

L-band RFI in NWP

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- Introduction
- GRDS SMOS results
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- Conclusions and future work

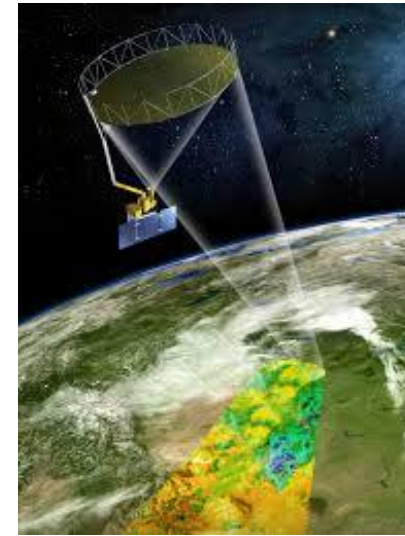
SMOS

- SMOS is the soil moisture and ocean salinity mission
- ESA Earth Explorer satellite launched in 2009
- Operated well beyond it's originally planned lifespan



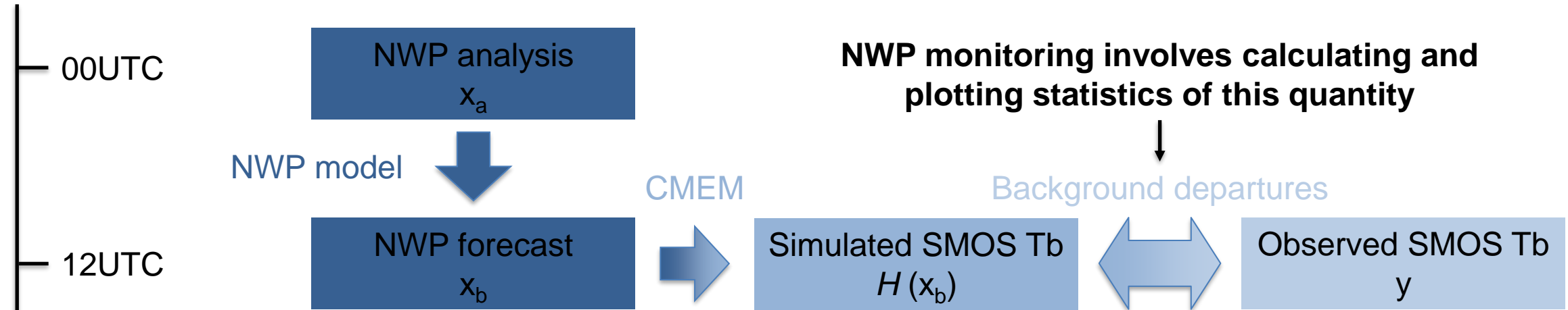
SMAP

- SMAP is the Soil Moisture Active-Passive mission
- NASA research satellite launched in 2015
- Active radar failed soon after launch but passive radiometer still operating



- Both are passive microwave instruments measuring L-band (1.4 GHz) brightness temperatures
 - Sensitive to ocean salinity and surface wind speed over ocean
 - Sensitive to soil moisture over land
 - Heavily affected by RFI e.g. military radar, wireless security cameras, satellite TV etc.

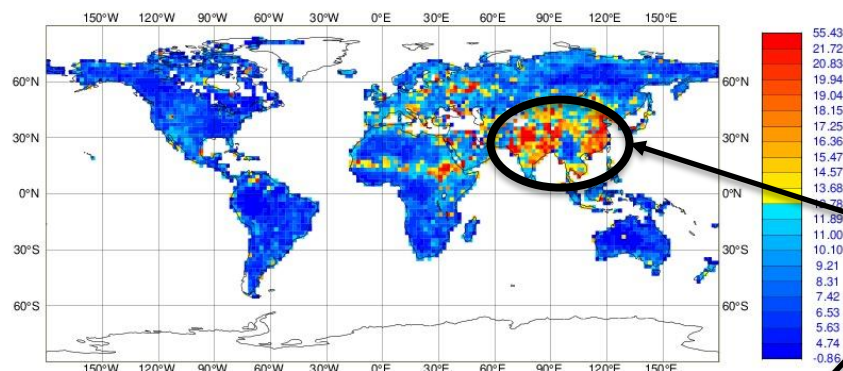
NWP monitoring introduction



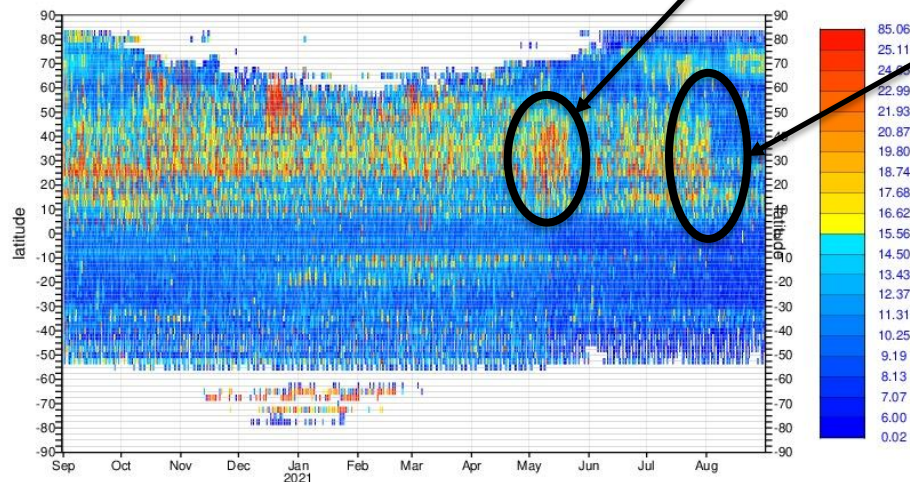
Neither the NWP model output or CMEM have any knowledge of simulation of RFI

