

# The Joint Effort for Data assimilation Integration (JEDI)



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**Joint Center for Satellite Data Assimilation (JCSDA)**

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**Joint ECMWF/OceanPredict workshop on Advances in  
Ocean Data Assimilation**

# JEDI Objectives



The Joint Effort for Data assimilation Integration (JEDI) is a collaborative development between JCSDA partners

Develop a unified data assimilation system:

- From toy models to Earth system coupled models
- Unified observation (forward) operators (UFO)
- For research and operations (including O2R2O)
- Share as much as possible without imposing one approach

Design driven by scientific vision for data assimilation

- Not trying to salvage old codes at all cost

# JEDI is a Joint Effort



**JEDI core-team:** A. Shlyaeva, B. Ménérier, C. Gibert, C. Gas, D. Holdaway, E. Lingerfelt, M. Miesch, M. Olah, M. Abdi-Oskoueï, R. Grubin, R. Honeyager, S. Herbener, S. Vahl, Y. Trémolet

**JEDI contributors (2020):** A. Weinbren, B. Johnson, BJ Jung, C. Pelley, C. Harrop, C. Martin, C. Thomas, D. Davies, D. Simonin, E. Liu, F. Diniz, F. Vandenberghe, G. Vernières, G. Thompson, H. Zhang, H. Ebrahimi, H. Kershaw, H. Shao, I. Genkova, J. McCreight, J. Rosinski, J. Guerrette, J. Ban, M. Wlasak, M. Pagowski, M. Cooke, N. Bowler, O. Lomax, R. Mahajan, R. Todling, S. King, S. Frolov, S. Sandbach, T. Sluka, V. Buchard, W. Śmigaj, X. Zhang, and more...

**JEDI collaborators:** C. Snyder, D. Kleist, D. Dee, N. Baker, R. Gelaro, T. Auligné, ...

**Representing:** JCSDA, NOAA/EMC, NOAA/ESRL, NASA/GMAO, NRL, USAF, NCAR, UKMO

And more than 200 padawans who attended five JEDI Academies

# October 2020: First JEDI Release



## Releases

### JEDI-FV3 RELEASE

#### CRTM RELEASE

## JEDI-FV3 Release

The JEDI-FV3 release contains everything needed to emulate a simplified version of the JCSDA near-real-time (NRT) applications websites with [JEDI-GFS](#) and [JEDI-GEOS](#). This includes interfaces for processing a wide variety of observational data and a library of observation operators for conventional, satellite radiance and GNSS radio-occultation measurements that can be run from both FV3-based GFS and GEOS models.

Version	Download	Quick Start - Tutorials	Support	Date
1.0.0	<a href="#">Code</a>	<a href="#">Run JEDI-FV3 in a Container</a>	<a href="#">Documentation</a>	2020-10-28
<a href="#">Release Notes</a>		<a href="#">Simulate Observations Like JCSDA NRT Application</a>	<a href="#">Forums</a>	
		<a href="#">Build and Test JEDI-FV3</a>		

Next release  
coming soon!

Available at <https://www.jcsda.org/jedi-fv3-release>

# JEDI Working Practices



- **Project methodology inspired by Agile/SCRUM**
  - Adapted to distributed teams and part time members
  - Work in small manageable increments with constant feedback
- **Collaborative environment**
  - Easy access to up-to-date source code (github)
  - Easy exchange of information (zenhub)
  - Weekly meetings by video (40 to 60 developers from at least 7 organizations)
  - Code sprints (8-10 developers working together on a specific topic, virtual in 2020/21)
- **Enforce software quality**
  - Automated testing: correctness, coding norms, efficiency
  - Code reviews (all developers actively involved)
- **Portability is part of the development**
  - Automatic tests with several compilers
  - JEDI available in containers (docker, singularity, charliecloud)
- **Modern programming technologies** (generic, object oriented)

