Non-oscillatory forward-in-time finite-volume methods for NWP

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The atmospheric dynamical core plays a central role

for up-to-date information: https://confluence.ecmwf.int/display/FCST/ (CY49r1 to be implemented 12 Nov 2024!)

Ocean – Land – Atmosphere – Sea ice

Spectral-transform formulation of the operational IFS (IFS-ST)

- hydrostatic primitive equations in hybrid mass-based vertical coordinate
- spherical-harmonics representation in horizontal
- finite-element approach for integrals in vertical
- two-time-level semi-implicit semi-Lagrangian integration scheme
- cubic-octahedral grid ("TCo")
- coupling to IFS physics using SLAVEPP (Semi-Lagrangian Averaging of Physical Parametrisations)

IFS dynamical core performance comparison: time-to-solution at 3km for dry baroclinic instability test case with 10 tracer fields

IFS dynamical core performance comparison: time-to-solution at 3km for dry baroclinic instability test case with 10 tracer fields

CCECMWF EUROPEAN CENTRE FOR MEDIUM-RANGE WEATHER FORECASTS(adapted from Michalakes et al, NGGPS AVEC report,⁶ 2015)

(Smolarkiewicz, Kanada), Kronika, Kanada, Kronika, Wedi 2014), Wedi 2014, Wedi 2014, Wedi 2014, Wedi 2014, Wedi

semi-implicit integration schemes (Smolarkiewicz and Szmelter 2011 for a more recent review)

FVM summary (from year 2019)

Current features:

- nonhydrostatic, deep-atmosphere, fully compressible equations
- horizontally-unstructured vertically-structured finite-volume discretisation
- semi-implicit integration with 3D implicit dynamics right-hand-sides (diffusion is) HEVI by default)
- (explicit) nonoscillatory forward-in-time conservative Eulerian advection
- flexibility with respect to horizontal and vertical meshes
- Atlas library mesh and parallel datastructures
- Fortran code and using hybrid MPI/OpenMP for CPUs, but Python/GT4Py DSL implementation under development
- 64-bit or 32-bit precision
- IFS-FVM coupled to IFS physical parametrisation package (CY43R3)
- ecRad radiation scheme on model grid

$$
\int_{\Omega} \nabla \cdot \mathbf{A} = \int_{\partial \Omega} \mathbf{A} \cdot \mathbf{n} = \frac{1}{\mathcal{V}_i} \sum_{j=1}^{l(i)} A_j^{\perp} S_j
$$

dual volume: *Vi,* face area: *Sj*

median-dual finite-volume approach

8 *Nodes of octahedral grid O24*

Octahedral reduced Gaussian grid of the IFS

- Quasi-uniform resolution over the surface of the sphere
- Suitable for spherical harmonics transforms and hence the spectral-transform IFS model
- Unstructured finite-volume IFS-FVM can develop mesh about nodes of the grid
- Using the same grid benefits overall infrastructure and model comparison studies
- \rightarrow see Malardel et al. 2015; Smolarkiewicz et al. 2016; Deconinck et al. 2017; Kühnlein et al. 2019

Summary of FVM spatial discretization

- horizontally-unstructured finite-volume (FV) and vertically-structured finitedifference/finite-volume (FD/FV) discretisation framework
- median-dual FV approach is current default but other options are explored

terrain-following coordinate

$$
\int_{\Omega} \nabla \cdot \mathbf{A} = \int_{\partial \Omega} \mathbf{A} \cdot \mathbf{n} = \frac{1}{\mathcal{V}_i} \sum_{j=1}^{l(i)} A_j^{\perp} S_j
$$

dual volume: V_i , face area: S_j

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- Gauss divergence theorem is central to FV technique
- Various approximations for FV fluxes between neighbouring cells depending on process and form of operator
- Fluxes in Laplacian operator (gradient & divergence) are usually linear & centred reconstructions of data at neighbouring points, compact specifications are used for diffusion, upwind and nonlinear fluxes occur in context of non-oscillatory advection

Smolarkiewicz et al. JCP 2016 Kühnlein et al. GMD 2019

FVM fully compressible equations with full IFS physics m $\mathbf{G} = \mathbf{G} \mathbf{G} \mathbf{G} + \mathbf{G} \mathbf{G} \mathbf{G} + \mathbf{G} \mathbf{G} \mathbf{G} + \mathbf{G} \mathbf{G} \mathbf{G} \mathbf{G} + \mathbf{G}$ *d***u** *dt* ⁼ ✓⇢**G**e+' ⁺ **^g ^f** ⇥ **^u** ⁺ *^M*(**u**) ⁺ **^P^u** , (1b) VM fully compressible equations with full IFS physics The property completes and equations with full it of privates

