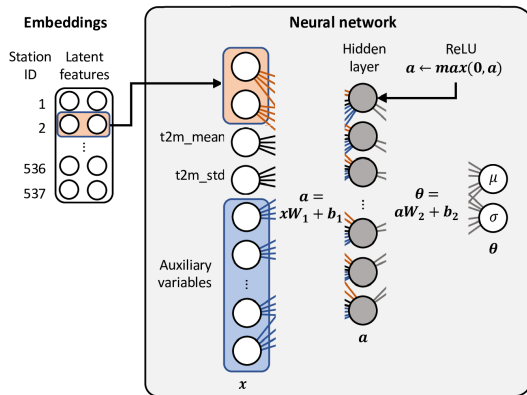
Python/R code available at <https://github.com/slerch/ppnn>.

# Data

- ▶ 10 years of forecasts and observations (2007–2016)
- ▶ 48 hours-ahead ECMWF 50-member ensemble forecasts of temperature (and 17 other variables)
- ▶ station observations at 537 locations
- ▶ data from 2016 used as evaluation set
- ▶ two training datasets: 2015 and 2007–2015



# Neural networks for distributional regression



- **Input:** Predictor variables (NWP quantities, station characteristics).
- **Output:** Distribution parameters  $\theta$
- **Embeddings** generate local adaptivity.

Training via CRPS minimization (mathematically principled non-standard choice).

# Advanced benchmark methods

- ▶ **Gradient boosting** for EMOS (Messner et al., 2017):  
Let  $F_{\theta} = \mathcal{N}_{(\mu, \sigma)}$  and

$$(\mu, \sigma) = \left( \mathbf{X}^T \boldsymbol{\beta}, \exp(\mathbf{X}^T \boldsymbol{\gamma}) \right),$$

and iteratively update coefficient vector entries improving the current model fit most.

- ▶ **Quantile regression forest** (Meinshausen, 2006; Taillardat et al., 2016): Nonparametric quantile regression based on random forests. Quantile estimates are obtained from an ensemble of decision trees.

Have to be implemented as **local** models to achieve good forecasts.

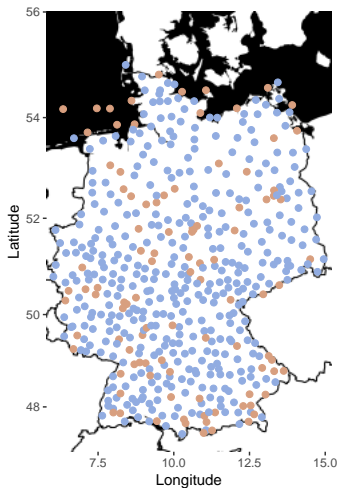
# Overview of results

CRPS: Continuous ranked probability score, **lower is better**

Model	Mean CRPS for training period	
	2015	2007–2015
Raw ensemble	1.16	1.16
<i>Benchmark post-processing methods</i>		
Global EMOS	1.01	1.00
Local EMOS	0.90	0.90
Local EMOS with boosting	0.85	0.80
Local quantile regression forest	0.95	0.81
<i>Neural network models</i>		
Neural network with auxiliary predictors and station embeddings	<b>0.82</b>	<b>0.78</b>