RFI in the observations therefore results in large discrepancies between the observations and model

STATISTICS FOR RADIANCES FROM SMOS/SMOS
 STDV OF FIRST GUESS DEPARTURE (ALL)
 DATA PERIOD = 2021-07-31 21 - 2021-08-31 21
 EXP = 0001, CHANNEL = 2 (FOVS: 45-54)
 Min: 0.038 Max: 54.532 Mean: 7.989
 GRID: 2.00x 2.00



STATISTICS FOR RADIANCES FROM SMOS/SMOS
 CHANNEL = 2 (FOVS: 45-54) [TIME STEP = 12 HOURS]
 STDEV FIRST GUESS DEPARTURE , ALL
 EXP = 0001, DATA PERIOD = 2020083106 - 2021083118, AREA = 90S - 90N/ 200 - 180
 Min: 0.016 Max: 85.063 Mean: 12.059

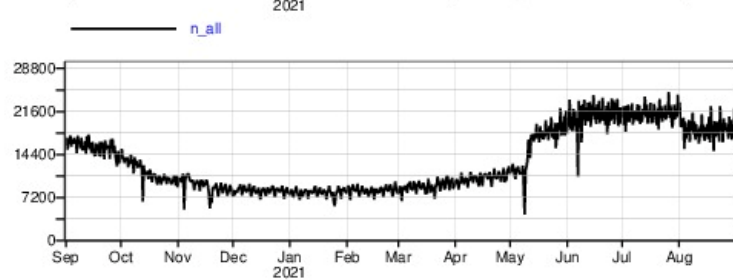
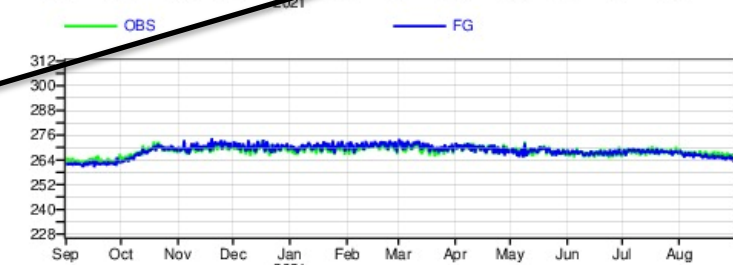
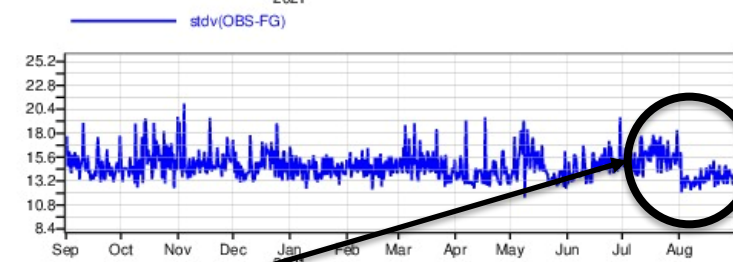
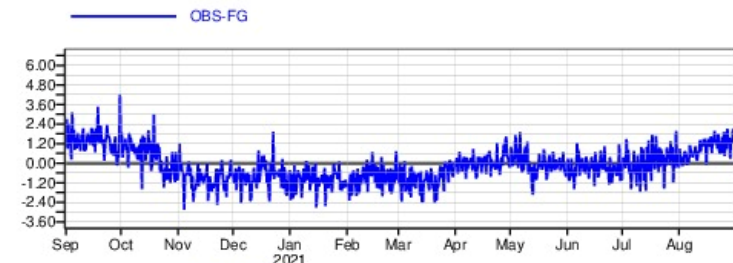