JEDI is active:  
> 200 PR merged /  
month on average



# Object Oriented Prediction System (OOPS)

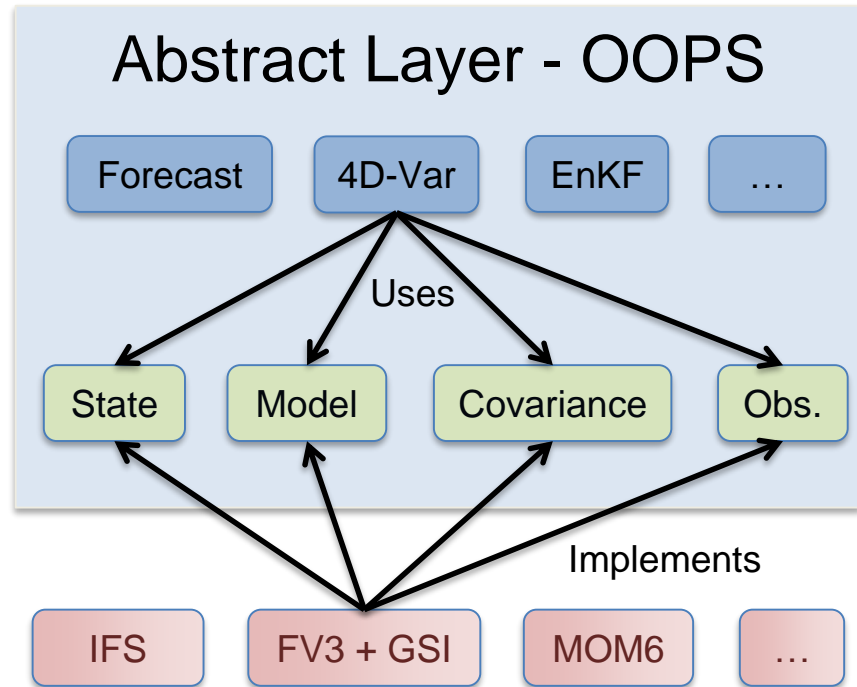


Generic, portable, model-agnostic  
DA system

Use **object-oriented** and **generic**  
programming

Each model implements pre-defined  
abstract interfaces

