

# Global deep-learning weather prediction model evaluation and error diagnostics

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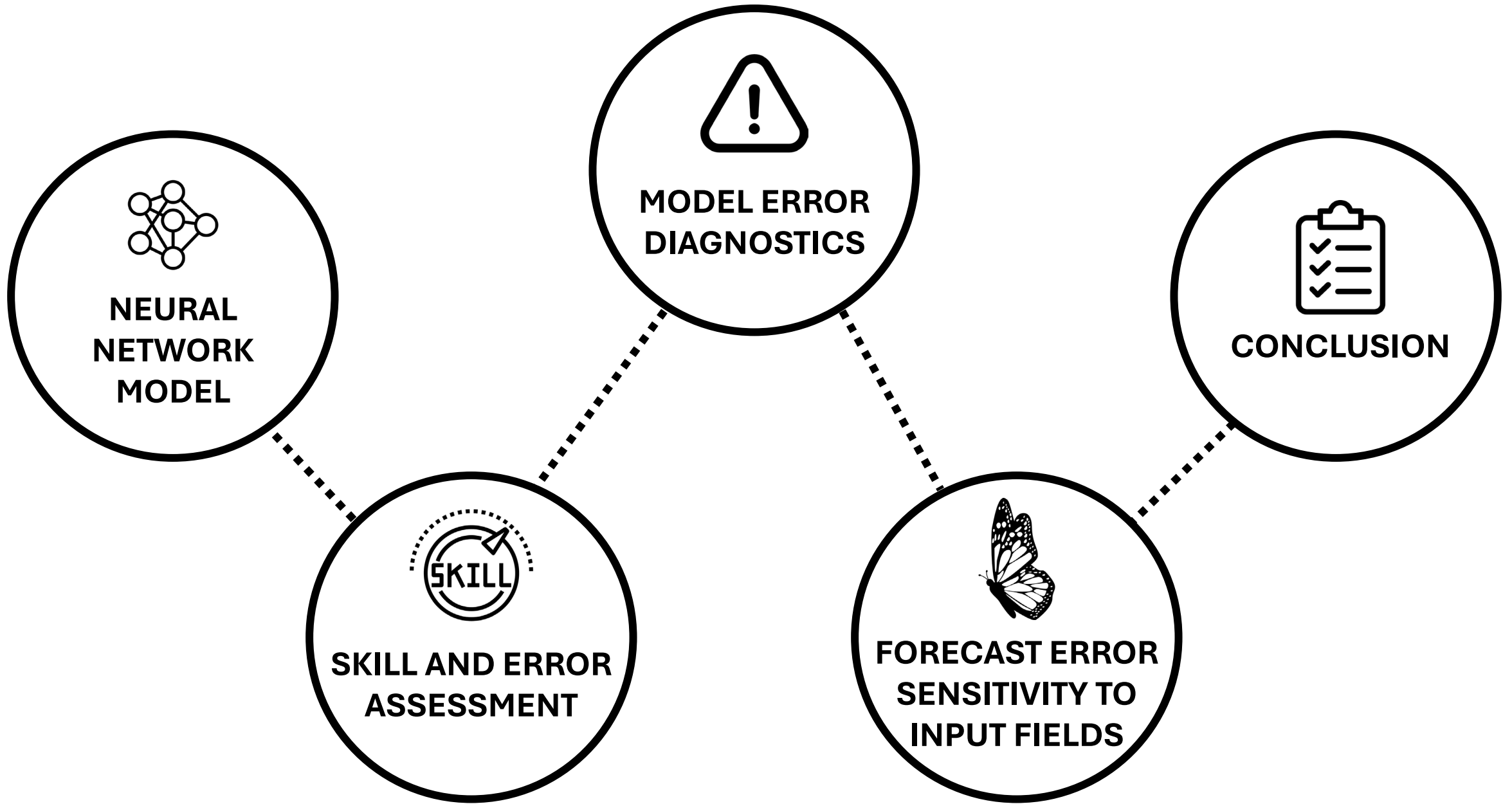
**FMF**

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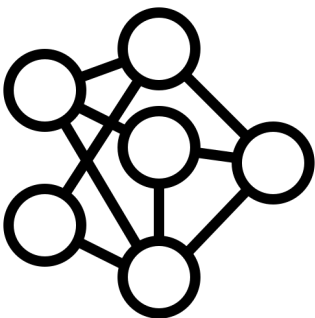
<sup>1</sup>University of Ljubljana