# Station-specific comparison of NN and benchmark models

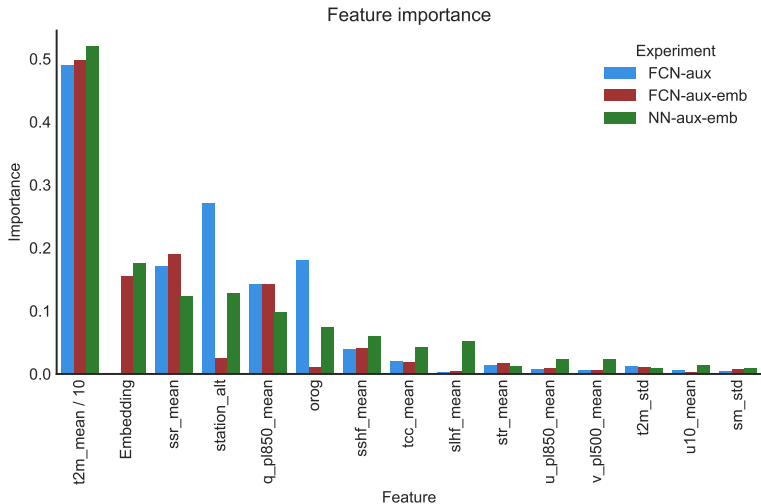


Station-specific best model is a  
NN model / benchmark model

NN models perform best at more  
than 80% of the stations.

Differences are statistically signifi-  
cant at a large fraction of stations.

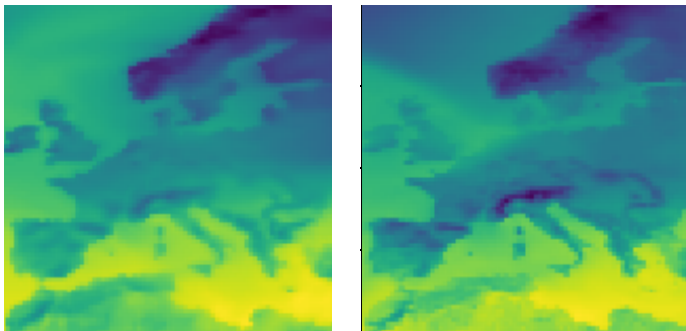
# Meteorological interpretation of neural network models



Change in mean CRPS after permuting a single input variable according to a random permutation across stations and dates.

# Incorporating spatial information

Ensemble forecasts are **gridded 2D fields** of forecasts of weather variables. Thus far, those were **interpolated** to station locations.

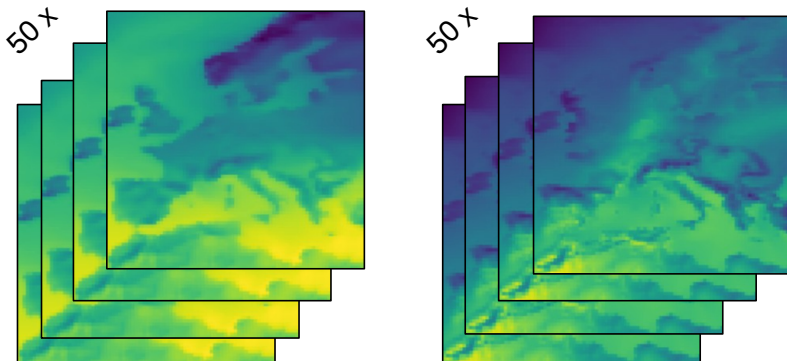


Gridded ECMWF forecasts over Europe ( $0.5^\circ$  resolution,  $81 \times 81$  pixels)

However, large-scale **spatial structure** and **predictability information** (e.g., 'weather regimes') get lost in the interpolation step.

## Ensemble information

Ensemble members provide 50 **physically coherent** forecasts of weather variables. Thus far, only **mean and standard deviation** of (interpolated) ensemble forecasts were used.

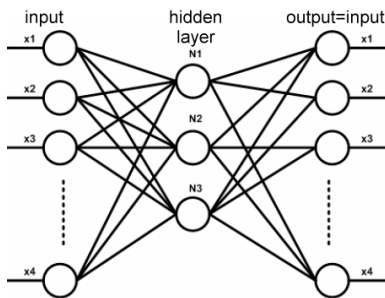


Possibly important **uncertainty information** might get lost by the use of summary statistics.