2.1 | **Flux-form fully compressible equations solved in the discrete model**

$$
\frac{\partial \mathcal{G}\rho_d}{\partial t} + \nabla \cdot (\mathbf{v} \mathcal{G}\rho_d) = 0,
$$
\n
$$
\frac{\partial \mathcal{G}\rho_d \mathbf{u}}{\partial t} + \nabla \cdot (\mathbf{v} \mathcal{G}\rho_d \mathbf{u}) = \mathcal{G}\rho_d \left[-\theta_\rho \widetilde{\mathbf{G}} \nabla \varphi' - \theta_\rho \widetilde{\mathbf{G}} \nabla \varphi_a + \mathbf{g} - \mathbf{f} \times \mathbf{u} + \mathcal{M}(\mathbf{u}) + P^{\mathbf{u}} \right]
$$
\n
$$
\frac{\partial \mathcal{G}\rho_d \theta'}{\partial t} + \nabla \cdot (\mathbf{v} \mathcal{G}\rho_d \theta') = \mathcal{G}\rho_d \left[-\mathbf{G}^T \mathbf{u} \cdot \nabla \theta_a + P^\theta \right],
$$
\n
$$
\frac{\partial \mathcal{G}\rho_d \, r_k}{\partial t} + \nabla \cdot (\mathbf{v} \mathcal{G}\rho_d \, r_k) = \mathcal{G}\rho_d P^{r_k}, \qquad r_k = r_v, r_l, r_r, r_i, r_s, \Lambda_a
$$

$$
\varphi = c_{\rho d} \left[\left(\frac{R_d}{\rho_0} \rho_d \theta (1 + r_v / \varepsilon) \right)^{R_d / c_v d} \right] = c_{\rho d} \pi \qquad \qquad \theta_{\rho} = \frac{1 + r_v / \varepsilon}{1 + r_t} \theta
$$

$$
r_t = r_v + r_l + r_r + r_s + r_i
$$

$$
\varphi' = \varphi - \varphi_a, \qquad \qquad \theta' = \theta - \theta_a \qquad \qquad \mathbf{v} = \mathbf{G}^T \mathbf{u}
$$

$$
\varepsilon = \frac{R_d}{R_v}
$$

tum equation

sure.

Universal characteristics of atmospheric flows to *u*ref in practice (see also Sections 2.3 and 4.3 below). Universal characteristics of atmospheric hows

Table 1 Universal characteristics of atmospheric motions Universal characteristics of atmospheric motions (R. Klein *Annu. Rev. Fluid Mech. 2010)*

Auxiliary quantities of interest dervied from the Table above

250 Klein

Courtesy EUMETSAT

hierarchy of characteristic lengths displayed in **Table 3**. The technical terms in the left column are

FVM semi-implicit integration

$$
\frac{\partial G\Psi}{\partial t} + \nabla \cdot (\mathbf{V}\Psi) = G\left(\mathcal{R}^{\Psi} + P^{\Psi}\right) ,
$$

$$
\Psi_i^{n+1} = \mathcal{A}_i(\widetilde{\Psi}, V^{n+1/2}, G^n, G^{n+1}, \delta t) + b^{\Psi} \delta t \mathcal{R}^{\Psi} \Big|_i^{n+1}
$$

$$
\equiv \widehat{\Psi}_i + b^{\Psi} \delta t \mathcal{R}^{\Psi} \Big|_i^{n+1},
$$

$$
\widetilde{\Psi} = \Psi^n + a^{\Psi} \, \delta t \, \mathcal{R}^{\Psi} \vert^n + \delta t \, P^{\Psi} \vert^n \ ,
$$

Main principles of default scheme:

- \triangleright Time integration aims for a high degree of implicitness with respect to rhs forcings
- Ø Focus on co-located arrangement of prognostic variables, but selected compact operators used
- Ø Numerically consistent second-order design about non-oscillatory forward-in-time flux-form advection (core design uses MPDATA, alternative transport schemes for selected variables and tracers incorporated)
- \triangleright Compact-stencil diffusion with implicit time stepping