**Separation of concerns**



# JEDI: Abstraction and Genericity

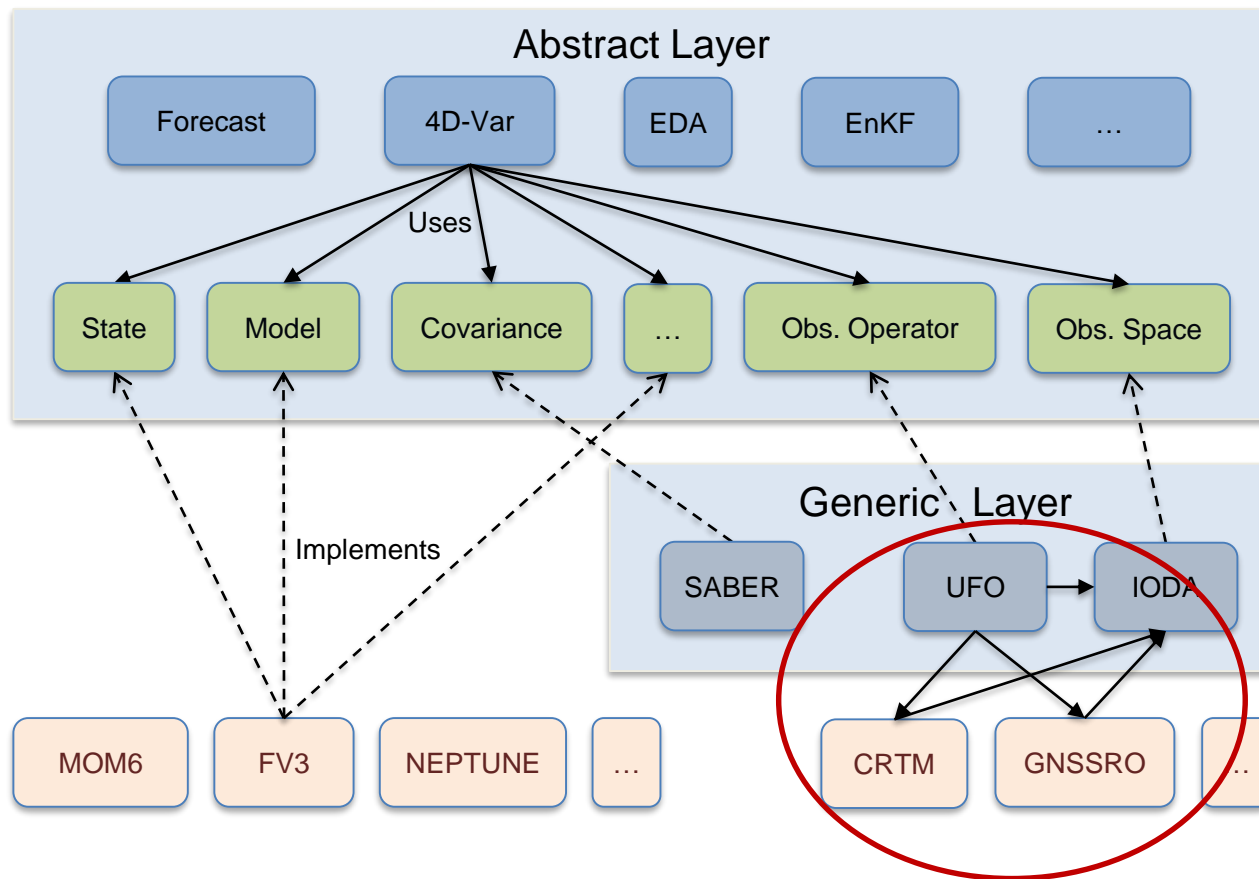


Generic Algorithms

Abstract Interfaces

Generic Implementations

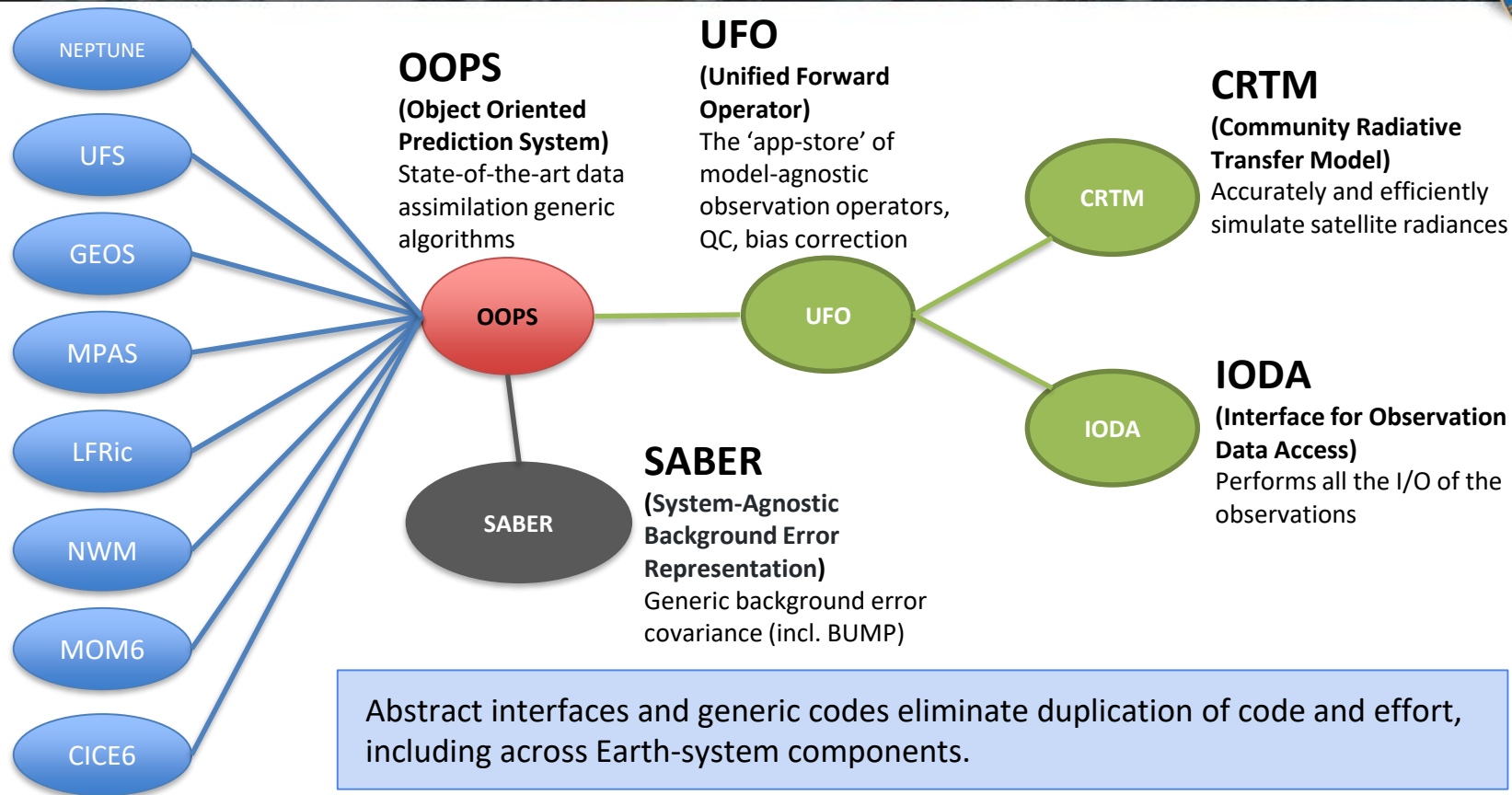
Specific Implementations



Abstract,  
model-agnostic  
DA system

OOPS is  
complemented  
by generic  
(shared)  
components.