<sup>2</sup>ECWMF





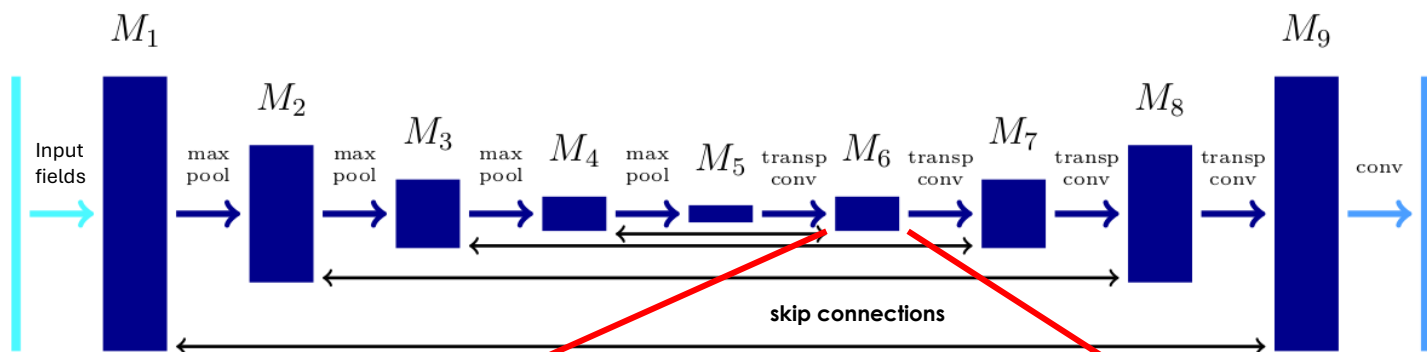
**NEURAL  
NETWORK  
MODEL**



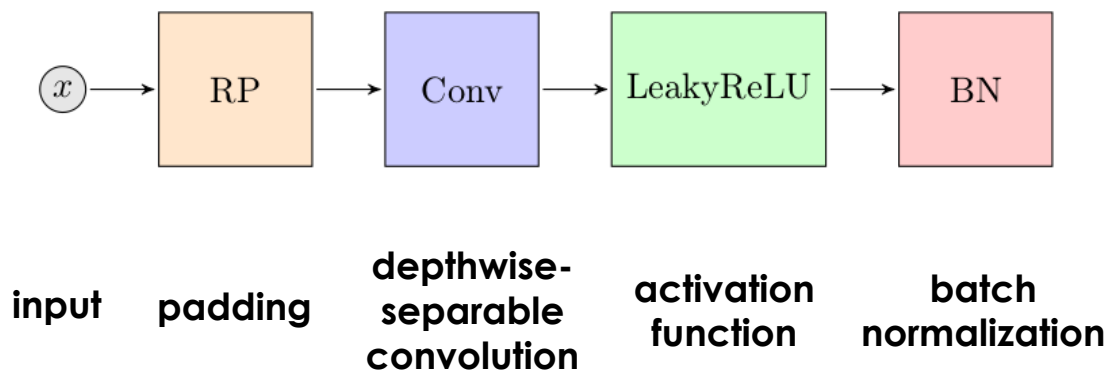
**NEURAL  
NETWORK  
MODEL**

# ConvCastNet: convolutional weather forecasting neural network

## MODEL ARCHITECTURE

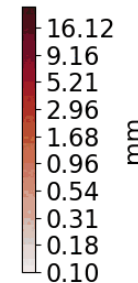
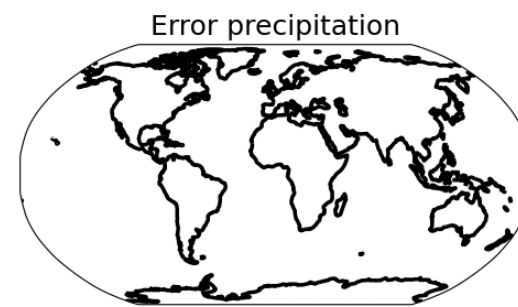
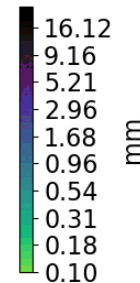
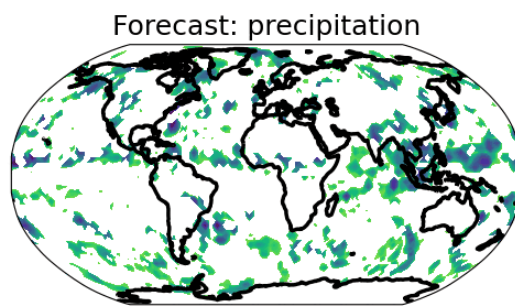
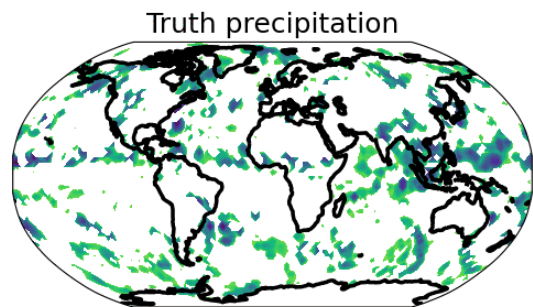
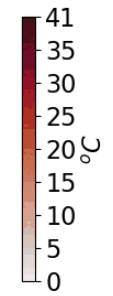
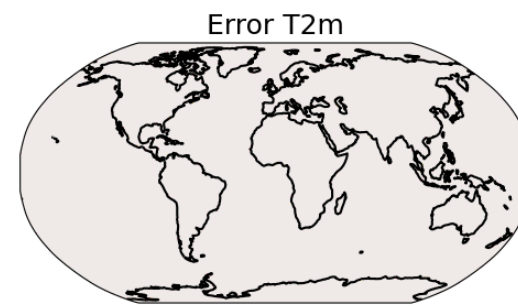
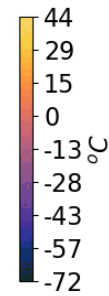
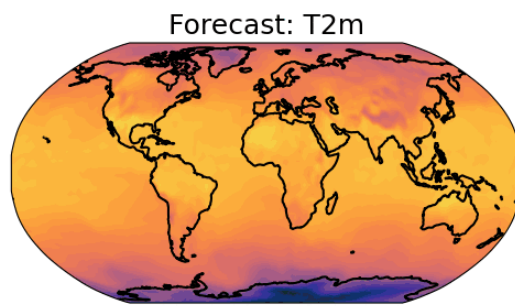
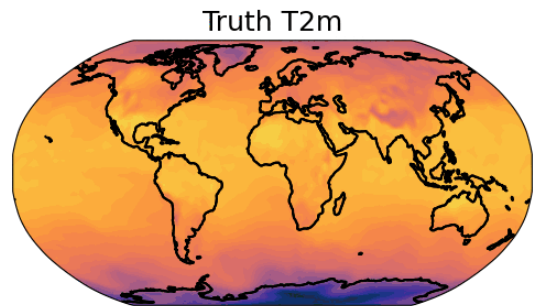
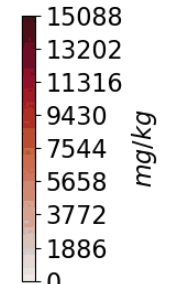
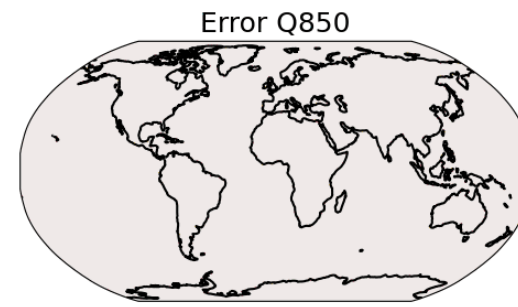
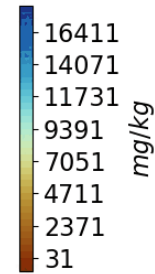
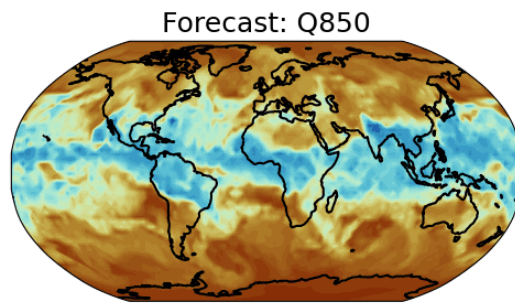
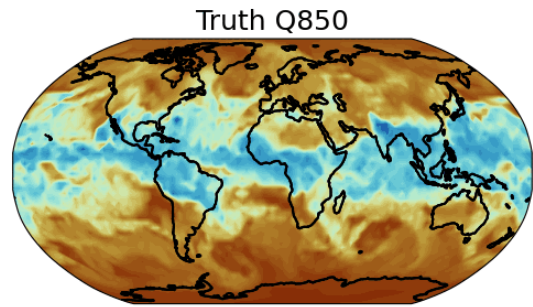
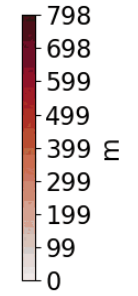
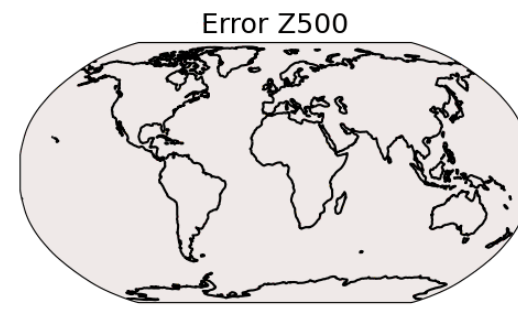
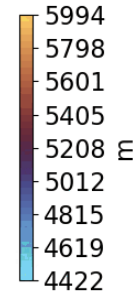
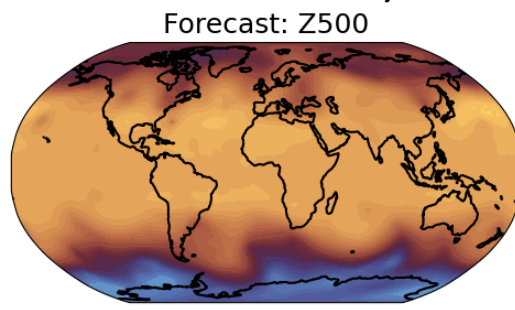
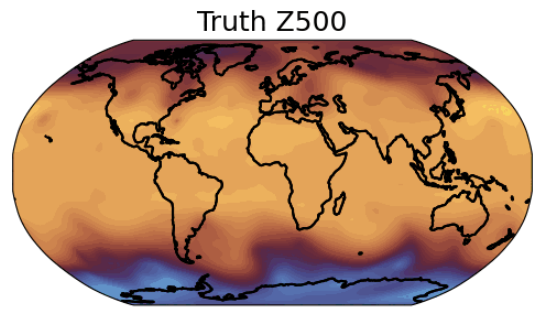