FVM coupling to IFS physical parametrisations

- Parametrizations for turbulence, convection, cloud microphysics, orographic and non-orographic gravity wave drag
- Land surface model HTESSEL
- ecRad radiation scheme on model grid (called every 1h)
- As the current default, tendencies from IFS physical parametrizations are incorporated in FVM SI scheme using Euler forward approach with subcycling of dynamics:

Physics time step from
$$
t^N
$$
 to $t^N + \Delta t_{phys} \equiv t^N + N_s \, \delta t$ for $\ell = 1, N_s$:

$$
\Psi_{\mathbf{i}}(t^N + \ell \delta t) = \mathscr{A}_{\mathbf{i}}(\widetilde{\Psi}, \mathbf{V}(t^N + (\ell \delta t - 0.5)), G(t^N + (\ell - 1)\delta t), G(t^N + \ell \delta t), \delta t) + b^{\Psi} \delta t \mathscr{R}_{\mathbf{i}}^{\Psi}(t^N + \ell \delta t)
$$

 $\widetilde{\Psi} = \Psi(t^N + (\ell - 1)\delta t) + a^{\Psi} \delta t \mathcal{R}^{\Psi}(t^N + (\ell - 1)\delta t) + \delta t P^{\Psi}(t^N, \Delta t_{phys})$ **CCECMWF 14**

Bauer et al. Nature 2015

Fundamentals of the FVM integration scheme

 \rightarrow See Piotr Smolarkiewicz's lecture for further discussion

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MPDATA scheme

- MPDATA: Multidimensional Positive Definite Advection Transport Algorithm
- Upwind scheme followed by error-compensating steps formulated as pseudo-flux achieves at least secondorder accurate solution
- Limiting the pseudo-flux using Flux-Corrected Transport approach achieves monotone solution
- wany variants or the scheme exist (sign-preserving,
split vs unsplit, third-order extension, structured grids, *A* • Many variants of the scheme exist (sign-preserving, unstructured meshes, curvilinear coordinates, moving meshes)
- \triangleright Smolarkiewicz (1983); Smolarkiewicz and Clark (1986); Smolarkiewicz and Grabowski (1990); Smolarkiewicz and Margolin (1998); Smolarkiewicz and Szmelter (2005); Kühnlein et al. 2012; Kühnlein and Smolarkiewicz (2017); Waruszewski et al. 2018

$$
\Psi_{i}^{n+1} = \mathcal{A}_{i}(\Psi^{n}, \mathbf{V}^{n+1/2}, G^{n}, G^{n+1})
$$

= $\chi_{i}^{n+1/2} \mathcal{A}_{i}(\Psi^{n}, \mathbf{V}^{n+1/2}, G^{n}, G^{n+1})$
= $\chi_{i}^{n+1/2} \Psi_{i}^{N_{n}}$
where $\chi^{n+1/2} \equiv \frac{G^{n}}{G^{n+1}}$

$$
\widetilde{\mathcal{A}}_i
$$
 iterates for $\eta = 1, N_\eta$:

$$
\Psi_{k,i}^{(\eta)} = \Psi_{k,i}^{(\eta-1)} - \frac{\delta t}{G_{k,i}^n \ V_i} \sum_{j=1}^{I(i)} F_{k,j}^{\perp} \left(\Psi_{k,i}^{(\eta-1)}, \Psi_{k,j}^{(\eta-1)}, V_{k,j}^{\perp} \right) S_j
$$

cz
ein
118

Split Eulerian flux-form advection into purely horizontal *^Axy ⁱ* and vertical *^A^z ⁱ* schemes, respec-Split Eulerian flux-form advection sequence *^A^z i*_t Eulerian flux-form advection

vertical sweeps and the full time step in the horizontal part. Mass-compatible norizontal-vertical Strang-split
flux faxe advaction in EVAA: $\frac{1}{2}$ to $\frac{1}{2}$ as vection in Fig. (1) as $\frac{1}{2}$ Mass-compatible horizontal-vertical Strang-split flux-form advection in FVM:

$$
\rho_{di}^{[1]} = \mathcal{A}_{i}^{z}(\rho_{d}^{n}, (v^{z}\mathcal{G})^{n+1/2}, \mathcal{G}^{n}, \mathcal{G}^{[1]}, 0.5\delta t),
$$

