Accelerating computational fluid dynamics with deep learning

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Deep learning has had a transformative impact on Google (and the tech industry) over the past decade

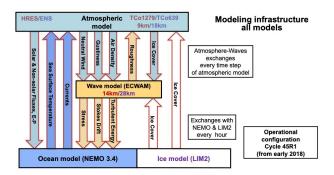
Can it also transform computational science?

"Pure" deep learning offers a drastic alternative to numerical weather prediction

ECMWF Integrated Forecast System

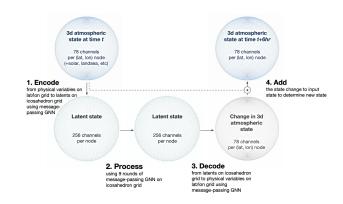
1,000+ person-years of effort

- ~1 million of lines of code
- ~10,000 CPU-hours per forecast
- ~7 days of accurate forecasts Built upon known physical laws



Keisler 2022 Graph Neural Network

<1 person-year of effort 1000s of lines of code 1 GPU-second per forecast ~6 days of accurate forecasts Fit to loads of data (from IFS)





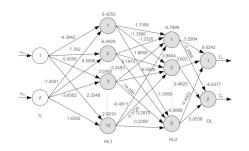
The "differentiable programming" paradigm of deep learning offers a potential middle path

Numerical methods

for interpretability, generalization and extensibility

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{j} = \sigma$$

Neural networks for fast approximation



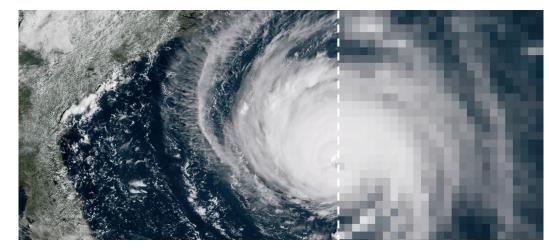
Today's talk: What does "differentiable programming" offer for computational fluid dynamics and weather modeling?

Traditional simulation methods are accurate, but slow

Navier-Stokes equations:

$$\begin{split} \frac{\partial \mathbf{u}}{\partial t} &= -\nabla \cdot (\mathbf{u} \otimes \mathbf{u}) + \frac{1}{Re} \nabla^2 \mathbf{u} - \frac{1}{\rho} \nabla p + \mathbf{f} \\ \nabla \cdot \mathbf{u} &= 0 \end{split}$$

Challenge: Need $\Delta x \rightarrow 0$ for accuracy, but runtime is $O(1/\Delta x^4)$