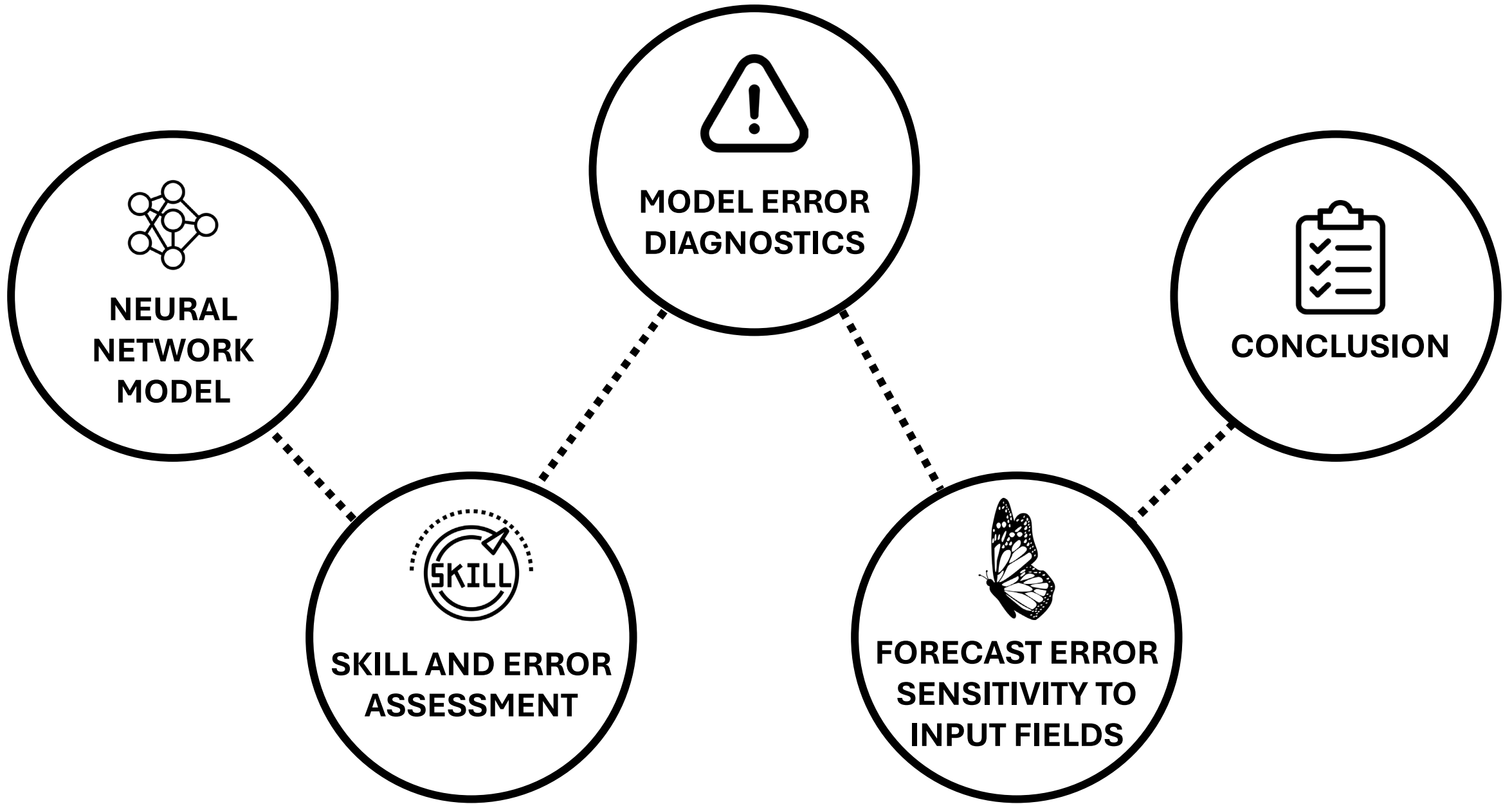
4 x



- Training data ERA5 reanalysis:
  - Train: 1970 – 2014
  - Validation: 2015 – 2019
  - Test: 2020 - 2022
- Model resolution:  $3^\circ$
- Variables
  - Z, u, v,  $\omega$ , T, q at 13 pressure levels
  - T2m, u10, v10, land and ice surface temperature, SST, mslp, tp
  - Sea ice, snow depth, soil moisture, top-of-atmosphere solar radiation, ...
- Training: 4 autoregressive steps
- Time step: 12 hr