\n
$$
\rho_{di}^{[2]} = \mathcal{A}_{i}^{xy}(\rho_{d}^{[1]}, (v_{h}\mathcal{G})^{n+1/2}, \mathcal{G}^{[1]}, \mathcal{G}^{[2]}, \delta t),
$$

\n
$$
\rho_{di}^{n+1} = \rho_{di}^{[3]} = \mathcal{A}_{i}^{z}(\rho_{d}^{[2]}, (v^{z}\mathcal{G})^{n+1/2}, \mathcal{G}^{[2]}, \mathcal{G}^{n+1}, 0.5\delta t)
$$

 $W^{[1]}$ $\sim 4\sqrt[2]{u}$ $\left(\sqrt[2]{c} \right)^{7}$ $\left(\sqrt{c} \right)^{n}$ $\left(\sqrt{c} \right)^{11}$ $\left(\sqrt{c} \right)^{5}$ ^d , ⇢*n*+¹ $\Psi_{i}^{[1]} = \mathcal{A}_{i}^{z}(\widetilde{\Psi}, (v^{z}\mathcal{G}\rho_{d})^{[1]}, (\mathcal{G}\rho_{d})^{n}, (\mathcal{G}\rho_{d})^{[1]}, 0.5\delta t)$, $\Psi_{\bm{i}}^{[2]} = \mathcal{A}_{\bm{i}}^{xy} (\Psi^{[1]}, (v_{\rm h}^{\perp} \mathcal{G} \rho_{\rm d})^{[2]}, (\mathcal{G} \rho_{\rm d})^{[1]}, (\mathcal{G} \rho_{\rm d})^{[2]}, \delta t)$, $\qquad \qquad$ $m^{[3]}$ azor $^{[2]}$ $m^{[2]}$ $m^{[3]}$ $m^{[3]}$ $m^{[3]}$ $m^{[3]}$ $m^{[3]}$ $m^{[3]}$ $m^{[3]}$ $m^{[3]}$ $\mathbf{F}_i = \mathbf{A}_i (\mathbf{F}^*, (v \text{ S} \rho d), (S \rho d), (S \rho d), (S \rho d)$ $\Psi_i^{[3]} = \mathcal{A}_i^z(\Psi^{[2]}, (\nu^z \mathcal{G} \rho_d)^{[3]}, (\mathcal{G} \rho_d)^{[2]}, (\mathcal{G} \rho_d)^{n+1}, 0.5 \delta t)$

Kühnlein et al. GMD 2019
 EXA
 S where ⁹b*ⁱ* ⌘ ⁹[3]

6 Author One et al. Formulate Schur complement ✓**ⁱ** = ✓ b**ⁱ** + *th* [↵✓ (✓ ✓*^r*)]**ⁱ** (21) ⁼ ✓?#*n*+1 ⌘ **1** *Profillate Schur complement* **on the co-located grid grid grid grid grid set al. 4** σ

Author One et al. 5

$$
r_{i}^{n+1} = \hat{r}_{i}, \quad r_{i}^{n+1} = \hat{r}_{i}, \quad r_{i}^{n+1} = \hat{r}_{i}, \quad r_{s}^{n+1} = \hat{r}_{s}i
$$
\n
$$
r_{vi} = \hat{r}_{vi} + \delta t_{h} \left[-\alpha_{r_{v}} (r_{v} - r_{vr}) \right]_{i}
$$
\n
$$
\theta_{i} = \hat{\theta}_{i} + \delta t_{h} \left[-\alpha_{\theta} (\theta - \theta_{r}) \right]_{i}
$$
\n
$$
\theta'_{i} = \hat{\theta'}_{i} + \delta t_{h} \left[-\tilde{G}^{T} u \cdot \nabla \theta_{a} - \alpha_{\theta} \theta' - \alpha_{\theta} (\theta_{a} - \theta_{r}) \right]_{i}
$$
\n
$$
u_{i} = \hat{u}_{i} + \delta t_{h} \left[-\tilde{G}^{T} u \cdot \nabla \theta_{a} - \alpha_{\theta} \theta' - \alpha_{\theta} (\theta_{a} - \theta_{r}) \right]_{i}
$$
\n
$$
u_{i} = \hat{u}_{i} + \delta t_{h} \left[-\theta^{*} \theta^{n+1} \tilde{G} \nabla \phi' - (\theta_{a} + \theta') \theta^{n+1} \tilde{G} \nabla \phi_{a} + g - f \times u + \mathcal{M}^{*} (u^{*}, u) - \alpha_{u} (u - u_{r}) \right]_{i}
$$