# JEDI Structure





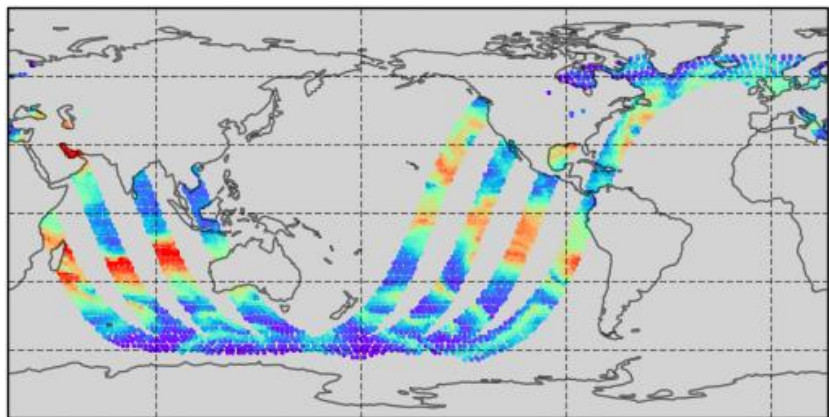
# GEOS in-core Data Assimilation



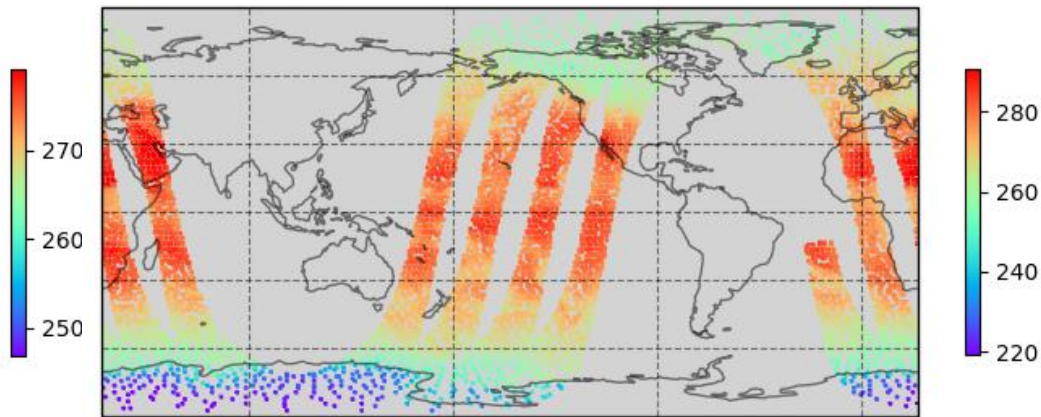
- Model runs in-core with FV3-JEDI.
- States can be exchanged from the model and be passed back to the model.
- Model can be rewind and used in outer loops.

Figures below show the in-core four-dimensional observation simulations for GMAO's production system. This is part of a continuously running near real time workflow.

GPM GMI Channel 6 h(x)  
2020-10-17T09:00:00 - 2020-10-17T15:00:00



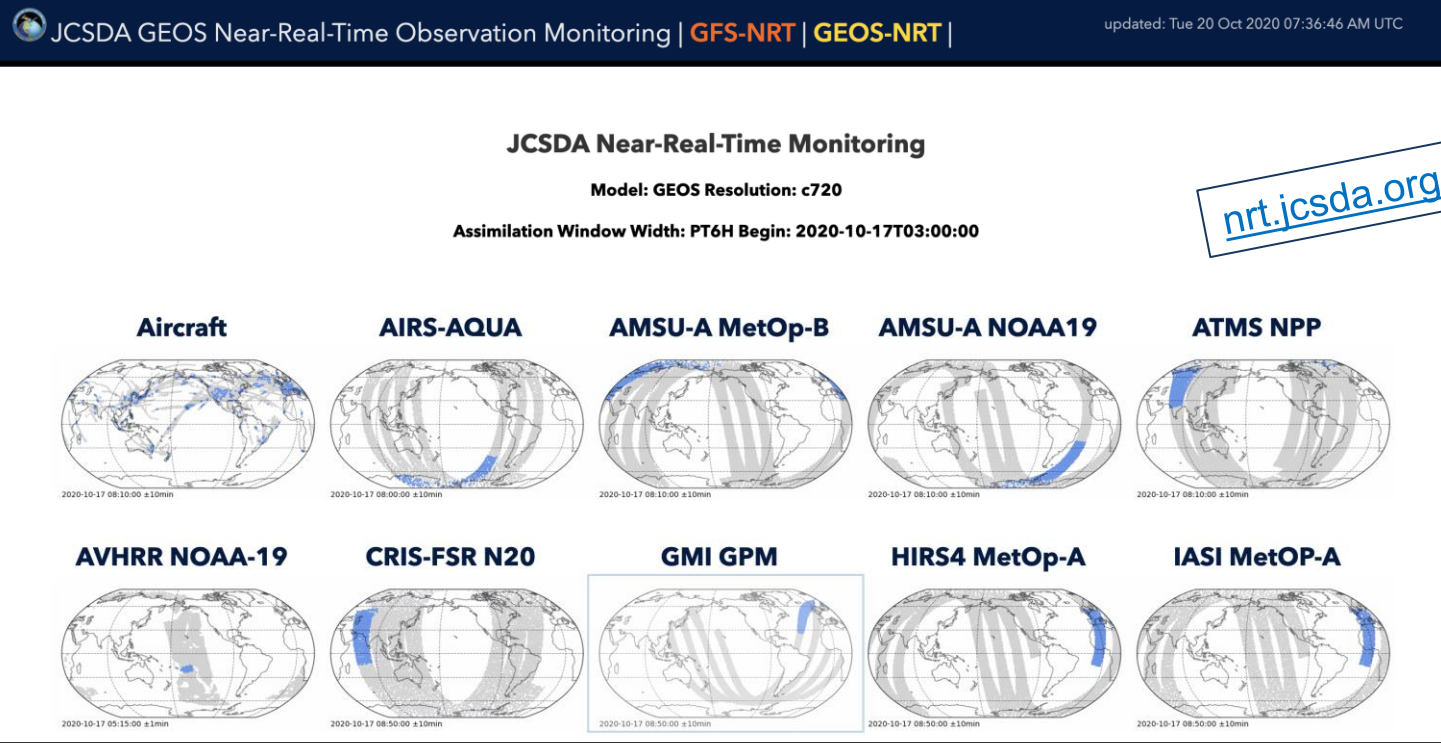
AQUA-AIRS Channel 1371 h(x)  
2020-10-17T09:00:00 - 2020-10-17T15:00:00