Start date: 23.9.2022 ; Forecast day: 0.0







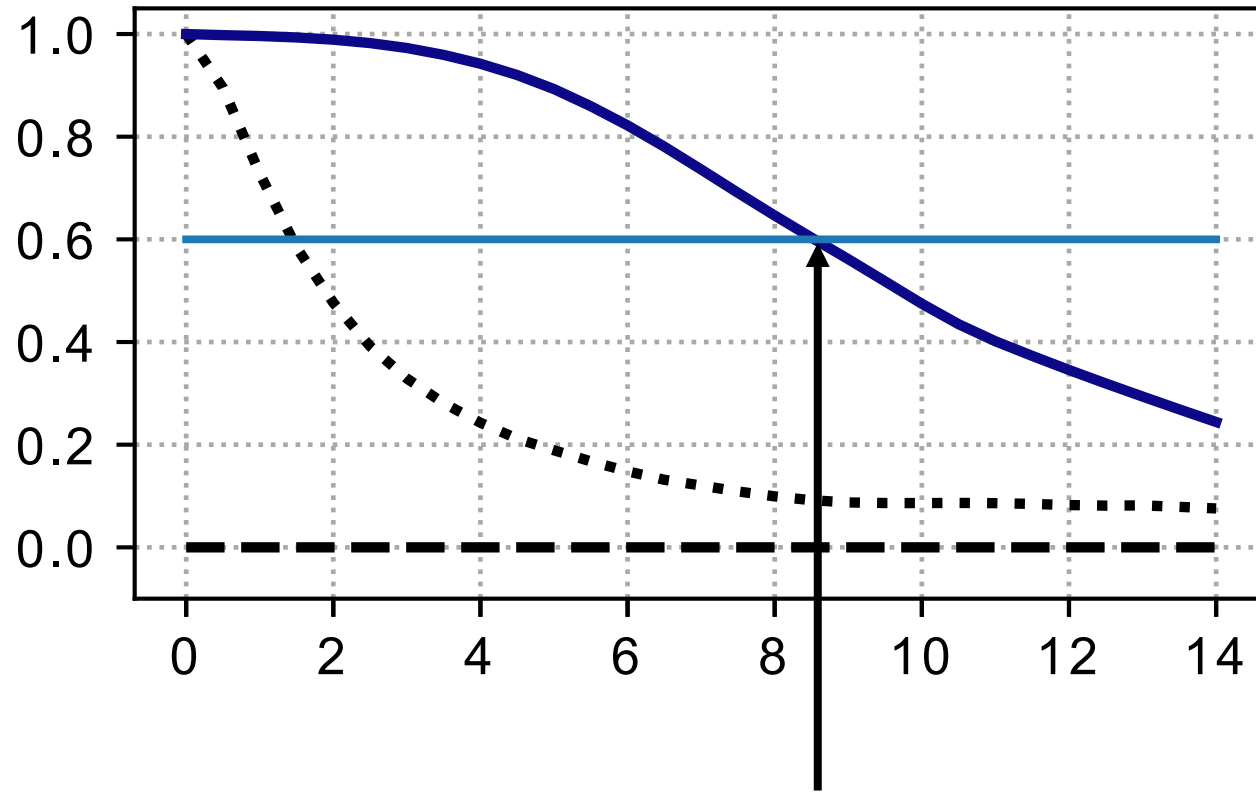




**SKILL AND ERROR  
ASSESSMENT**

# GLOBAL SKILL

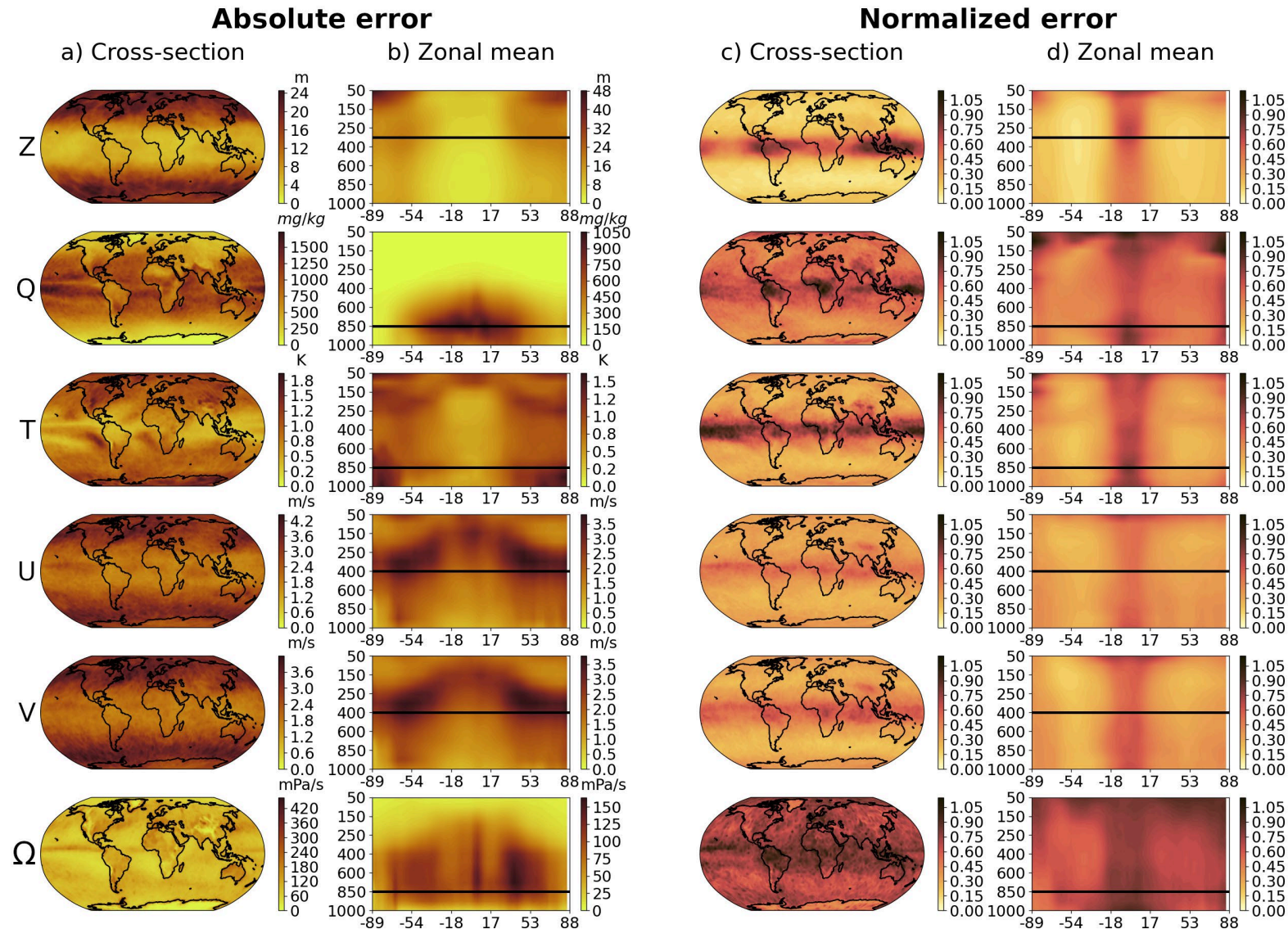
## ACC Z500



Large-scale forecast skill close to state-of-the-art ML models

ACC > 0.6 for 8.5 days

# SPATIAL DISTRIBUTION OF ERRORS



Lead time: 2 days



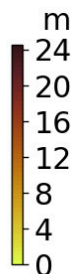
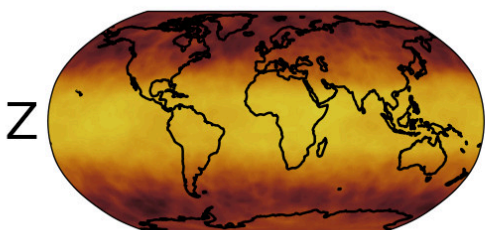
**Absolute error:**  
absolute difference between  
forecast and ERA5 „truth“

**Normalized error:**  
absolute error divided by natural  
variability

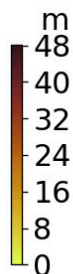
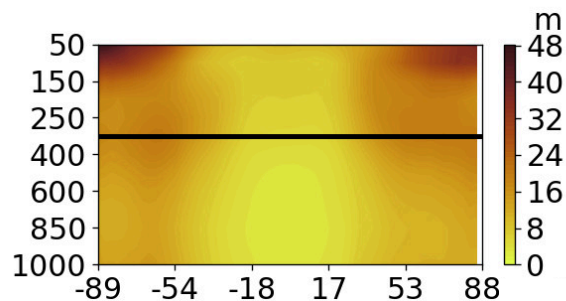
# GEOPOTENTIAL

## Absolute error

a) Cross-section

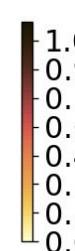
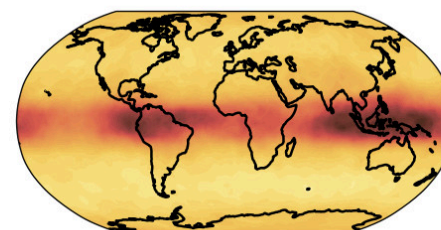


b) Zonal mean

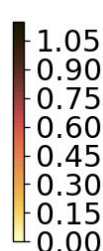
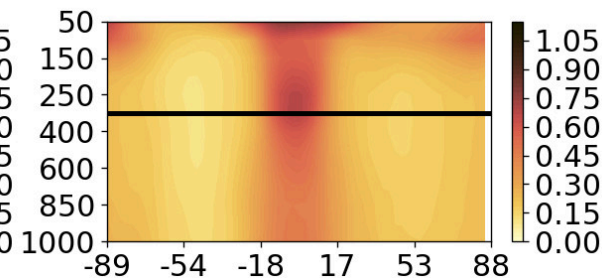


## Normalized error

c) Cross-section



d) Zonal mean



Large absolute errors:

- Mid-to-high latitudes
- Polar stratosphere

Correspond to large natural variability

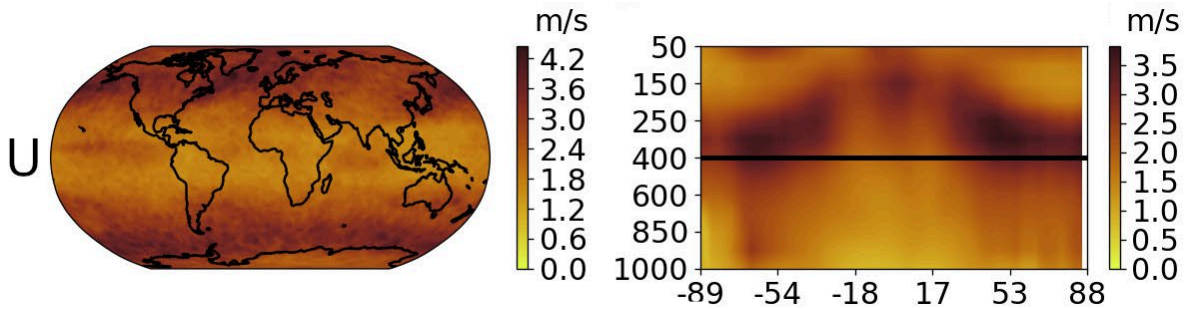
Large normalized errors:

- Tropics
- Polar and tropical stratosphere

Better describes error relative to expected natural weather variability

# ZONAL WIND

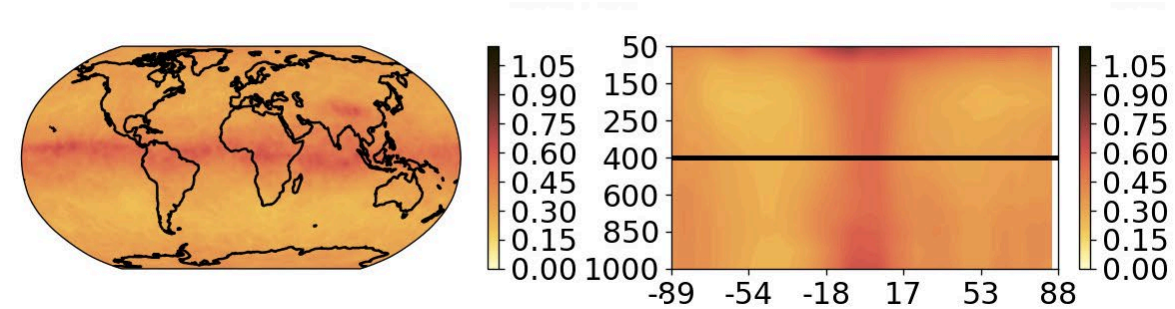
## Absolute error



Large absolute errors:

- Region of strong mid-latitude westerly jet
- Stratosphere

## Normalized error

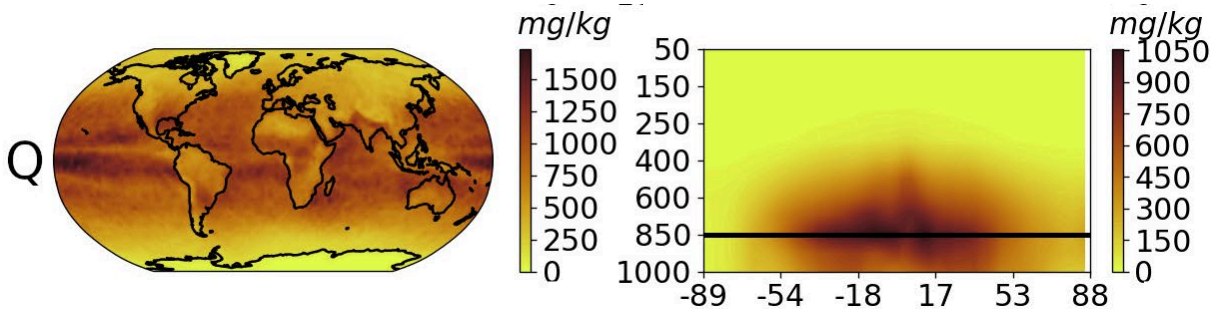


Large normalized errors:

- Tropical atmosphere
- Tibetan Plateau

# SPECIFIC HUMIDITY

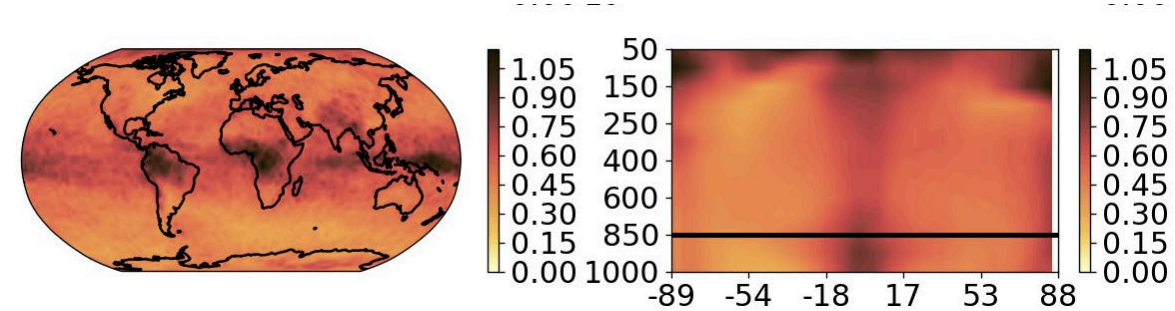
## Absolute error



Large absolute errors:

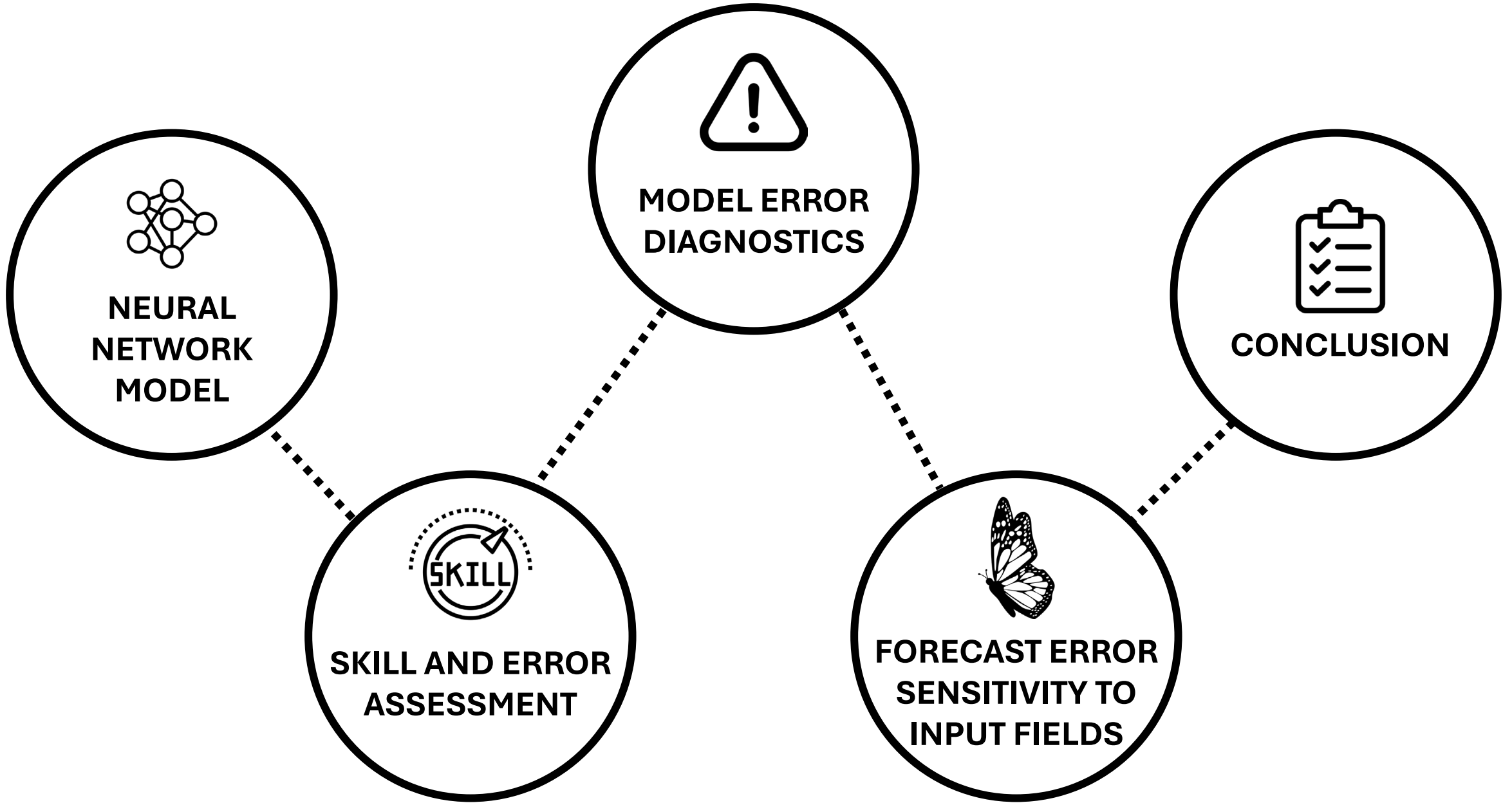
- Above oceans
- Lower troposphere

## Normalized error



Large normalised errors:

- Congo and Amazon basin
- Maritime continent
- Tropical oceans
- Stratosphere





**MODEL ERROR  
DIAGNOSTICS**





**MODEL ERROR  
DIAGNOSTICS**

# MODEL ERROR DIAGNOSTICS

- How does the forecast skill improve if we continuously replace forecasted fields with ERA5 „truth“ in:
  1. Tropics?
  2. Stratosphere?
- We perform the analysis by replacing forecasted fields in the tropics/stratosphere with ERA5 „truth“:

autoregressive input field

ERA5 „truth“ term

Model forecast term

$$x(\lambda, \varphi, p, t + \Delta t) = \text{weight}_\tau(\lambda, \varphi, p) \cdot \text{ERA5}(\lambda, \varphi, p, t + \Delta t) + (1 - \text{weight}_\tau(\lambda, \varphi, p)) \cdot \mathcal{M}_{t \rightarrow t + \Delta t}(s(t))(\lambda, \varphi, p)$$

- We measure skill gain with the following metric:  $1 - \frac{\text{error}(M(x))}{\text{error}(M(x_{\text{forced}}))}$