$$
Lu = \hat{\vec{u}} - \delta t_h \theta_{\rho}^{\star} \widetilde{G} \nabla \varphi' \longrightarrow u = L^{-1} \hat{\vec{u}} - L^{-1} \delta t_h \theta_{\rho}^{\star} \widetilde{G} \nabla \varphi' \longrightarrow u = \overline{u} - C \nabla \varphi' \overline{u} = L^{-1} \hat{\vec{u}} \qquad C = L^{-1} \delta t_h \theta_{\rho}^{\star} \widetilde{G}
$$

•density in flux form of the driven in flux form of the dr **ⁱ** ⁼ *^r*b*ⁱ* **ⁱ** , *rs* for the Exner pressure variable.

ⁱ ⁼ *^r*b*^l* **ⁱ** , *rr*

 \bullet Schur complement is formed to reduce the dimension of the original 5-by-5 system to one Helmholtz equation of

• Newton relaxation terms

on MPDATA, as described in **?**

Helmholtz equation for implicit treatment of Exner pressure <u>The following acquation for implicit treatment of Exner pressure</u> es: .
. . . .

takes into account a time-dependent ambient state and forcings from physical parametrisations:

The following is the internal energy constraint written in a perturbation form for the Exner pressure, that explicitly

 t to a term and σ equation of state complied with mass community, thermodynamic, and σ Total derivative of equation of state combined with mass continuity, thermodynamic, and water vapour Total and
miving retia equational vialda asso Smalerkiewiez et al. (2014, 2017, 2010); Kühnlein et al. 2010; notal derivative or equation or state combined with mass continuity, thermodynamic, and water va
mixing ratio equations yields, see Smolarkiewicz et al. (2014, 2017, 2019); Kühnlein et al. 2019: ve or equation or state combined with mass continuity, thermodynamic, and
equations yields, see Smolarkiewicz et al. (2014, 2017, 2019); Kühnlein et al , → **d** with the control
With the control *P* ✓ I with mass contini
vicz et al. (2014, 2 continuity, thermod
014, 2017, 2019): 1 + *rv* /"

$$
\frac{\partial(\mathcal{G}\rho_{d}\varphi')}{\partial t} + \nabla \cdot (\mathbf{v}\mathcal{G}\rho_{d}\varphi') = \mathcal{G}\rho_{d} \left[-\frac{\xi\varphi}{\mathcal{G}} \nabla \cdot (\mathcal{G}G^{T} \mathbf{u}) - \frac{1}{\mathcal{G}\rho_{d}} \nabla \cdot (\mathcal{G}\rho_{d}\varphi_{a}G^{T} \mathbf{u}) + \frac{\varphi_{a}}{\mathcal{G}\rho_{d}} \nabla \cdot (\mathcal{G}\rho_{d}G^{T} \mathbf{u}) - \frac{\partial \varphi_{a}}{\partial t} + P^{\varphi} \right]
$$
\nwith
$$
P^{\varphi} = \xi\varphi \left(\frac{P^{\theta}}{\theta} + \frac{P^{r_{V}}/\varepsilon}{1 + r_{V}/\varepsilon} \right) \qquad \xi = \frac{R_{d}}{c_{Vd}}
$$

• The Exner pressure obtained from (13) does not necessarily fulfil the equation of state at the moment, this needs

• The Exner pressure obtained from (13) does not necessarily fulfil the equation of state at the moment, this needs

1 + *rv* /" $\varphi_1' = \mathcal{A}(\varphi'^n + (1-\beta)\delta t \mathcal{R}^{\varphi'}|^n + \delta t P^{\varphi'}|^n, (\nu \mathcal{G} \rho_d)^{\perp}|^{n+1/2}, (\mathcal{G} \rho_d)^n, (\mathcal{G} \rho_d)^{n+1}, \delta t) + \beta \delta t \mathcal{R}^{\varphi'}|^{n+1}$ | | |

 $\mu \in [0.3, 1.0]$ $\beta \in [0.5, 1.0]$

• Put a note about forcing of pressure from physics but don't go into details in this paper

to be developed.

