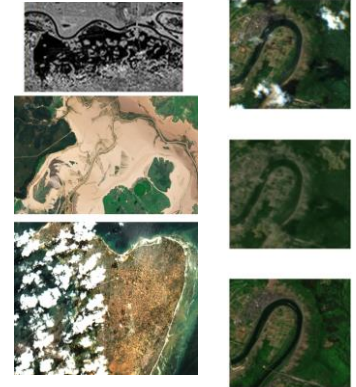


# FloodSENS: Flood Segmentation in Partially Clouded Optical Satellite Images

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## Earth Observation and Floods: Challenges and Proposed Solution

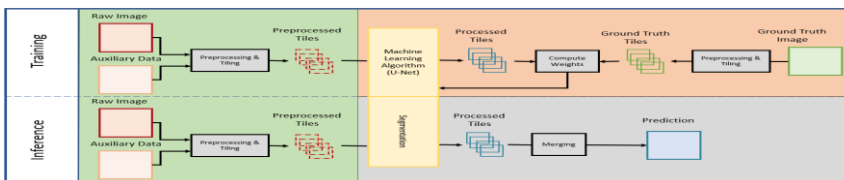
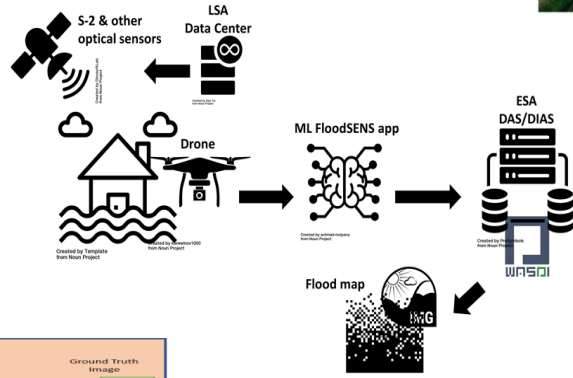
SAR is the preferred sensor: penetrates clouds and is all-weather, day & night capable  
 Optical is straightforward to interpret and many EO missions exist for a long time  
 But: optical is hampered by frequent cloud cover during floods  
 Solution: use ML to reconstruct flooded area under partial cloud cover  
 Benefit to industry: get longer archives of historical flood data for better risk mapping; make optical flood images more useful for disaster response



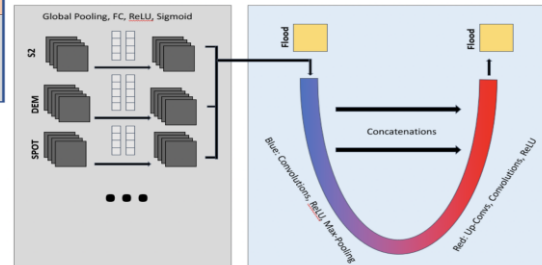
## FloodSENS Smart Sensing of Floods



<https://incubed.phi.esa.int/portfolio/floodsens/>

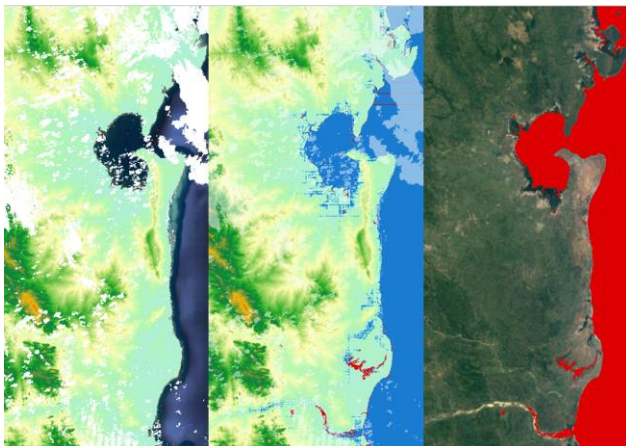


**Overall structure:** (1) **Pre-processing:** Input and reference data is pre-processed and tiles for training or inference. (2) **Training:** The loss is computed on a tile by tile basis. (3) **Inference:** Processed tiles are merged back together to create full sized prediction raster

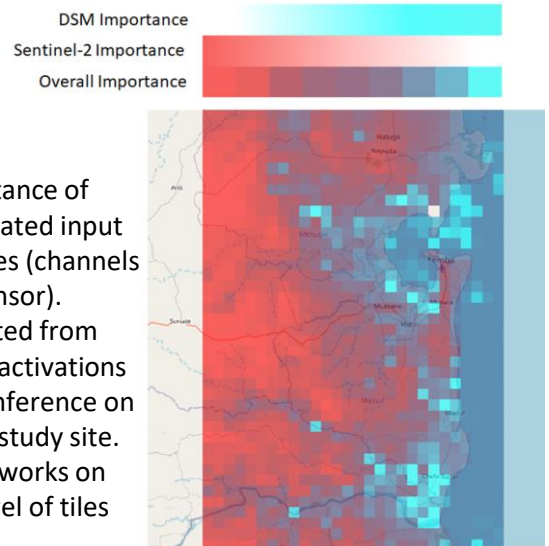


**Proposed algorithm architecture:** The combined Network Image with SENet block in UNet

**Real example (below):** TC Kenneth in Mozambique case using a simple UNET: Input: cloudy S2 & DEM; ground truth (GT): SAR flood map.



Left: Input data, Clouds in white, DEM color  
 Right: GT in red on top of S2  
 Middle: Blue inferred water presence



Importance of aggregated input features (channels per sensor).  
 Extracted from SENet activations after inference on entire study site.  
 SENet works on the level of tiles