Examples of NWP monitoring plots

Despite existing RFI screening we still see RFI signatures

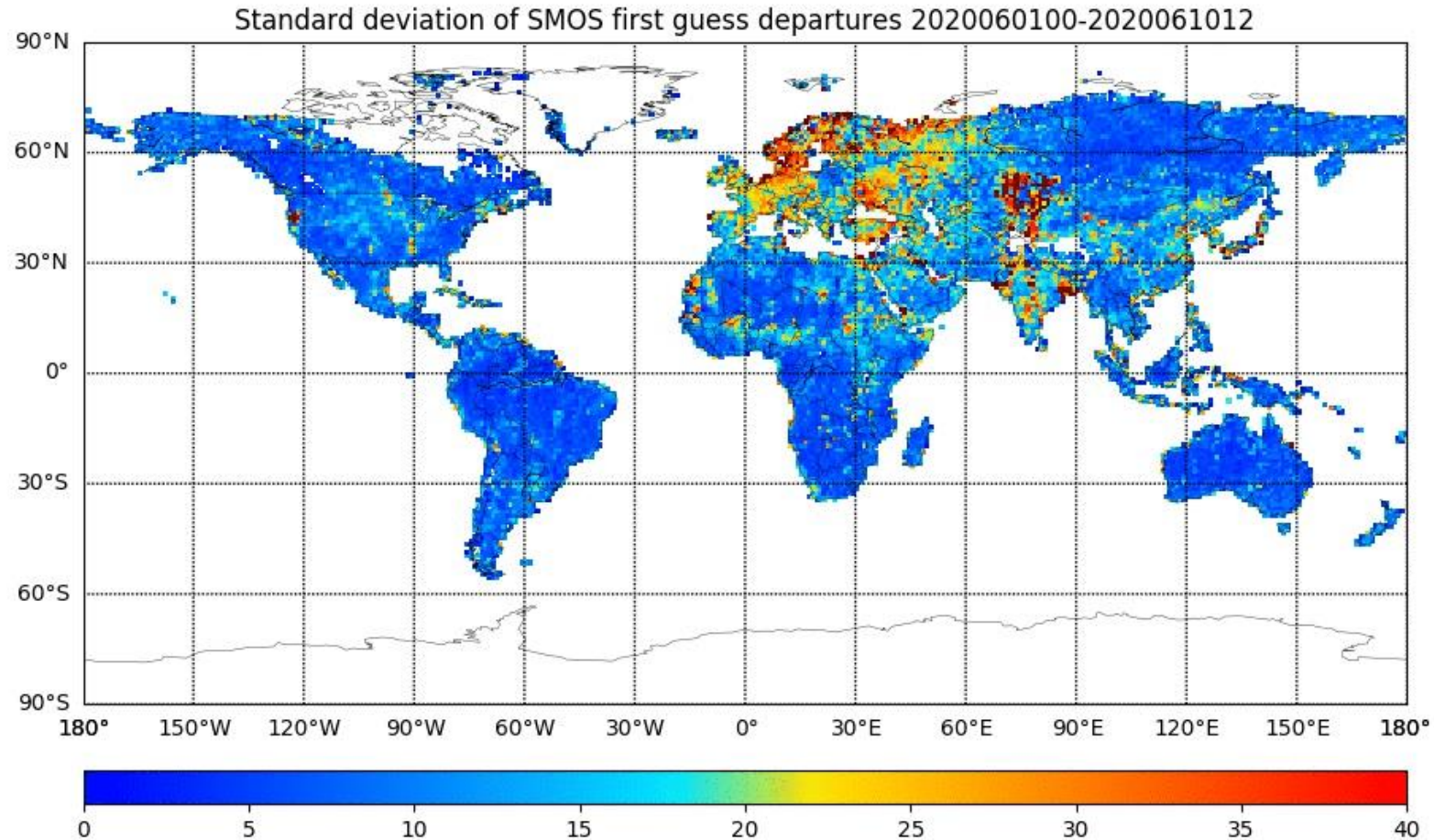
Recent improvements to SMOS RFI screening visible in statistics

STATISTICS FOR RADIANCES FROM SMOS/SMOS
 CHANNEL = 2(FOVS: 37-45), ALL DATA [TIME STEP = 12 HOURS]
 Area (GLOBE) : lon_w= 240.0, lon_e= 240.0, lat_s= -90.0, lat_n= 90.0 (over Land)
 EXP = 0001 (LAST TIME WINDOW: 2021083109)



