Representation learning of cloud systems using energy-based deep learning neural networks Chatterjee D.¹, P. Bigalke¹, S. Schnitt¹, C. Acquistapace¹, H.Deneke², S. Crewell¹ ¹Institute for Geophysics and Meteorology, University of Cologne ²Leibniz Institute for Tropospheric Research, Leipzig HDSLEE in Life · Earth · Energy e-mail: <u>dchatter@uni-koeln.de</u> University of Cologne

Goals of the project

What is the research gap that we try to fill?

• Cloud representation in NWP and climate models is critical

• Unmet need to fully exploit high resolution observations

- Develop new usages of geostationary sat data
- Exploit DL techniques to get new insight in mesoscale cloud organization:
- Case study 1 over land: learn to identify cloud systems with different radiative properties through representation learning
- case study 2 over ocean: investigate the pseudo continuous (PC) order of cloud systems and exploit pseudo continuous feature space to approach discrete space
- Analyze the identified patterns with respect to:

Iarge scale environmental conditions, physical processes, temporal variability, for renewable energy applications

I. First study: Over land

64x64

128x128

II. Second study: Over ocean

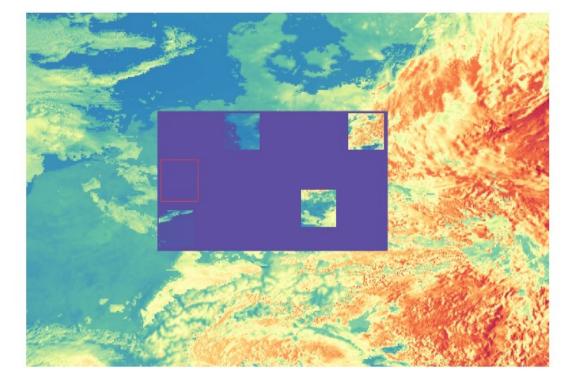
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local time

I.I Satellite data

I.II Methodology

= central European domain

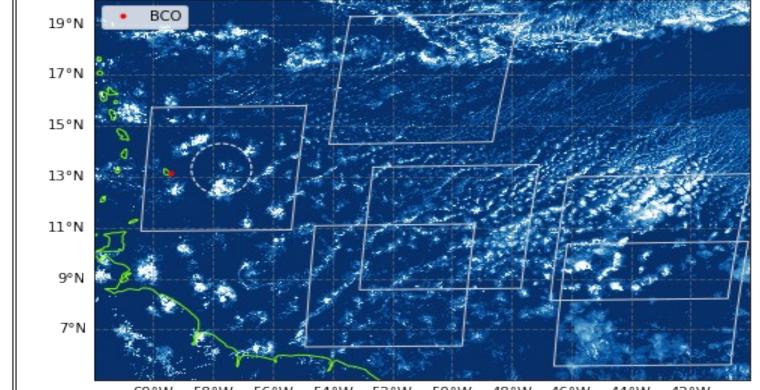


4 <u>random</u> crops at any instant

- Enhanced resolution MSG data set ⁵
- Cloud optical depth (COD) and 10 additional retrieval products
- Period: April to July 2013, 2015
- Every 5 min between 6 and 18 utc
- $2.06 \text{ km} \times 1.07 \text{ km}$ spatial resolution

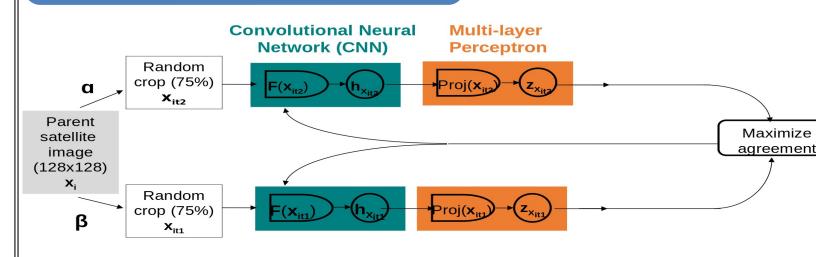
Cloud Optical Depth (COD)

Centroid joint histogram of COD vs CTP



56°W 54°W 52°W 50°W 48°W 46°W 44°W 5 <u>random</u> crops at any instant

II.II Methodology



Neural network^{3,2} uses cloud optical depth as input feature and puts similar cloud structure and distribution closer to each other in the feature space than dissimilar ones.