with

Elliptic Helmholtz boundary value problem Reorganising terms finally yields the elliptic (inhomogeneous) Helmholtz equation for the pressure perturbation \blacksquare The future in the future of the future of the future problem can be written compact of the set un undary value proble |
| \overline{a} 1
Iu alue pr $\frac{1}{2}$

$$
0 = -\sum_{\ell=1}^3 \left(\frac{A_{\ell}^{\star}}{\zeta_{\ell}} \nabla \cdot \zeta_{\ell} \widetilde{\mathbf{G}}^T (\overline{\mathbf{u}} - \mathbf{C} \nabla \varphi') \right) - B^{\star}(\varphi' - \widehat{\varphi'}) \equiv \mathcal{L}(\varphi') - R
$$

where the spatial grid index index in (15) is over the summation of the summation \mathcal{L} is over the three divergence operators on \mathcal{L} Coefficients:

$$
A_1^* = 1, \quad A_2^* = \frac{c_{vd}}{R_d} \frac{\varphi_a}{\varphi} = -A_3^*, \qquad \zeta_1 = \mathcal{G}, \quad \zeta_2 = \mathcal{G} \rho_d \varphi_a, \quad \zeta_3 = \mathcal{G} \rho_d, \qquad B^* = \frac{1}{\beta \delta t} \frac{c_{vd}}{R_d \varphi}
$$

Advective part:

A?

$$
\widehat{\varphi'} = \mathcal{A}(\varphi'^n + (1-\beta)\delta t \mathcal{R}^{\varphi'}|^n + \delta t P^{\varphi'}|^n, (\mathbf{V}\mathcal{G}\rho_d)^{\perp}|^{n+1/2}, (\mathcal{G}\rho_d)^n, (\mathcal{G}\rho_d)^{n+1}, \delta t)
$$

- ^{it} Evno *t* \triangleright 3D implicit Exner pressure solution is a crucial aspect for the performance, robustness and accuracy of the FVM model
- ■
■ > Different kinds of solution methods considered/developed as some future HPC architectures may require approaches that operate within the acoustic radius

Linear solvers for the 3D Helmholtz problem where $r^{(1)}$ denotes the residual error of Eq. (20). The precondition of Eq. (20). The precondition of \mathbb{R}^2 chargonal entries. The actual indicates the constitution in the constitution of the constitution in th **Lilical**

- We prefer the Generalized Conjugate Residual method of order *k* for nonsymmetric systems (GMRES, BiCGSTAB are alternatives, pipelined versions can be useful) *^Pz(e^µ*+1*)* ⁺ *^P*h*(eµ) ^r*^ˆ ⁼ ⁰*,* (B2) *P* //P prefer the Generalized Conjugate Residual method of order *k* for
Interpretence systems (GMRES, BiCGSTAB are alternatives, pipelined v
- extribution of the diagonal coefficient of *Philipseum* coefficient of *Philipseum*

ⁱ schemes, respec-

^d and

^h *^G*⇢d*)*[2]

,Gn+1*,*0*.*5*t) ,* (A1)

*,*0*.*5*t) ,* (A2)

ⁿ+1*,*0*.*5*t) ,* (A2)

ⁱ using half-time steps in the two

tively. For each model time step *t*, these are applied in the

vertical sweeps and the full time step in the horizontal part.

 $S_{\rm eff}$

(vzG⇢d*)*[3] for the three sub-steps. For compatibility with

mass continuity, these quantities are then all employed in the

subsequent advective transport of scalar variables 9e (Eq. 8)

subsequent advective transport of scalar variables 9e (Eq. 8)

horizontal part of the unstructured-mesh FV MPDATA of

Kühnlein and Smolarkiewicz (2017). The vertical scheme

^A^z is a corresponding 1-D structured-grid MPDATA. Re-

sults from numerical experimentation relevant to NWP show

 $t_{\rm eff}$

based on MPDATA can be considerably more efficient than

the standard fully multidimensional (unsplit) MPDATA of

Kühnlein and Smolarkiewicz (2017). This is particularly due

tion of the horizontal advection transport *^Axy* follows the

ⁱ . In Eqs. (A1) and (A2), the implementa-

- Bespoke preconditioners for atmospheric configurations
- Multi-grid extension for preconditioner (Gillard et al. 2024) **A**
 A for precor *k*, conditioner (Gillard et al. 2024)
- ^d and ^h *^G*⇢d*)*[2] مان العبد العبد
العبد العبد ال
والعبد العبد العبد العبد العبد العبد الع for tutorials with **B11** and **B22 referrences** of GeTC. Ø See Smolarkiewicz et al. (2000, 2004); Smolarkiewicz and Szmelter 2011