RFI

- L-band RFI sources are highly variable in strength, source location and time



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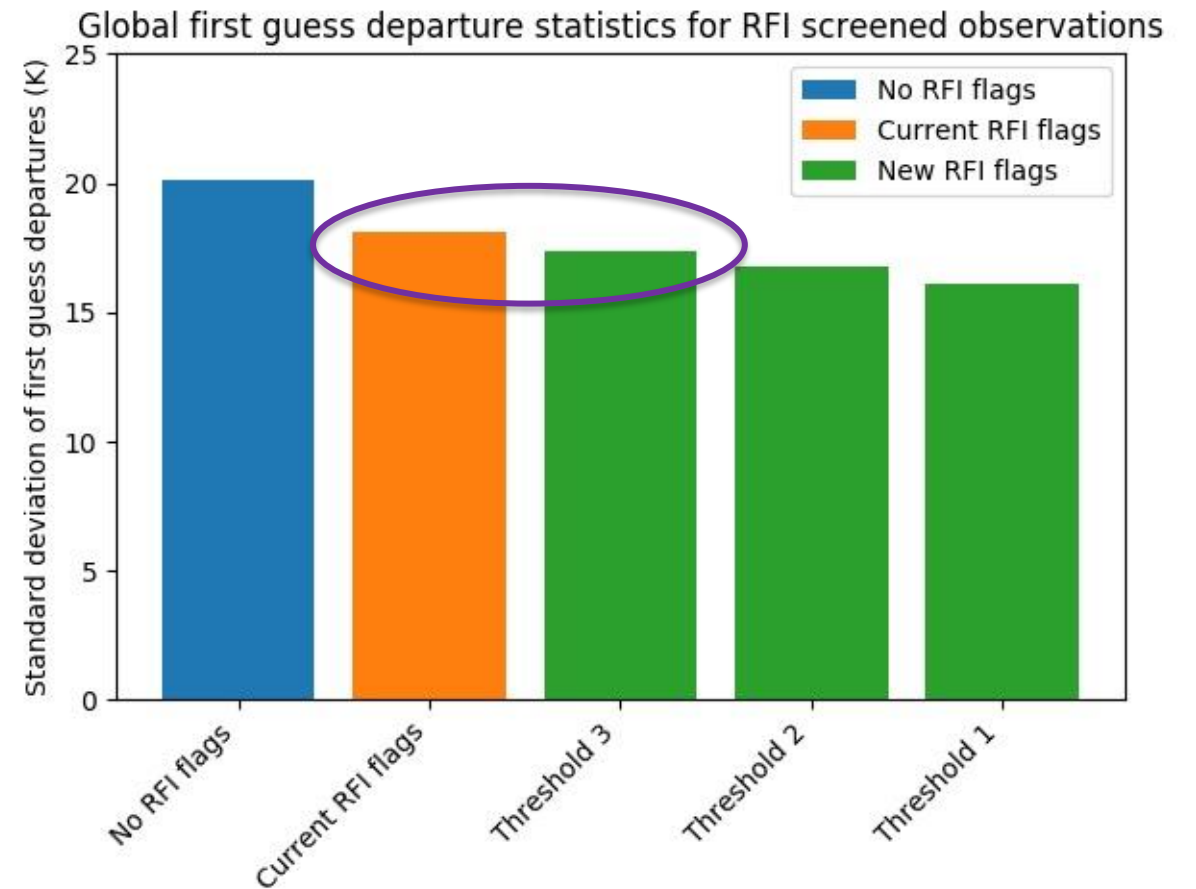
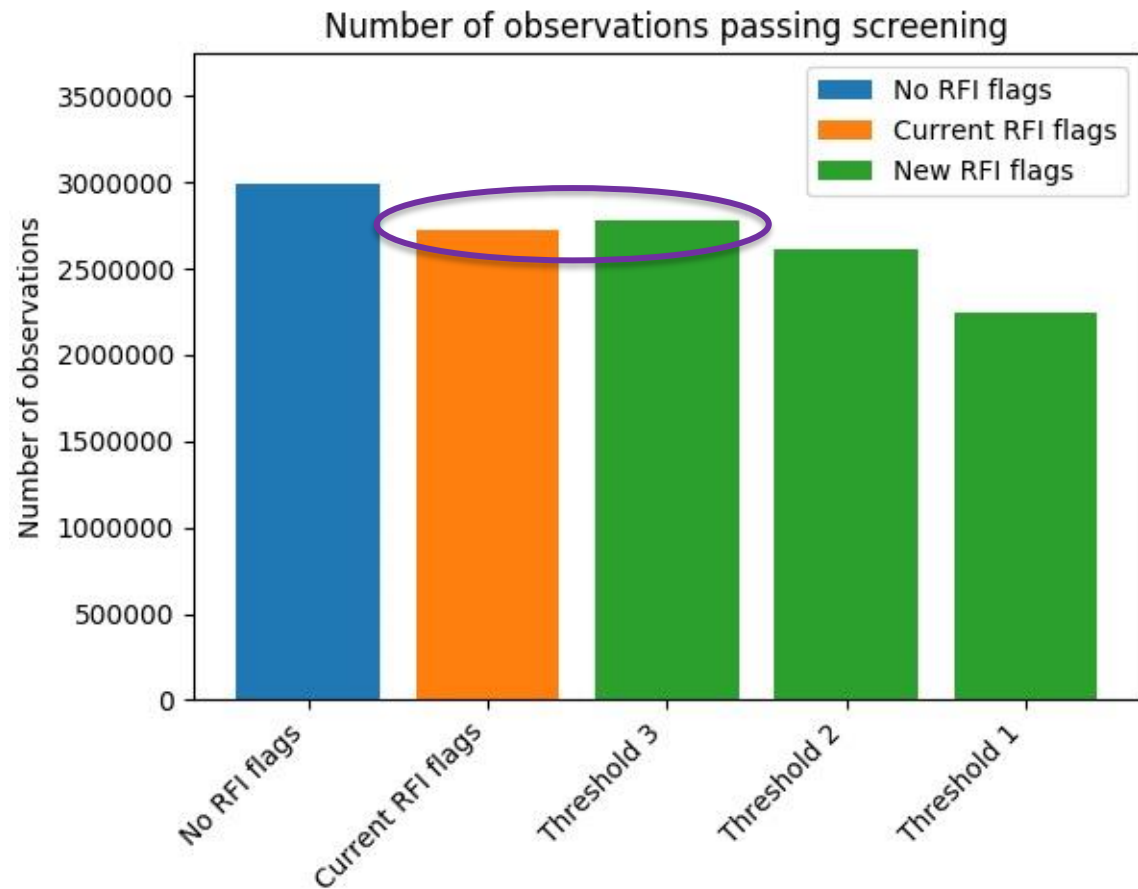
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GRDS results