# GEOS NRT observation simulation



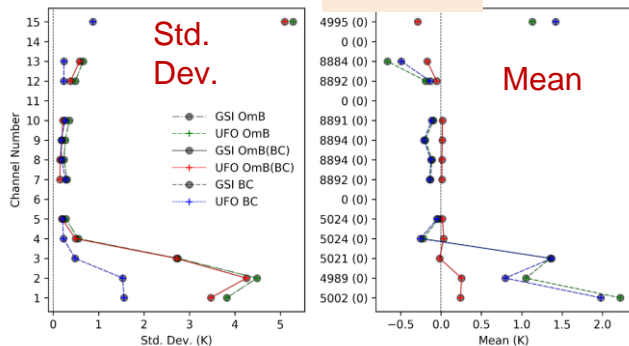
Continuously running in-core 4D H(x) using restarts and a subset of observations from GMAO's production system. Results are posted in near real time to the JCSDA website:



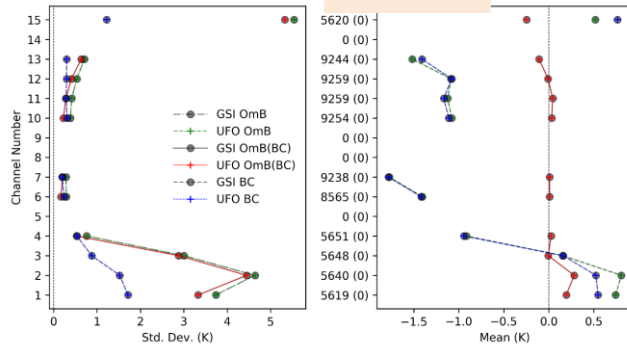
# UFO Validation against GSI (ASMU-A)



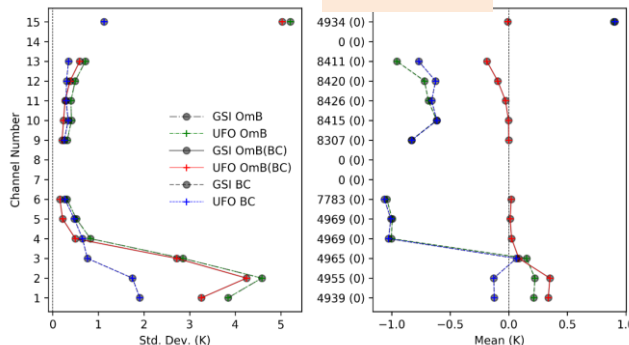
NOAA-15



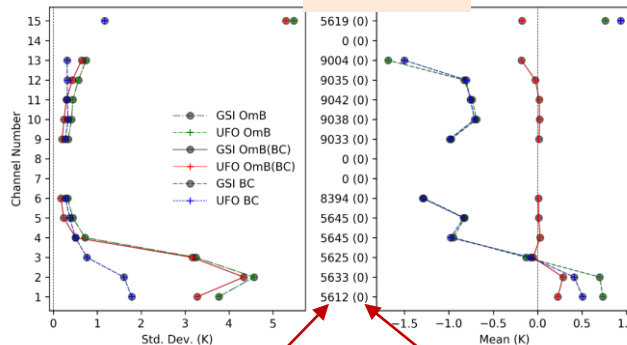
NOAA-18



NOAA-19



METOP-A



GDAS operational platforms/sensors (~GFSv15.3) were tested by JCSDA for one cycle using EMC provided obs and geovals

Code/configurations are in github repo (develop)

Figures from JCSDA OBS team (H. Shao *et al.*)