Cloud optical depth (COD) product⁶

every 10-15 min between 9 and 15

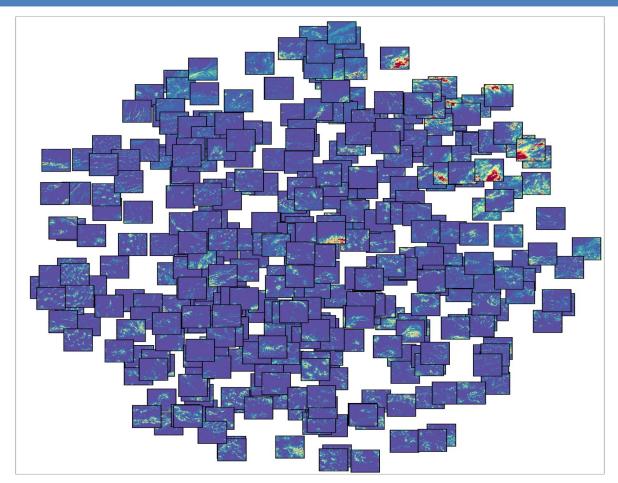
Period: Nov - Apr 2017 – 2021

Domain: 5-20°N, 40-60°W

COD capped above 50

2 km horizontal resolution

II.III Analysis of the feature space and main results





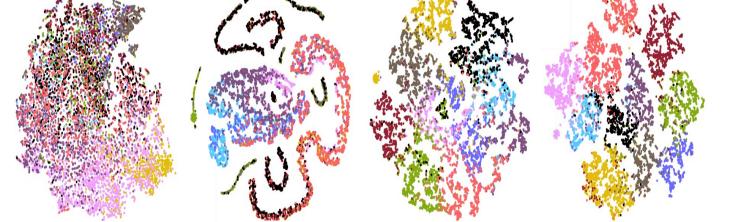
Random crop (75%) Parent satellite Cross Entropy image (128x128) Cosine Random

Cloud optical depth features act as signal to train self-supervised learning (SSL) approach^{1,2} that classifies the satellite images into 'K' classes.

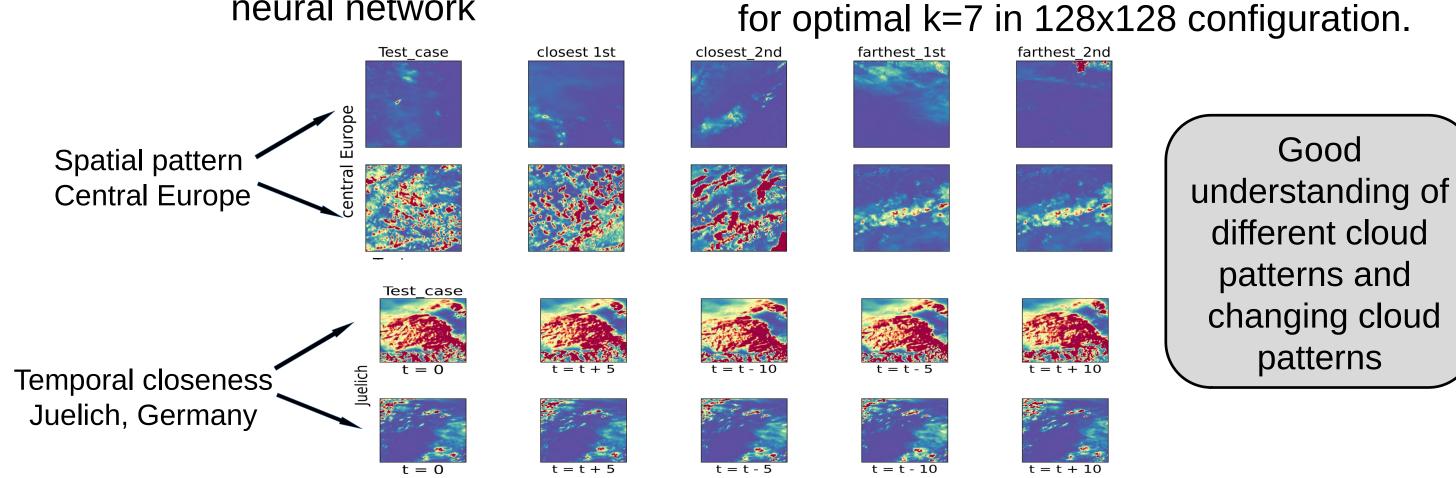
I.III Analysis of the feature space and main results