- GRDS (Ground RFI Detection System) is an independent software package designed to better detect low level RFI from any passive Earth observation data – see previous presentation (Onrubia et al) for details
- The final version of the GRDS was used to generate one month (July 2019) of SMOS data
- New flags were provided and 3 different thresholds used within the algorithms:
 - GRDS threshold 1: Most aggressive screening
 - GRDS threshold 2: Intermediate screening
 - GRDS threshold 3: Least aggressive screening
- The performance of the GRDS was assessed against:
 - Baseline: No RFI screening
 - Control: SMOS v620 (current at the time of the analysis) RFI screening
- Various analyses were carried out including global statistics, gridded maps, histograms of departure distributions

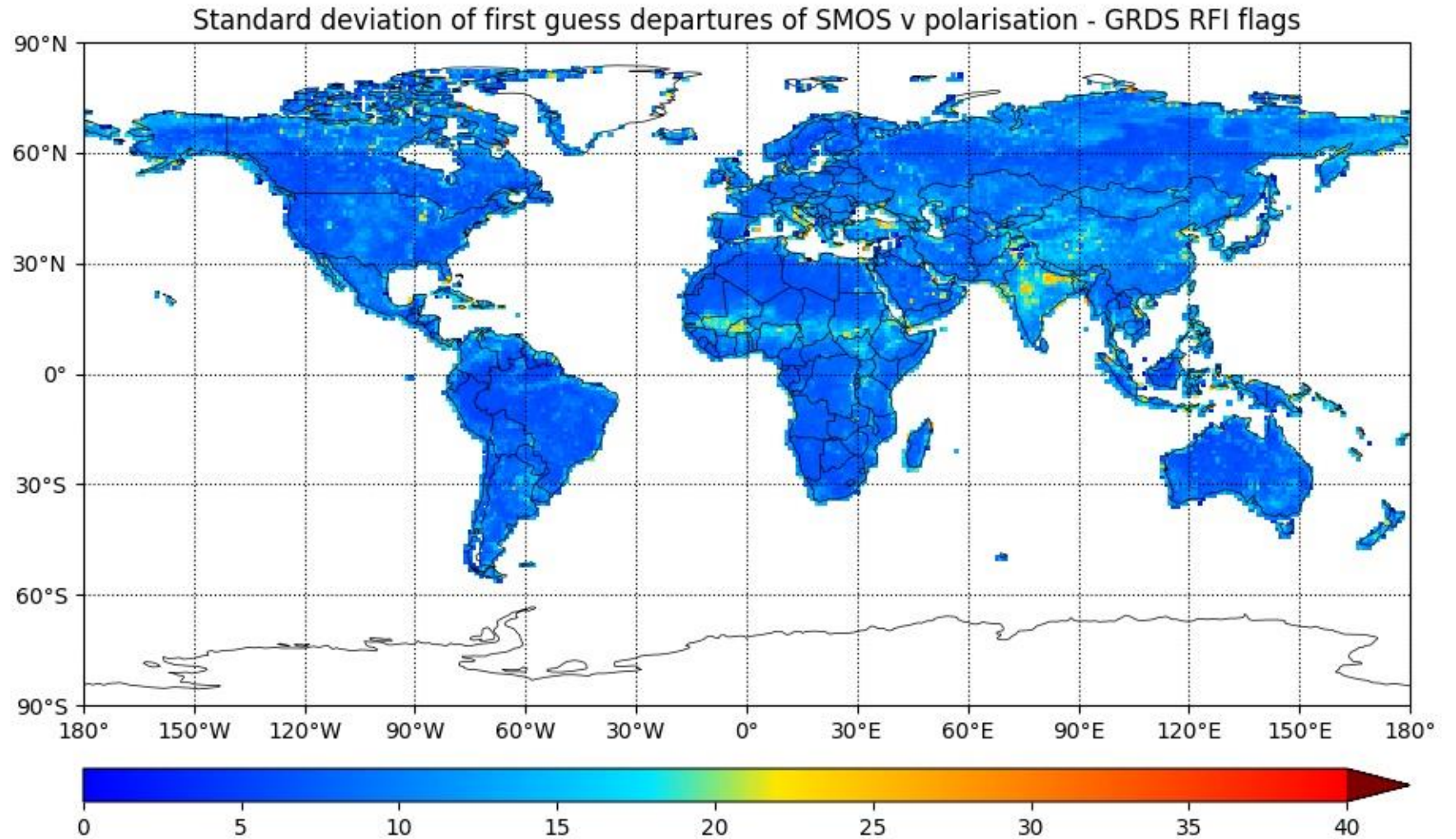
Bar charts

- Threshold 3 screens fewer observations but reduces departures more than current screening
- Thresholds 2 & 1 screen more observations and further reduce departures