GSI and UFO values on top of each other

Obs # passed GSI QC

# difference between JEDI and GSI Qced observations



# JEDI-GODAS: Observations



## Generic Quality Control: No Coding!

```
obs filters:  
- filter: Domain Check  
  where:  
  - variable: {name: sea_area_fraction@GeoVals}  
    minvalue: 0.9  
- filter: Domain Check  
  where:  
  - variable: { name: sea_surface_temperature@GeoVals}  
    minvalue: 5.0  
- filter: Background Check  
  absolute threshold: 0.2  
- filter: Bounds Check  
  minvalue: -2.0  
  maxvalue: 2.0  
  action:  
    name: assign error  
    error function:  
      name: LinearCombination@ObsFunction  
      options:  
        variables: [mesoscale_representation_error@GeoVals,  
                   obs_absolute_dynamic_topography@ObsError]  
        coefs: [0.1,  
               0.01]  
- filter: BlackList  
  where:  
  - variable:  
    name: latitude@MetaData  
    minvalue: -65  
    maxvalue: -30  
  - variable:  
    name: longitude@MetaData  
    minvalue: -125  
    maxvalue: -90  
- filter: BlackList  
  where:
```

Land mask

Reject ADT obs if  
 $SST < 5^{\circ}C$

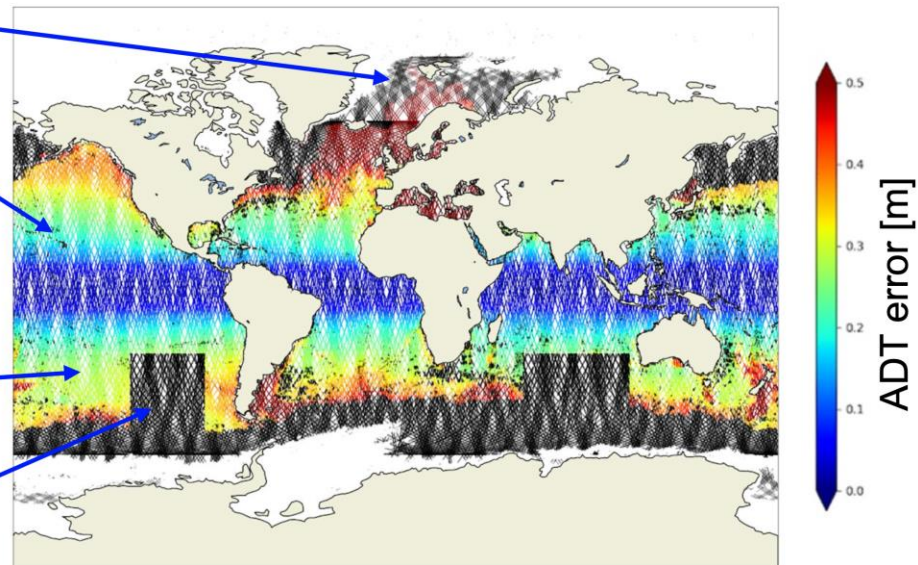
Reject ADT obs if  
 $|Obs - Bkg| < 0.2 \text{ m}$

Reject ADT obs  
outside of  
 $[-2.0\text{m}, 2.0\text{m}]$

Assign ADT  
obs error  
[m]

Reject ADT obs in  
specific region

### ● Rejected observations



Figures from SOCA team

# JEDI-GODAS: Covariance Modeling



$$B = K F_h^{\frac{1}{2}} D_p D_f C_v^{\frac{1}{2}} \mathbf{C}_h C_v^{\frac{1}{2}} D_f D_p F_h^{\frac{1}{2}} K^T$$

**B-matrix on Unstructured Mesh Package**  
(BUMP, Benjamin Menetrier)

Impulse response of  $\mathbf{C}_h$  to dirac  
delta functions

**BUMP  $\mathbf{C}_h$  operator** is similar  
to a diffusion operator at a  
fraction of the computational  
cost

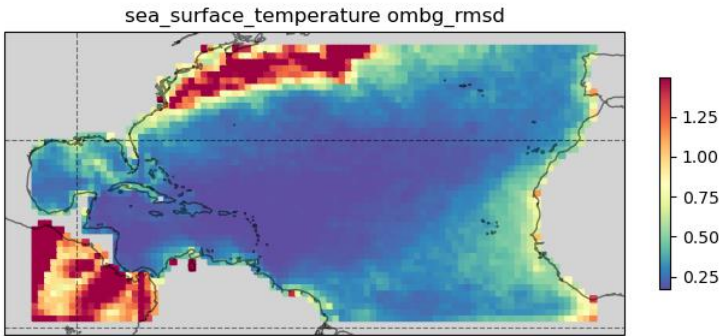
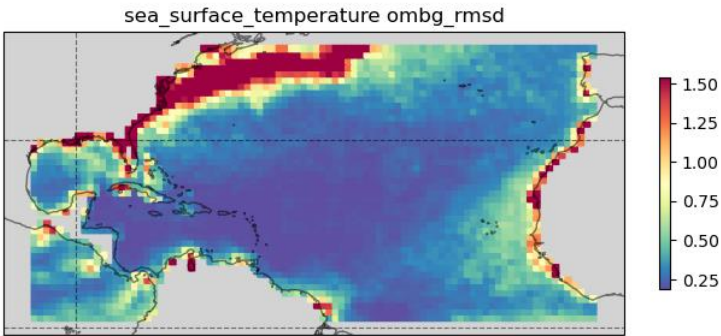
More in talk later in this session