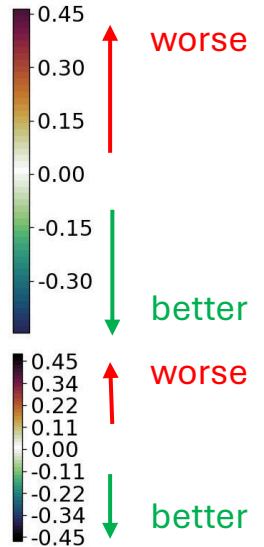
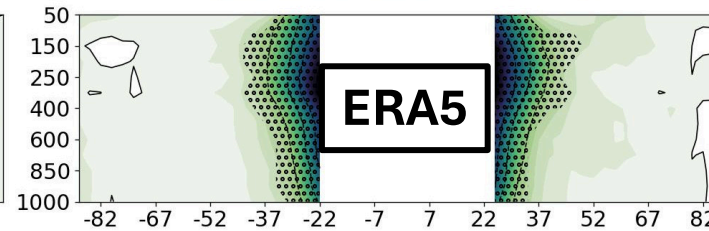
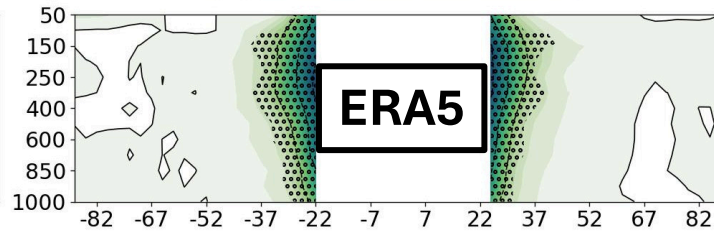
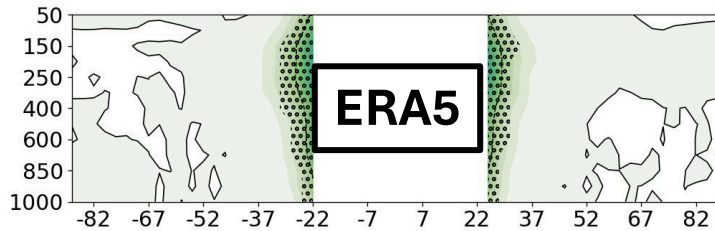
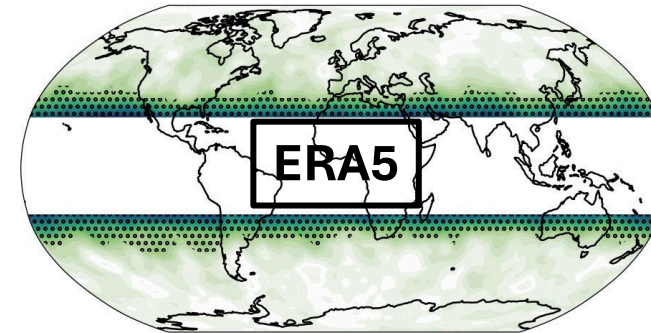
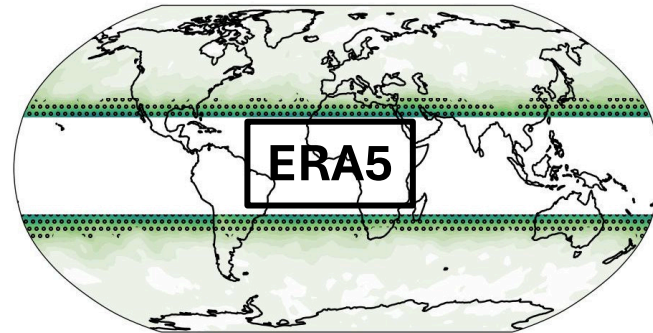
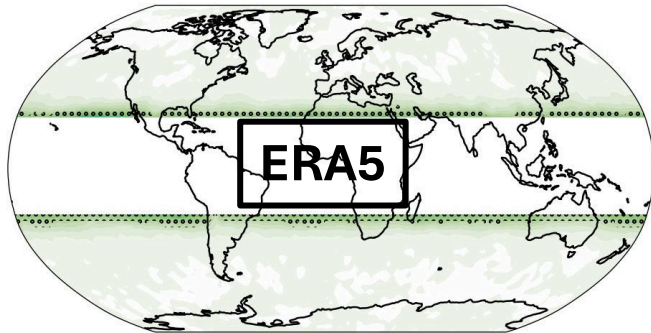
# FORECAST SKILL IMPROVEMENT