Gridded maps – V-pol

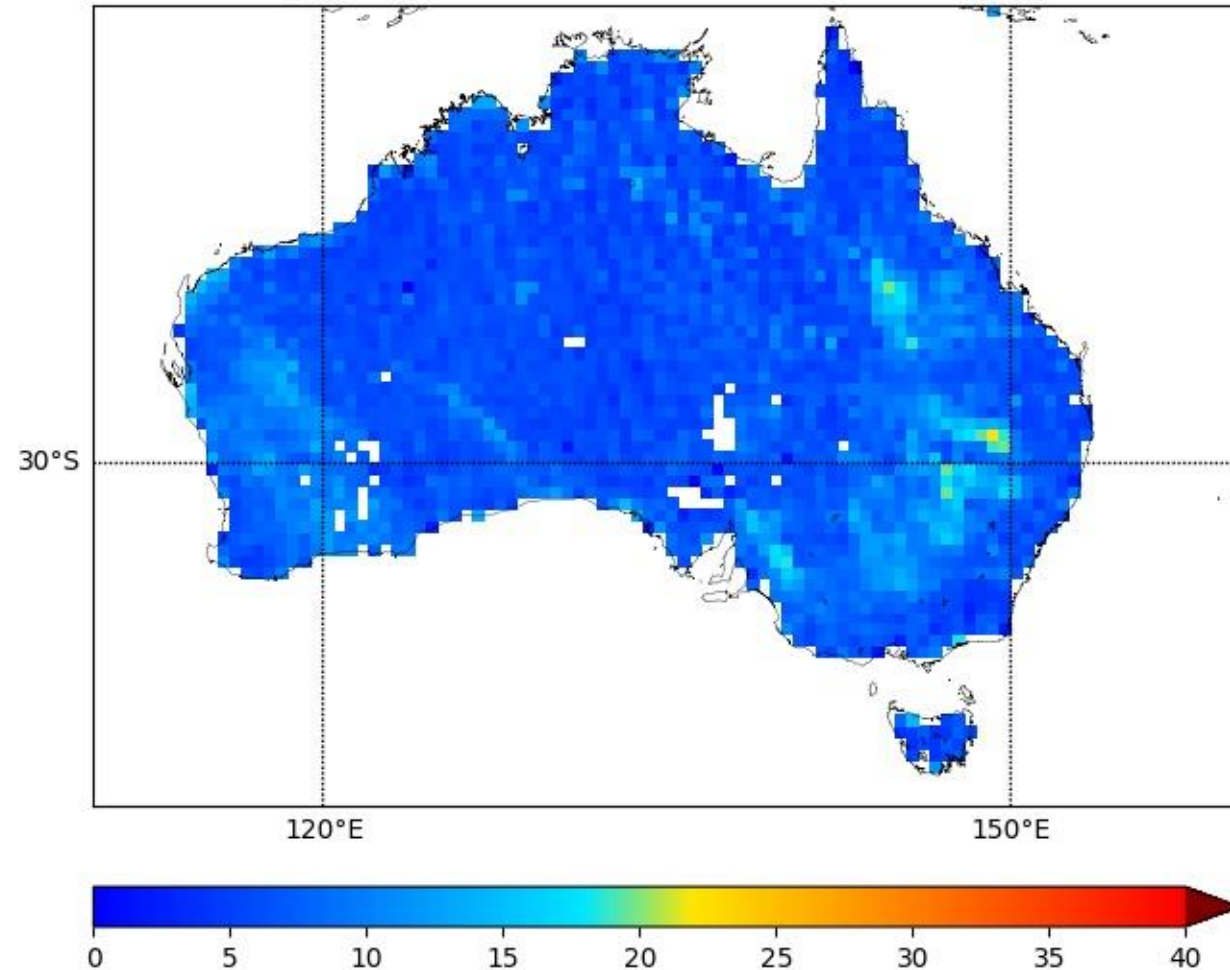
- No screening
- Current screening
- GRDS threshold 3
- GRDS threshold 2
- GRDS threshold 1



Gridded maps – Australia – V-pol (proxy for false alarm rate)