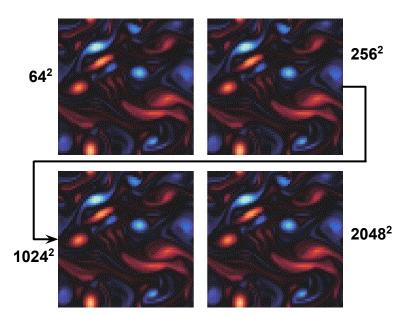


Satellite photo

Weather forecast

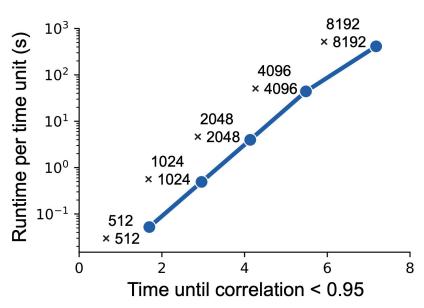
Quantifying effects of resolution

- Higher resolution → more accurate
- Lower resolution → faster simulation



Accuracy-efficiency tradeoff

Direct simulation

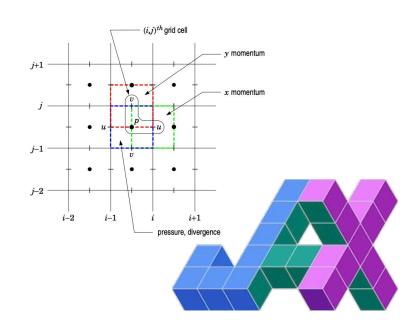


Our work is built upon the "JAX-CFD" library for computational fluid dynamics

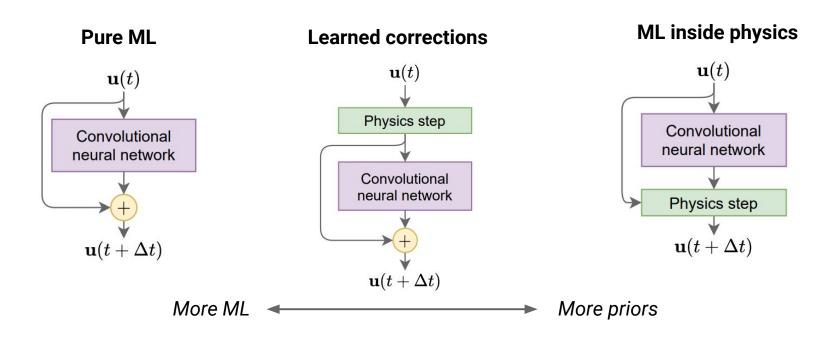
JAX-CFD is:

- Fully **differentiable**
- GPU/TPU native
- Designed for hybrid ML/physics models (e.g., learned interpolation)
- Based on relatively simple numerics (first/second order)

github.com/google/jax-cfd

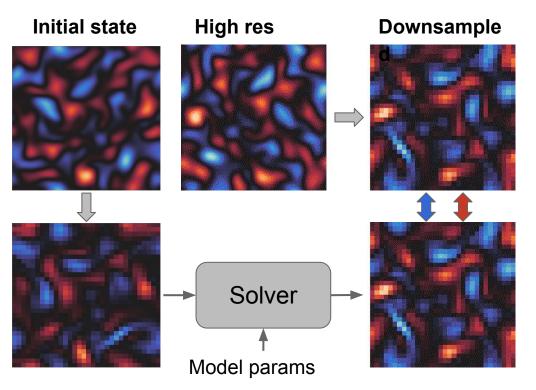


We consider a range of hybrid ML/physics models

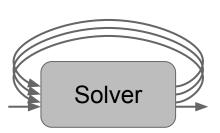


All of these models have two key "inductive biases": (1) locality and (2) translation invariance

Our training setup: learn to simulate on coarse grids

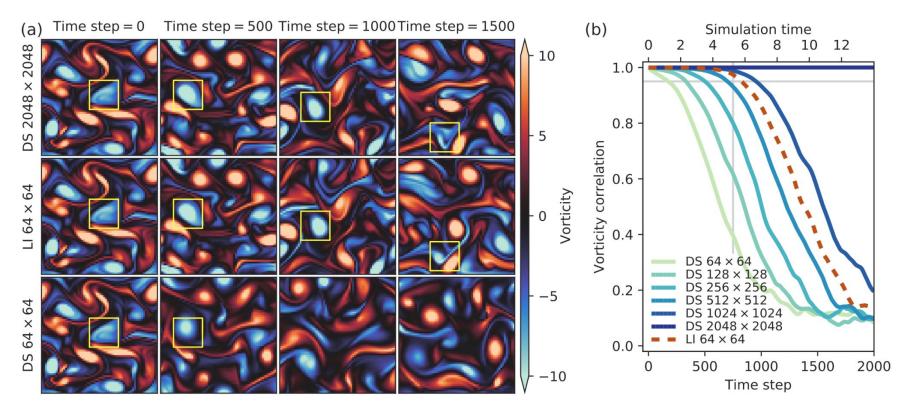


Unrolled in time for end-to-end training:



$$L(x, y) = \sum_{i=1}^{T} MSE \left(\mathbf{u}_{exact}(t_i), \mathbf{u}_{pred}(t_i)\right)$$

Performance on the "test dataset"

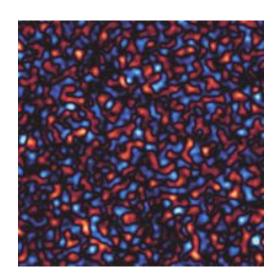


Learned Interpolations model matches CFD at ~12x higher resolution

Evaluation setup

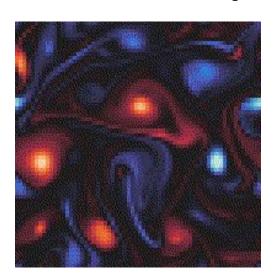
Metrics:

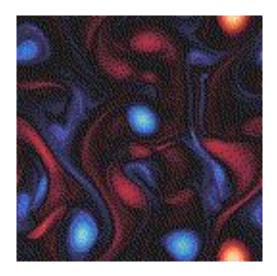
- Pointwise accuracy
- Statistical consistency
- Numerical stability



Generalization datasets:

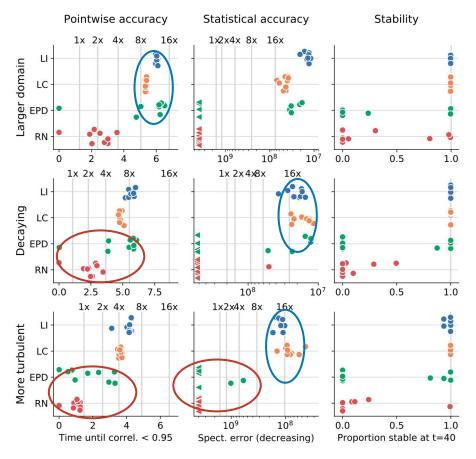
- 1. Larger domain
- 2. Decaying turbulence
- 3. Higher reynolds numbers (Re=4k)





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Comparing models along ML axis on eval datasets



Metrics:

- 1. Pointwise accuracy (T until correlation < 0.95)
- 2. Statistical accuracy (Error in energy spectrum)
- 3. Stability (Proportion of stable)

Each model trained 9 times

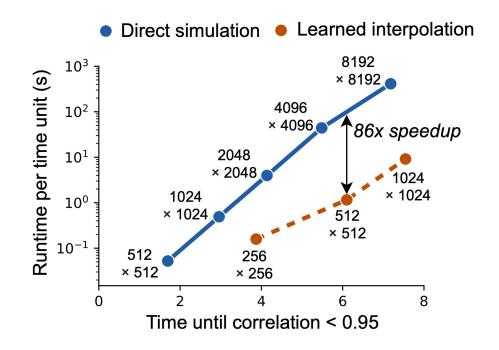
Takeaways:

- Physics-ML hybrids perform best overall
- Pure ML models don't generalize well

2D turbulence: efficiency and the pareto frontier

Benchmarking results:

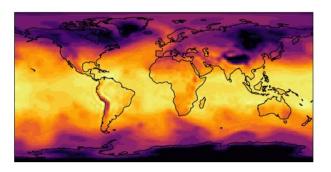
- Our method uses 150x more FLOPS
- 2. But is only 12x slower at same resolution on Google TPUs
- 3. Overall: ~80x faster for the same accuracy (10³ / 12)



Our current focus: a differentiable, accelerator-native GCM

Can **deep learning** inside an atmospheric GCM improve global weather forecasts?

What is the **optimal combination** of numerical methods and machine learning?



"Dynamics"
Accelerate
this stuff

Primitive equations $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{V}) = 0$

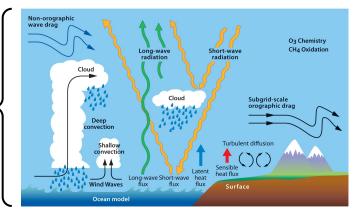
 $\frac{\partial \mathbf{V}}{\partial t} = -2\mathbf{\Omega} \times \mathbf{V} - \mathbf{\Omega} \times (\mathbf{\Omega} \times \mathbf{r}) - \nabla \phi_a - \alpha \nabla p - \alpha \nabla \cdot \mathbf{F}$ $\frac{D}{Dt}(c_v T) + p \frac{D\alpha}{Dt} = -\alpha \nabla \cdot (\mathbf{R} + \mathbf{F}_s) + LC + \delta$

 $\frac{Dq_{v}}{Dt} = g \frac{\partial F_{q_{v}}}{\partial p} - G$

Discretization



"Physics"
Learn this stuff



Thanks for your attention!

Summary: numerical methods + auto diff + accelerators + deep learning = an amazing toolkit for scientific computing!

To learn more:

- Paper: Kochkov et al, <u>Machine learning</u> <u>accelerated computational fluid</u> <u>dynamics</u> (PNAS, 2021)
- Code: github.com/google/jax-cfd



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