(vzG⇢d*)*[3] for the three sub-steps. For compatibility with \blacksquare W Weighted line Jacobi method preconditioner in FVM (Kühnlein et al. 2019): **i** . In Eqs. (A1) and (A2), the intion of the horizontal advection transport *^Axy* follows the

$$
e^{\mu+1} = \omega \left[\mathcal{D} + \mathcal{P}_z \right]^{-1} \left(\mathcal{D} e^{\mu} - \mathcal{P}_h(e^{\mu}) + \hat{r} \right) + (1 - \omega) e^{\mu}
$$

$$
\mathcal{D}_{k,i} = -\frac{1}{4\mathcal{V}_i} \sum_{\ell=1}^3 \frac{A_{\ell k,i}^{\star}}{\zeta_{\ell k,i}} \sum_{j=1}^{l(i)} \frac{\zeta_{\ell k,j}}{\mathcal{V}_j} \left(\mathcal{B}_{k,j}^{11} S_j^{x^2} + \mathcal{B}_{k,j}^{22} S_j^{y^2} \right)
$$

with B_1 and B_2 referring to the diagonal entries of B_2 referring to the diagonal entries of GeTC.

For *n* = 1,2,... until convergence do

ECMWF EUROPEAN CENTRE FOR MEDIUM-RANGE WEATHER FORECASTS **21** for $v = 0$k-1 do $\beta = -\frac{\langle r^{\nu} L(q^{\nu}) \rangle}{\langle \int (q^{\nu}) \int (q^{\nu}) \rangle}$ $\frac{\sqrt{2(q\gamma)}}{\langle \mathcal{L}(q^{\nu})\mathcal{L}(q^{\nu})\rangle}$ $\psi_i^{\nu+1} = \psi_i^{\nu} + \beta q_i^{\nu}$, $r_i^{\nu+1} = r_i^{\nu} + \beta \mathcal{L}_i(q^{\nu}),$ exit if $||r^{v+1}|| \leq \epsilon$. $e_{\mathbf{i}} = \mathcal{P}_{\mathbf{i}}^{-1} (r^{\nu+1}),$ evaluate L**i**(*e*) , $\forall_{l=0,\nu} \; \alpha_l = -\frac{\langle \mathcal{L}(e) \mathcal{L}(q^l) \rangle}{\langle \mathcal{L}(q^l) \mathcal{L}(q^l) \rangle} \; ,$ $q_i^{\nu+1} = e_i +$ $\frac{\nu}{\sqrt{2}}$ *l* =0 α _{*l*} q' _{**i**}, $\mathcal{L}_{\mathbf{i}}(q^{\nu+1}) = \mathcal{L}_{\mathbf{i}}(e) + \sum_{i=1}^{(\nu)}$ *l* =0 α _{*l*} $\mathcal{L}_{\mathbf{i}}(q^l)$, end do , reset $(\psi, r, q, \mathcal{L}(q))_{\mathbf{i}}^k$ to $[\psi, r, q, \mathcal{L}(q)]_{\mathbf{i}}^0$, GCR(k) scheme

end do .

FVM comparison to hydrostatic IFS-ST: dry adiabatic dynamics

experimental setup following Ullrich et al. QJ 2012

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FVM comparison to hydrostatic IFS-ST: dry adiabatic dynamics

Second-order finite-volume provides essentially the same -60° solution-quality than spectral-transform model for this test

surface pressure (hPa) at day 15 1040 60° 1020 1000 30° 980 Finite-volume / O320 0° 960 940 -30° 920 900 -60° 880 315° 90° 135° 180° 225° 270° 1040 60° 1020 1000 30° 980 0° Spectral-transform / TCo319 960 940 -30° 920 900 880 The blue vertical line indicates the spatial scale corresponding the nominal grid spatial grid spatial grid sp
The spectra sp 270° 315° 225° 32km **23**

cCECMWF

Snapshot of computational efficiency: FVM vs IFS-ST

- Dry baroclinic instability experiments in identical configuration O1280/TCo1279 (9km) with L137
- Time steps of IFS-FVM were a factor of 6-7 smaller than IFS-ST

O1280/TCo1279 with L137 dry dycore on 350 nodes of ECMWF's Cray XC40

Comparison study on latest GPU hardware in prep!