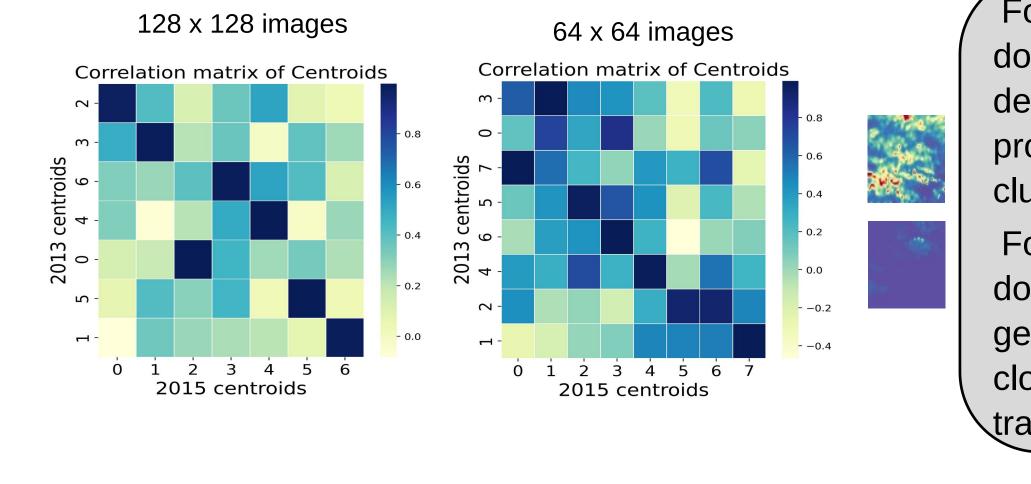
II.I Satellite data



Progressive visualization of the feature space for 10 classes at a) 1 epoch, b) 25 epoch, c) 250 epoch, d) 700 epoch by the neural network

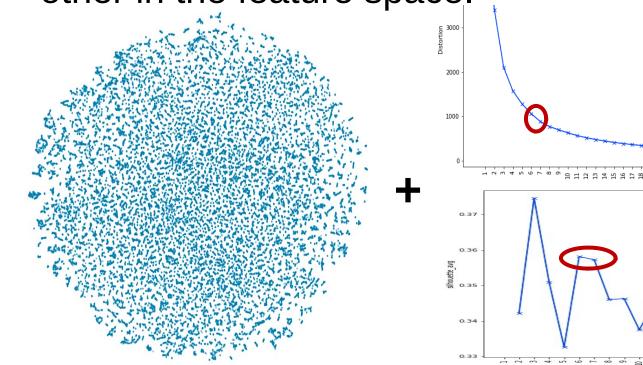


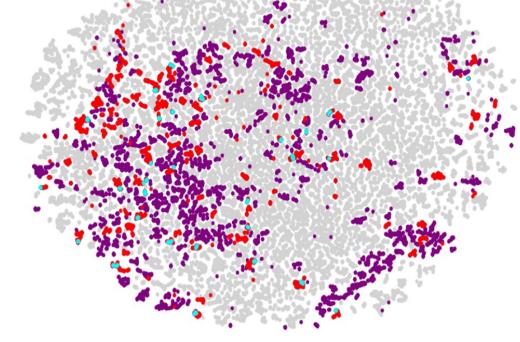
Row one and two, top two nearest and two farthest images when compared with the test image features in 128 x 128 configuration. Row 3 and 4 transfer learning the trained network over Juelich domain area for understanding the evolution of cloud systems