# Ocean Global and Regional DA

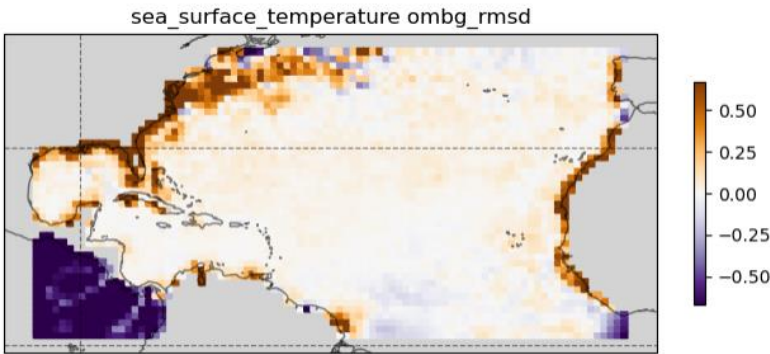


## SST HAT10 vs Global UFS (1 degree)



2015-01-01 00Z to 2015-12-31 23Z

JCSDA ioda-plots



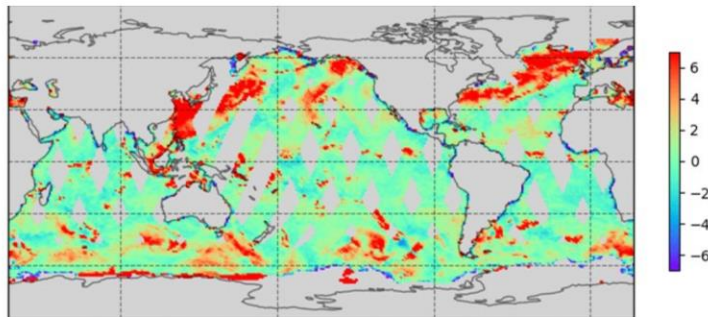
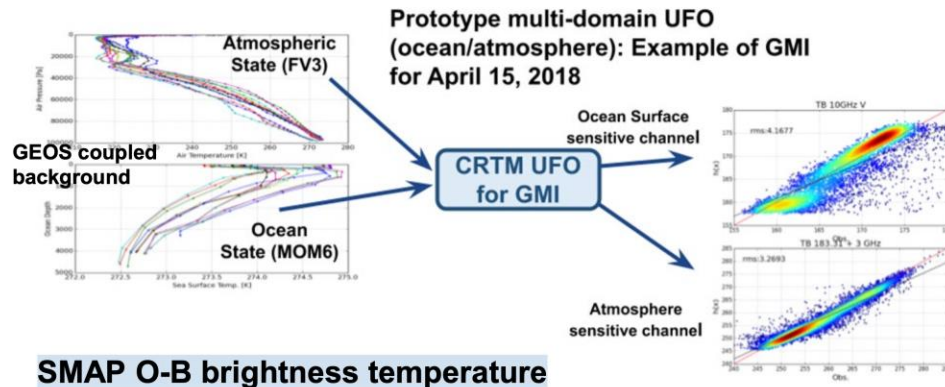
Figures from  
SOCA team

# SOCA: Towards Coupled DA



Hamideh Ebrahimi (JCSDA)

- direct assimilation of MW brightness temperatures
  - SST (**GMI**)
  - SSS (**SMAP**)
- using CRTM with 2 domains (atmosphere & ocean)



2015-01-01 01Z to 2015-01-01 23Z

JCSDA ioda-plots

# JCSDA Workflow Requirements



## Models

- FV3-GFS / FV3-GEOS
- MOM6 / SOCA
- UFS
- MPAS
- Neptune
- LFRic
- ...

## Systems

- HPC (NOAA, NASA, Navy, USAF, NCAR, Met Office...)
- Cloud (AWS, ...)
- Workstations, laptops (Linux, OSX)

## Workflow engines

- ecFlow
- Cylc
- Airflow...