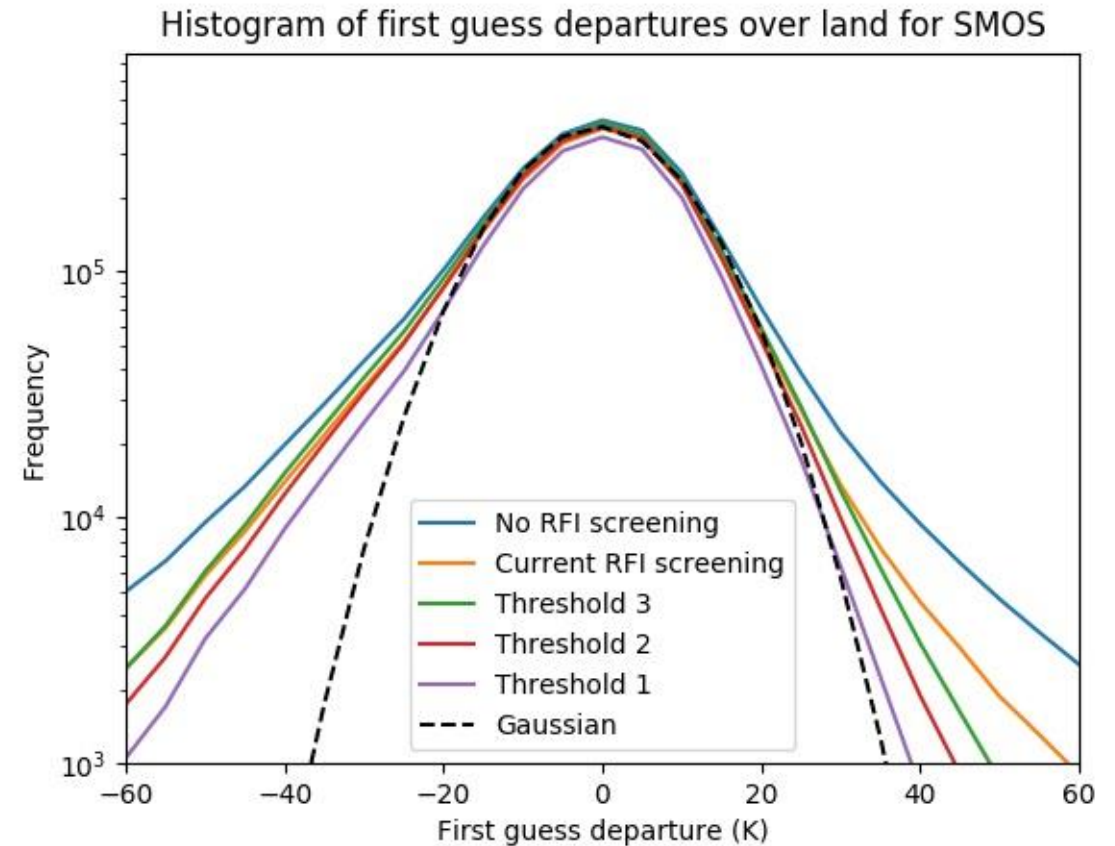
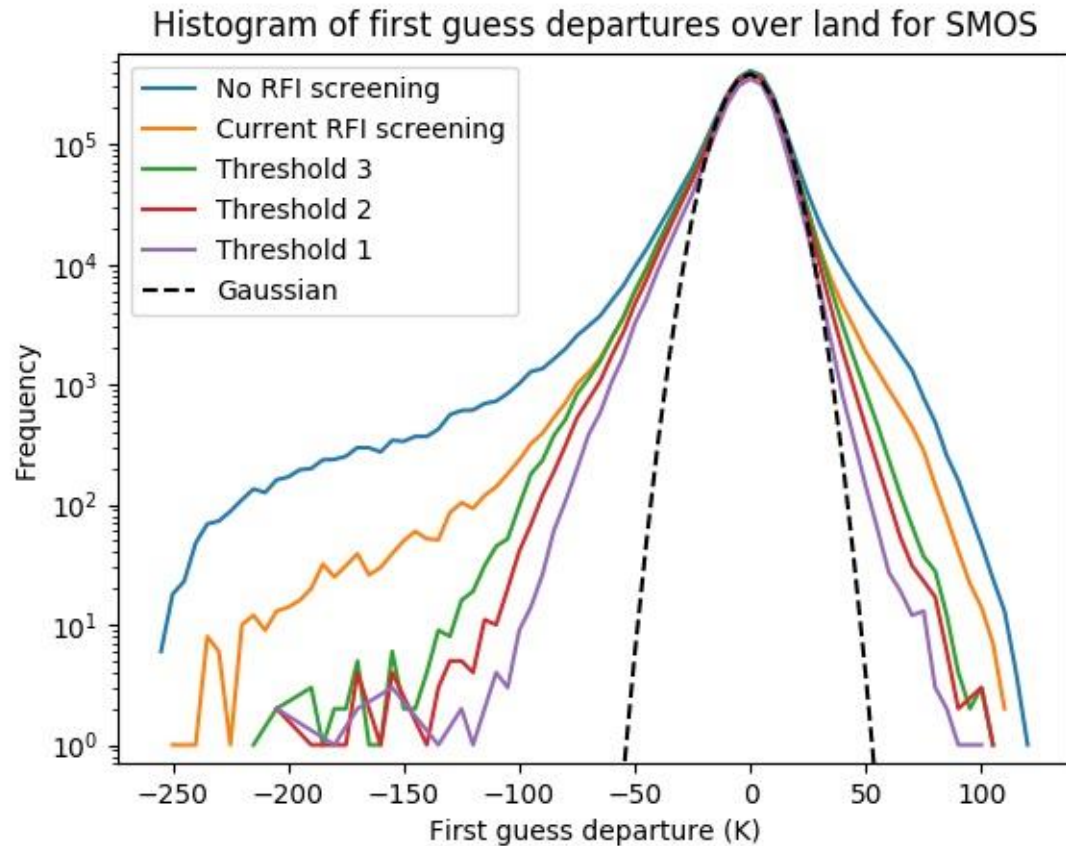
Standard deviation of first guess departures of SMOS v pol - GRDS RFI flags
Stdev(fg_depar) = 10.37 Count = 144619 Flagged (%) = 3.30%

- No screening (0%)
- Current screening (0%)
- GRDS threshold 3 (0.18%)
- GRDS threshold 2 (0.74%)
- GRDS threshold 1 (3.3%)



Histograms

- GRDS significantly reduces the tails and makes departure distribution more Gaussian and symmetric
- Threshold 1 also reduces the peak:
 - Could be a sign of false alarms or could be weakly RFI-affected observations