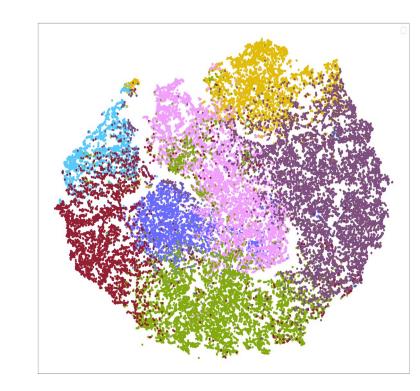
For larger (128x128) domain, algorithm determined from 2013 produces the same distinct clusters for 2015 For the smaller sized domain (64 x64) difficult to generalize for **two** unique cloud systems \rightarrow larger training data set needed

In the soft space, 300 random samples are shown. Similar cloud systems lie closer to each other in the feature space.

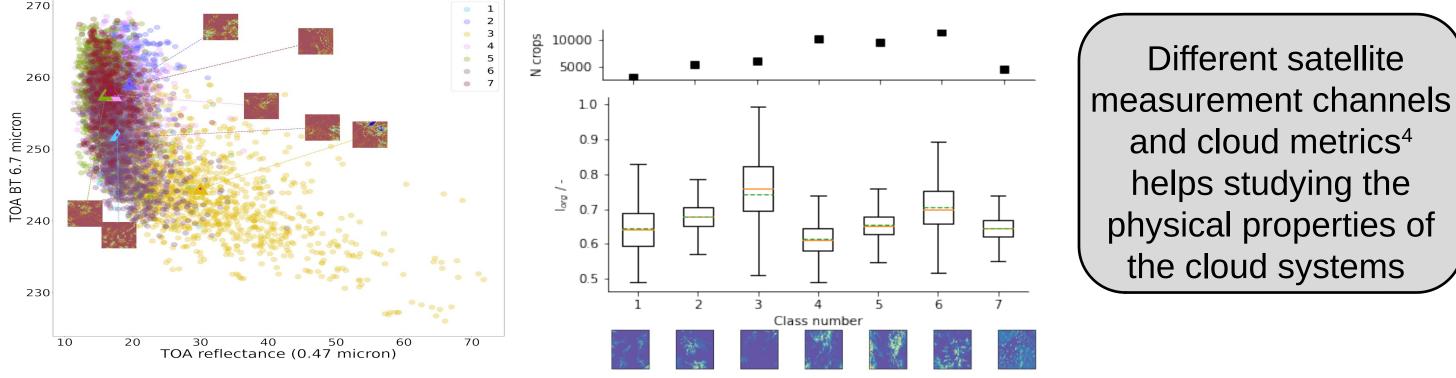




EUREC4A campaign core period similarly distributed as past years



Features of the samples trained using the pseudo continuous approach are used as an input in statistical approaches such as Elbow method and Silhouette method to get an idea what would be the optimal number of clusters for the given feature space



Relations between various satellite retrieved products supports the physical interpretation of the identified cloud classes. Colors reveal separation of the different classes. Triangles mark centroids for which corresponding images are shown.

Take Home message:

I. The neural network is able to separate cloud structures and distributions and analysis with both cases provides a physical interpretation of the identified cloud systems.

II. Test of the algorithm from a different year show same clusters, confirming the reliability of the methodology III. The generalization capacity of the deep neural network with unseen data is promising but depends on the spatial scale of cloud systems.

References:

[1] Caron, M., et al. (2020) <u>doi: 10.48550/arXiv.2006.09882</u> [2] Goyal, et al. (2021) doi: <u>10.48550/arXiv.2103.01988</u> [3] Chen et al. (2020) <u>https://doi.org/10.48550/arXiv.2002.05709</u> [4] Janssens, M., et al. (2021). doi: <u>10.1029/2020GL091001</u> [5] Deneke, H., et al. (2021) doi: <u>10.5194/amt-14-5107-2021</u> [6] Walther & Heidinger (2012) doi: 10.1175/JAMC-D-11-0108.1