Octahedral and HEALPix meshes with FVM

Octahedral O400 example for baroclinic instability benchmark

Octahedral and HEALPix meshes with FVM

HEALPix H240 example for baroclinic instability benchmark

Octahedral and HEALPix meshes with FVM

Stratified flow past Schär mountain in small-planet configuration

Stratified flow past steep orography in small-planet configuration

Experimental setup following Zängl MWR 2012

 \rightarrow IFS-FVM robust wrt very steep slopes of orography

CCECMWF EUROPEAN CENTRE FOR MEDIUM-RANGE WEATHER FORECASTS

DCMIP2016 dynamical core intercomparison: splitting supercell

Zarzycki et al. GMD 2019

DCMIP2016 dynamical core intercomparison: splitting supercell

final 2h result as various grid spacing (panels are at 4, 2, 1, 0.5 km)

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DCMIP2016 dynamical core intercomparison: splitting supercell

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CCECMWF

 \rightarrow FVM uses second-order Finite-Volume method

 \rightarrow TEMPEST uses higher-order Spectral-Element methods

$$
IKE(t) = \frac{1}{2} \int_{0}^{z_t} \int_{0}^{A_e} \rho \left(u'^2 + v'^2 + w'^2 \right) dA dz
$$

European Centre for medium-range weight

DCMIP2016 dynamical core intercomparison: tropical cyclone

Figure 4. Azimuthally averaged vertical wind composite of the simulated TCs from days 4–10 of the 50 km simulation.

> 75 **EUROPEAN CENTRE FOR MEDIUM-RANGE WEATHER FORECASTS**

ulated TCs from days $4-10$ of the 25 km simulation.

Figure 6. Wind–pressure relationship in the simulated TCs at all ber of the editorial board of *Geoscientific Model Development*. The time steps for 25 km simulations of participating models. authors also have no other competing interests to declare.

Willson et al. GMD 2024 wilison et al. Givid Zuz

DCMIP2016 dynamical core intercomparison: tropical cyclone

Figure 8. Azimuthally averaged vertical wind composite of the simulated TCs from days $4-10$ of the 25 km simulation.

Figure 4. Azimuthally averaged vertical wind composite of the simulated TCs from days 4–10 of the 50 km simulation.

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FVM case study of Hurricane IRMA

- Major Hurricane of Category 5 in tropical Atlantic
- Formed 30 August 2017
- Dissipated 14 September 2017
- 285 km/h 1-minute sustained winds
- 914 hPa minimum MSLP
- Peak intensity on 5 September 2017
- Fourth-costliest tropical cyclone on record

FVM forecast experiments of Hurricane IRMA

- **Initialisation from IFS analysis 20170904 00 UTC**
- O1280/TCo1279 corresponding to ~9 km nominal spacing, L62
- § IFS CY43R3, uncoupled

FVM forecast experiments of Hurricane IRMA

Christian Kühnlein, Linus Magnusson

FVM forecast experiments of Hurricane IRMA

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F IFS CY43R3, uncoupled

Christian Kühnlein, Linus Magnusson

Relevance of nonhydrostatic effects for the supercell convective storm formulation of IFS: From what horizontal grid spacing *^h* appear significant di↵erences?

EUROPEAN CENTRE FOR MEDIUM-RANGE WEATHER FORECASTS EXAMPLE AND AND AND NHA-IFS USE IN MILDROW-WANDLE WERTHERN PORLOAGING

Relevance of nonhydrostatic effects for the supercell convective storm

EUROPEAN CENTRE FOR MEDIUM-RANGE WEATHER FORECASTS INH-FIM USES SERVICE TO DESIGN NANOE MEATHER TO DESIGN TO

Single-precision implementation of FVM

- Runtimes for a O640/L62 4-day forecast using single- vs. double-precision on Cray XC40
- Configuration is for init date 22 May 2018 00 UTC, full IFS physics package, all parametrisations apart from radiation and non-orographic GW drag are called at every FVM time step here
- Radiation called every hour and run on the same O640 grid
- Convergence of the FVM preconditioned Krylov solver is essentially identical with SP and DP given typical thresholds

Single-precision implementation of FVM

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Single-precision implementation of FVM

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FVM 1.0: a nonhydrostatic finite-volume dynamical core for the IFS

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