## Tropics

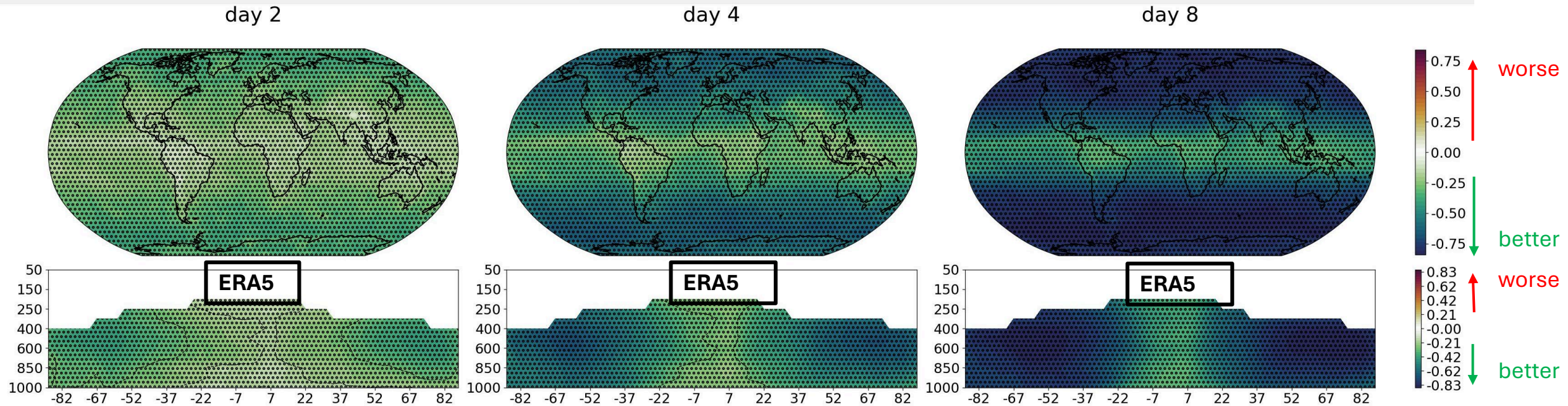
day 2

day 4

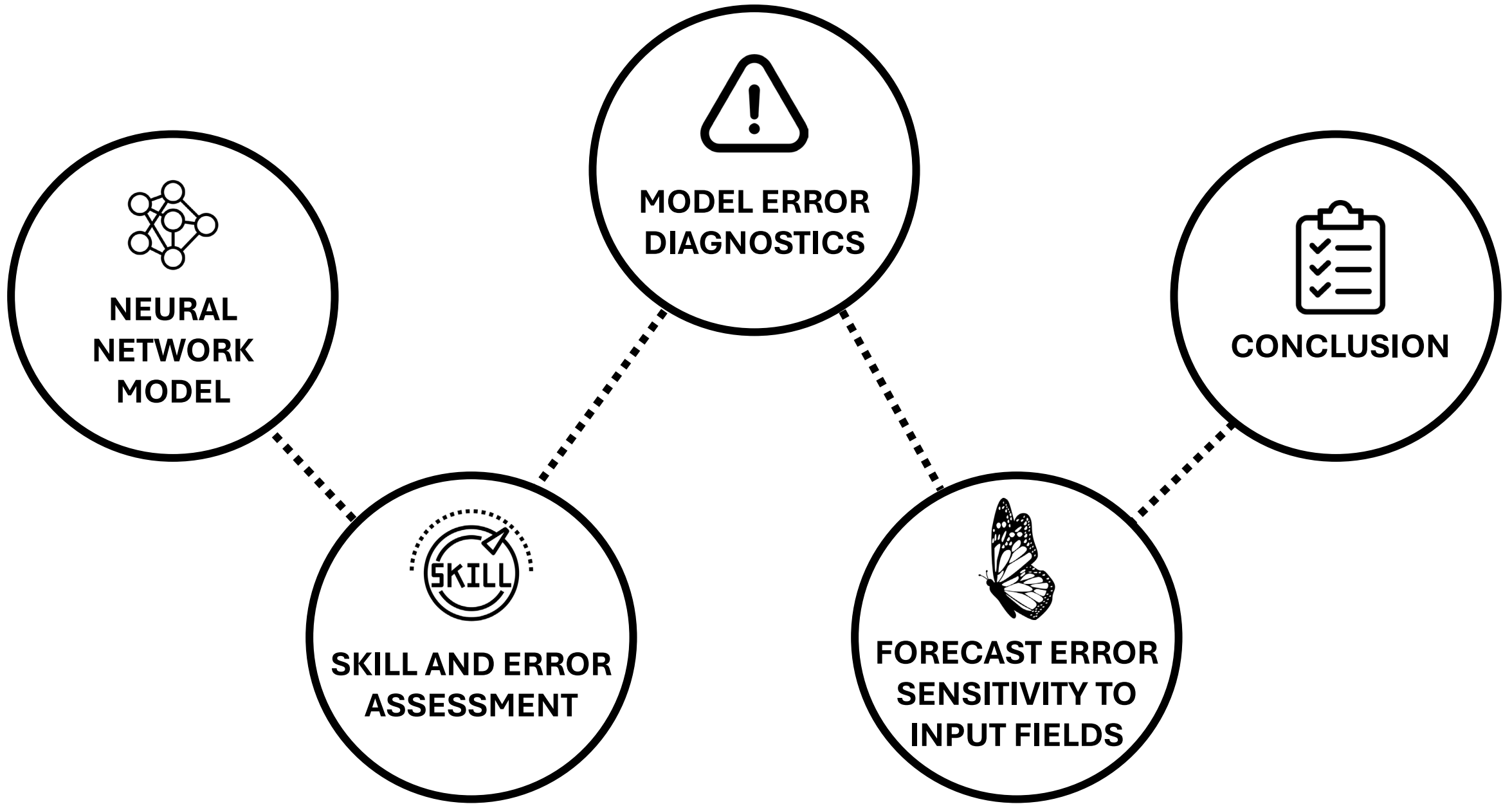
day 8



# Stratosphere



- This method easily diagnoses problematic regions in ML models
  - Very few issues regarding the boundary between ERA5 „truth“ and the model forecast
- We identify the stratosphere to be the key region needing better representation to improve model skill
- We could investigate other regions e.g. mountains or oceans as well





**FORECAST ERROR  
SENSITIVITY TO  
INPUT FIELDS**



**FORECAST ERROR  
SENSITIVITY TO  
INPUT FIELDS**

# FORECAST ERROR SENSITIVITY TO INPUT FIELDS

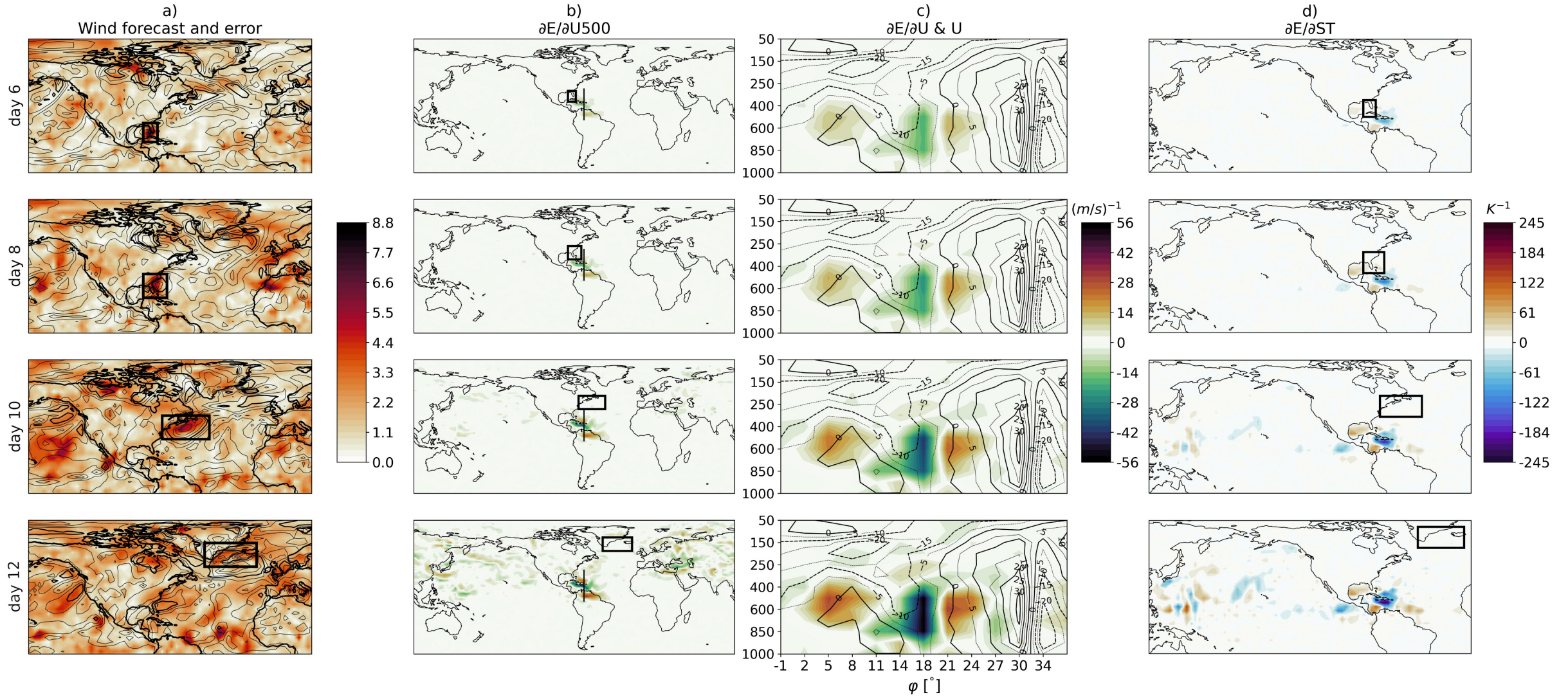
- Calculate the sensitivity of the forecast errors to the input fields:

=> derivative of forecast error with respect to input fields:  $\frac{\partial E}{\partial(IC)}$

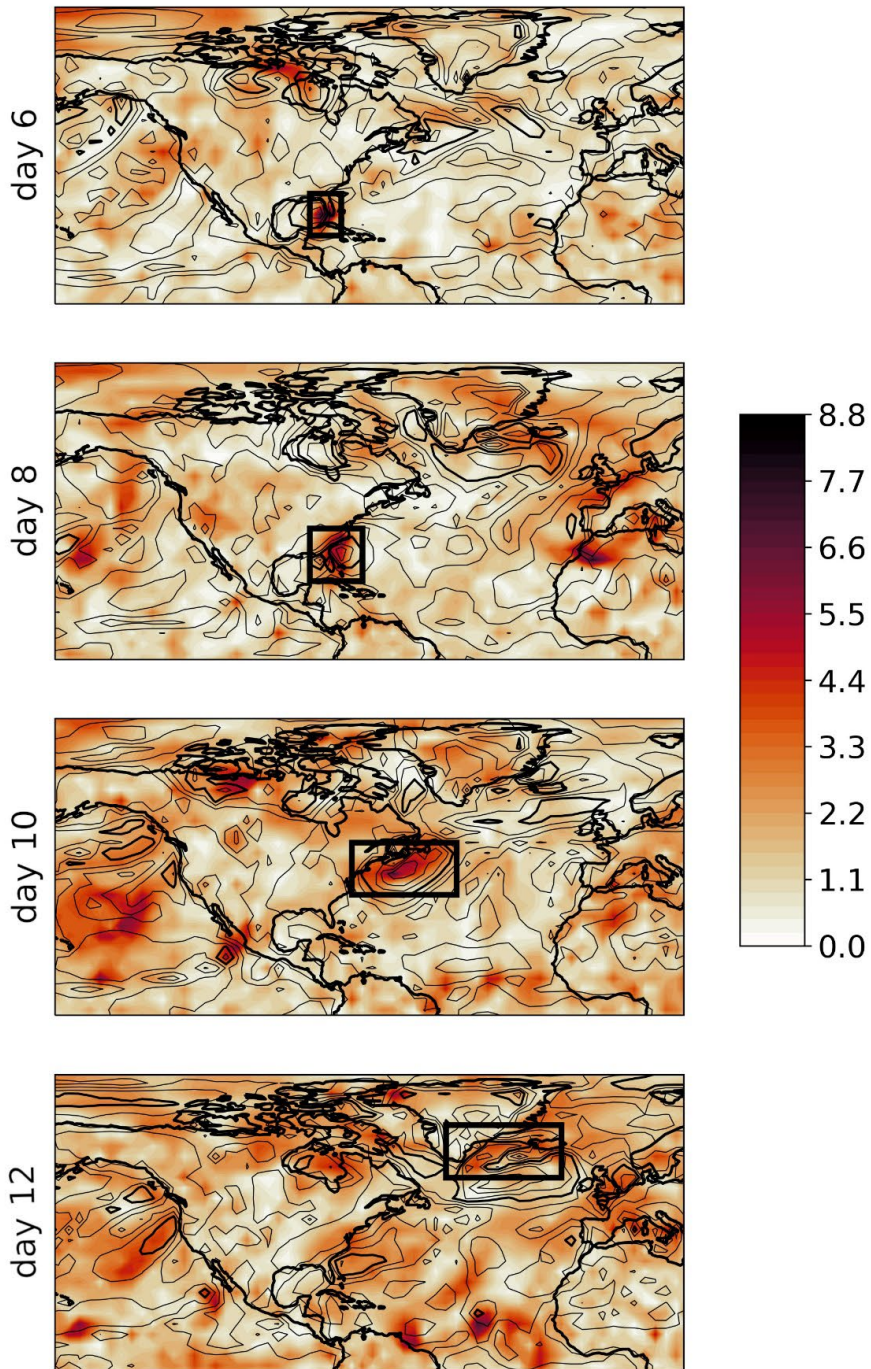
- ML models are auto-differentiable → error backpropagation
- Can it be used to improve weather forecasts?