# Deep autoencoders for dimensionality reduction

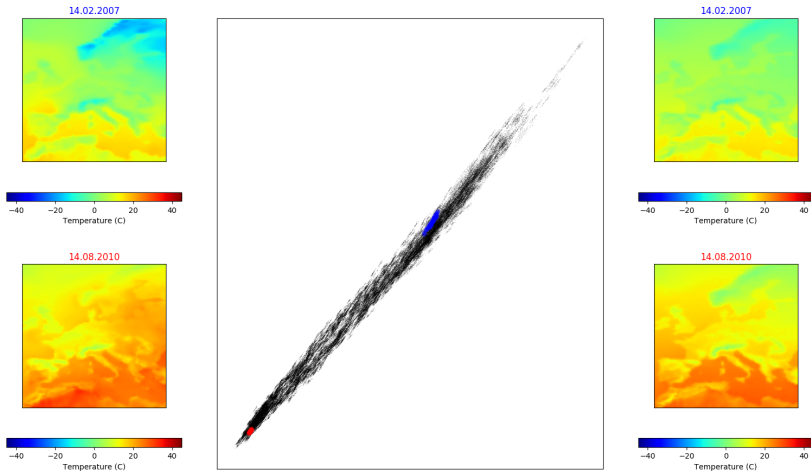
Specific NN architectures to learn a compact representation of inputs (**unsupervised**) by

- ▶ training the network to re-create its own inputs
- ▶ creating a bottleneck by using fewer hidden units than inputs



- ▶ latent information from spatial forecast fields **encoded in hidden layer** can be used as an **additional input** to the NN model for distributional regression

# Projections of ensemble forecasts (temperature)

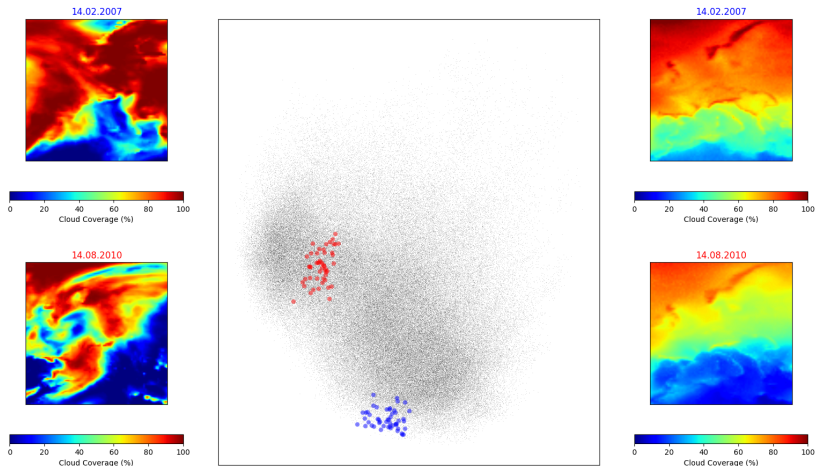


Left: Example input forecast fields from two days.

Middle: Ensemble members in projected space (blue: top, red: bottom).

Right: Reconstructed fields.

# Projections of ensemble forecasts (cloud cover)



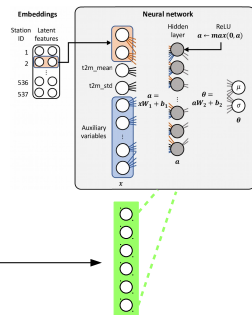
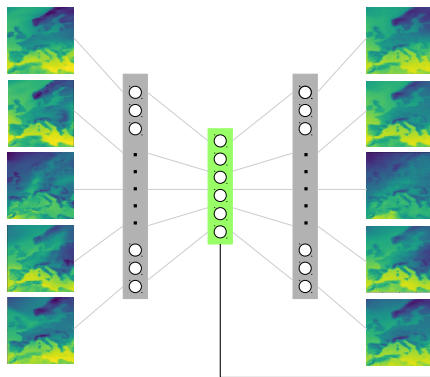
**Left:** Example input forecast fields from two days.

**Middle:** Ensemble members in projected space (blue: top, red: bottom).

**Right:** Reconstructed fields.

# Autoencoder representations as additional NN-input

## 1. Autoencoder neural networks for nonlinear dimensionality reduction of spatial input fields



## 2. Latent representations as additional model input for post-processing

Preliminary results suggest improvements in mean CRPS.

Ongoing joint work with Kai Polsterer.