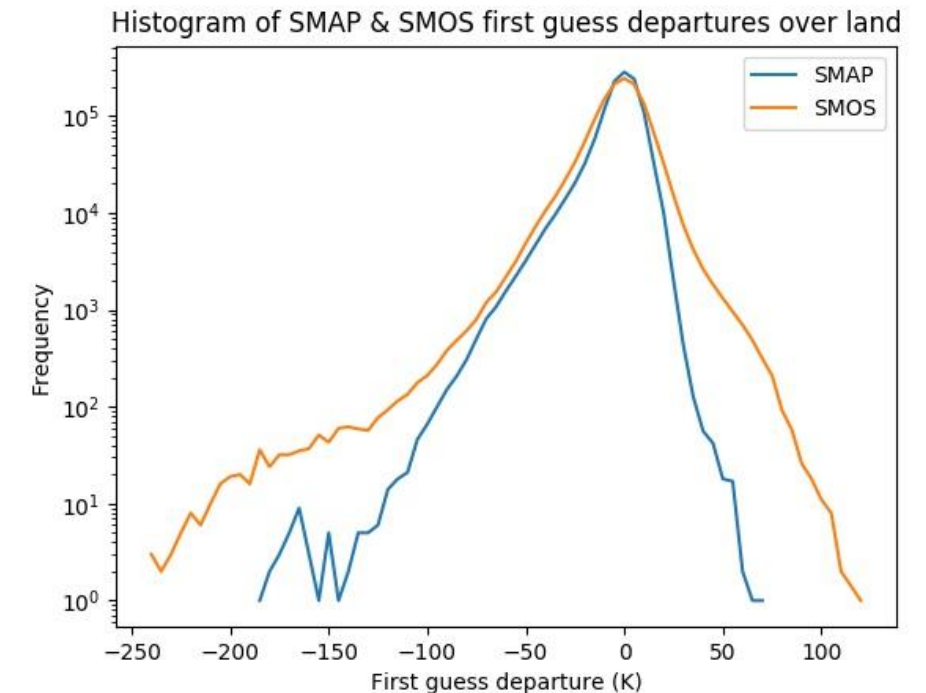
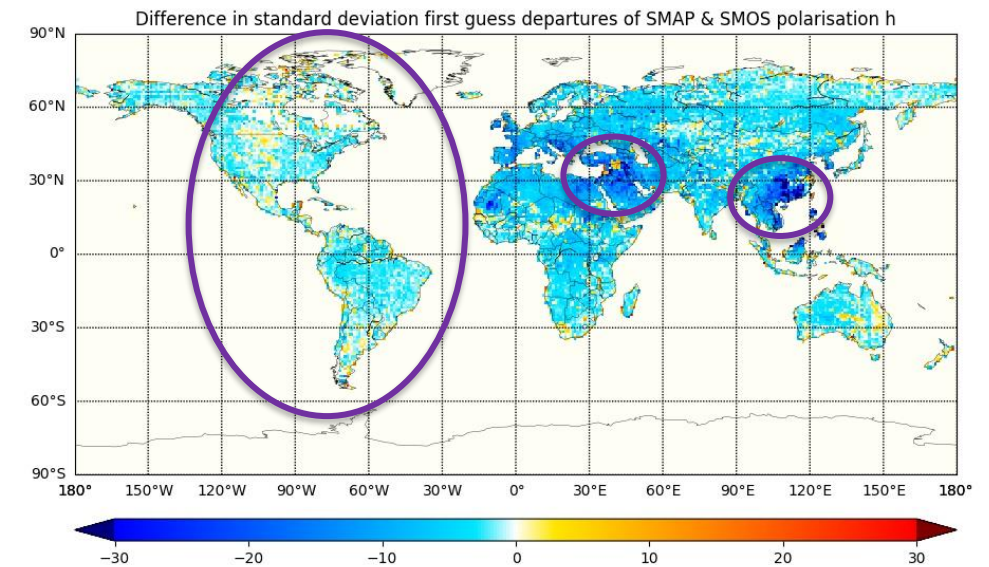


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SMOS v SMAP

- SMOS and SMAP measure at the same frequency but:
 - They have different instrument designs
 - **Several automated algorithms are applied to the SMAP data to screen for RFI**
- SMAP has smaller standard deviations of background departures:
 - Differences are largest in areas of known RFI sources
 - Smaller differences over RFI-free areas
- SMAP background departure distribution also has reduced tails than corresponding SMOS distribution
- Indicates that SMAP 'onboard' RFI screening is effective



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Conclusions and future work

- The GRDS provides significant improvements over the currently operational RFI screening information available for SMOS:
 - Reduction/removal of hot spots and extreme departure values
 - Improvements in global statistics
 - Low false alarm rates
- The 'onboard' screening for SMAP minimises the effects of RFI on the data
- **However, using the GRDS or SMAP screening still means we are losing valuable Earth observation data. The best solution is to remove RFI at source, but this is challenging!**

Future work

- Apply to more instruments (e.g. GMI, AMSU-A, ATMS) and higher frequencies (e.g. 5G at 24GHz)
- Adapt the GRDS for operational use (e.g. as part of the SMOS ground segment?)
- Develop NWP-based RFI monitoring and screening (use pre-5G deployment 'climatology' as baseline to compare against)