In addition to all *normal* operational and research requirements

# EWOK + R2D2



**EWOK** provides generic tools to describe suites = abstract algorithms (same concepts as OOPS/JEDI).

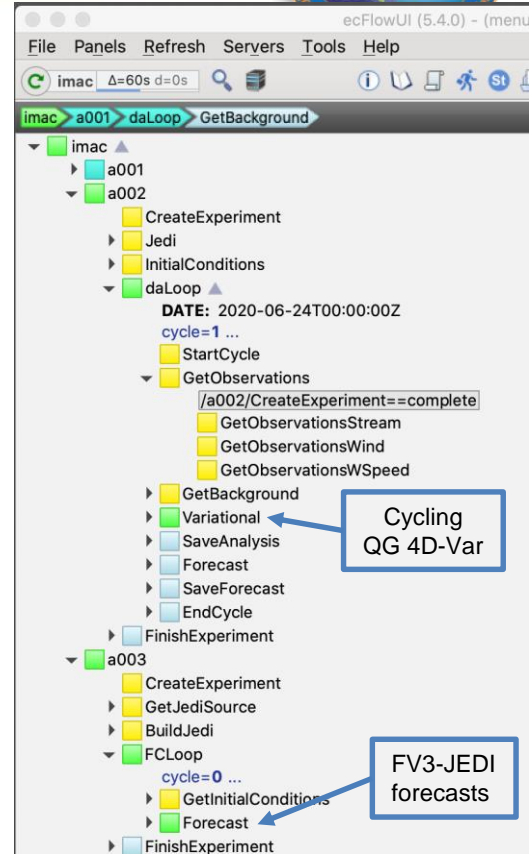
Tasks are generic, with model specific implementations only when required (same concepts as OOPS/JEDI).

Given specific parameters (experiment configuration) a suite is generated for a target model (UFS, GEOS), workflow engine (ecflow, cylc) and machine (Orion, Discover).

Data access is a major obstacle to portability and genericity,

**R2D2** abstracts storage from the workflow:

- Data is managed and accessed by key/values (not path or filename).
- Easy access for experiments (HPC, cloud) and diagnostics (desktop, cloud).
- It can store/fetch data in the cloud (S3) and locally, or a combination of both (local data store first, then remote).



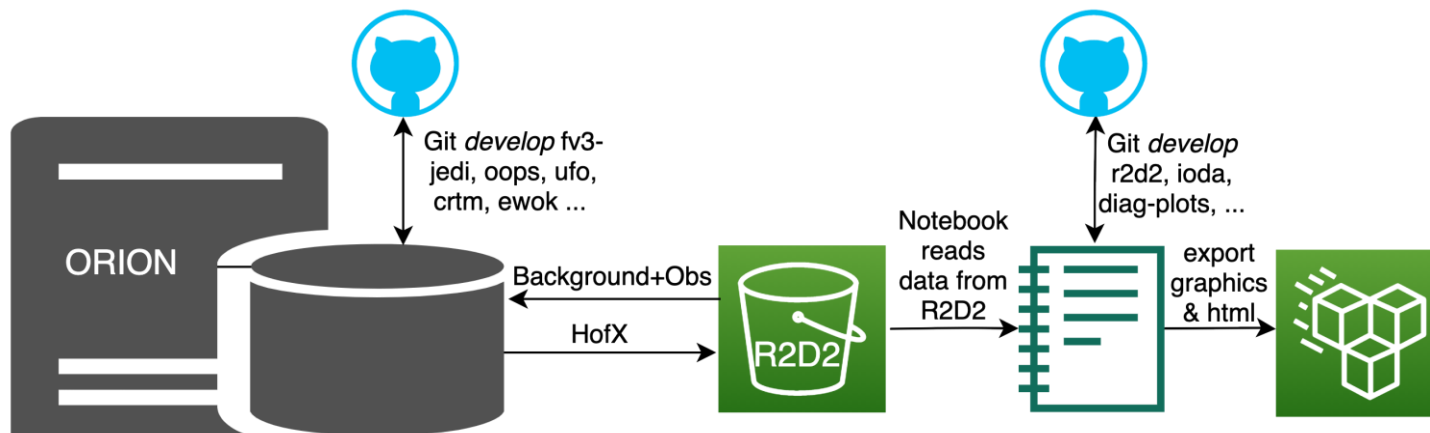


# Generic Diagnostics



Output of EWOK experiments are stored in R2D2 on AWS:

- Jupyter notebooks for interactive diagnostics
- Immerse scientists into the data
- Collective scientific diagnostics and inter-comparisons
- Easy interfacing with ML tools (SageMaker...)





# Final Comments



JEDI is becoming more mature:

- “H(x)” computed in near real time for monitoring
- The system will evolve in non-cycling, then cycled data assimilation applications with more models

Next steps:

- Environment for running and managing experiments (HPC and cloud)
- Cloud-based interactive diagnostic tools
- Scientific validation (operational-grade cycling experiments)
- Coupled DA (Coupled H(x), Coupled B, Coupled solvers)
- Investigate integration of AI/ML