# HURRICANE IAN: forecast initialisation – September 23, 2022



## Wind forecast and error

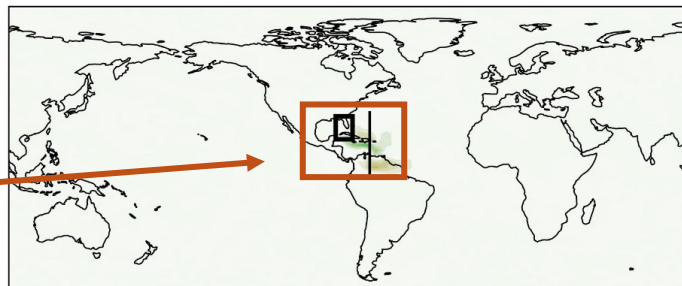


- Contours: 10 m horizontal wind speed forecast
- Colour: 10 m normalised wind forecast error
- Black box: domain for error calculation

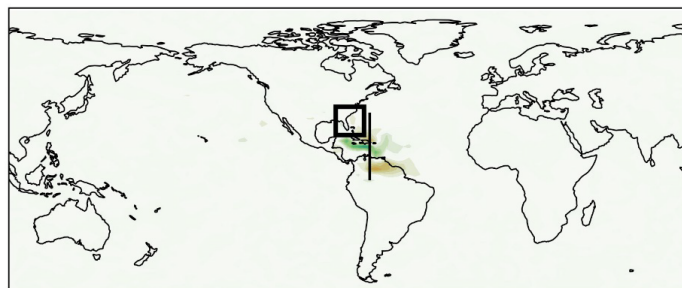
Aim of case study: estimate the sensitivity of Hurricane Ian's forecast error to the initial conditions.

# SENSITIVITY TO ZONAL WINDS

Sensitivity to subtropical jet stream

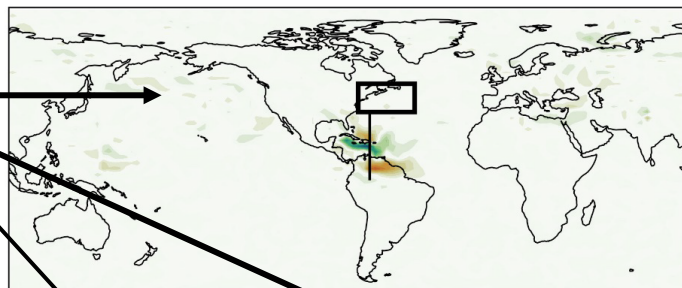


day 6



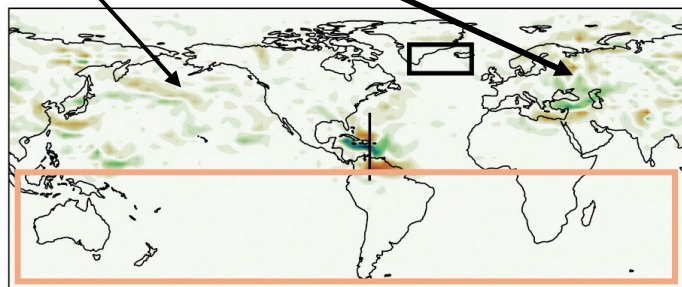
day 8

Sensitivity to upstream Rossby waves and tropical waves

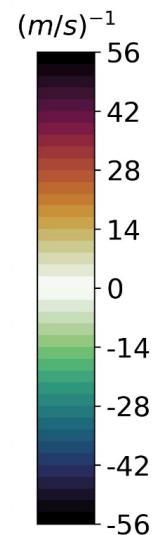


day 10

No sensitivity to Southern Hemisphere initial conditions

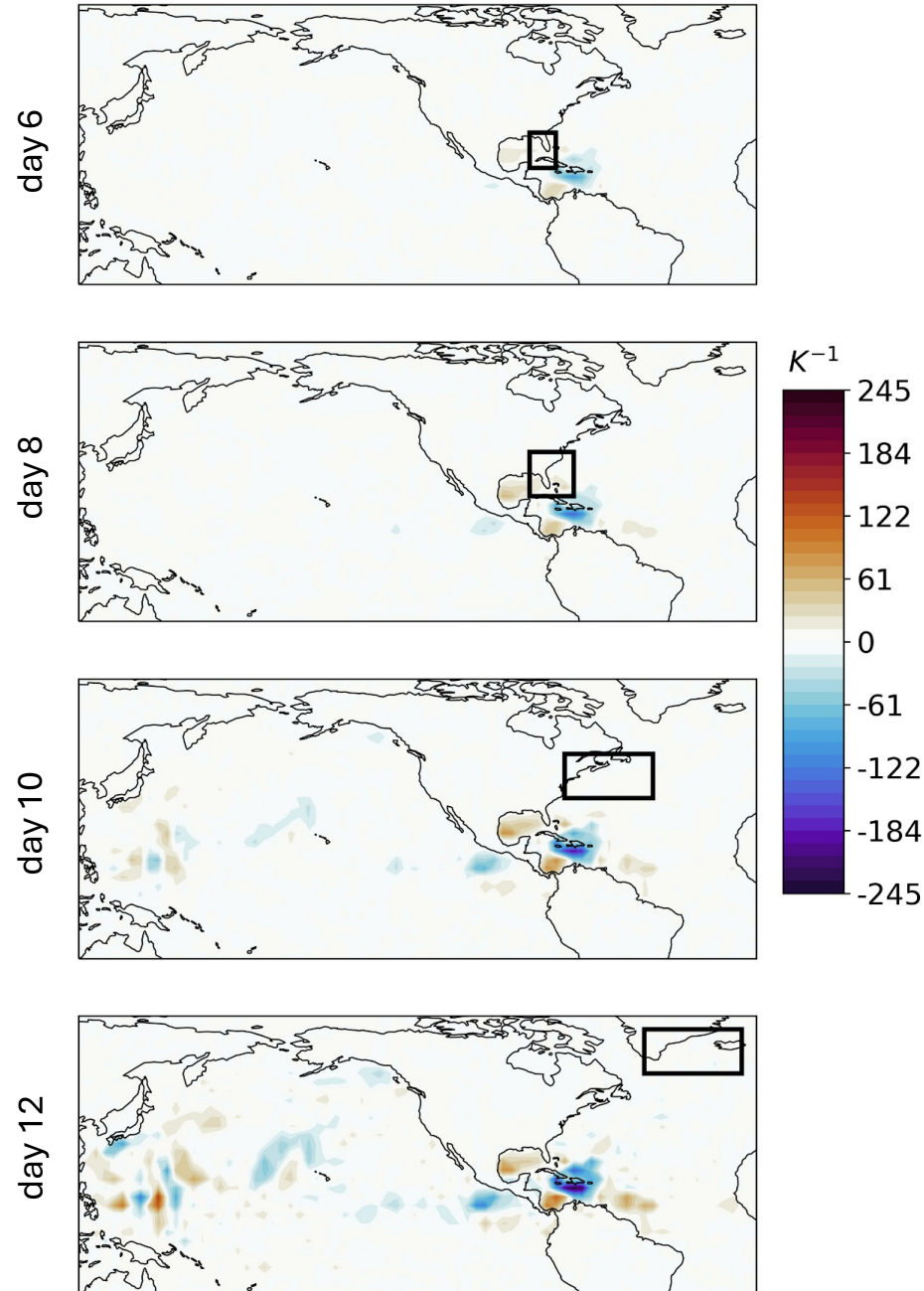


day 12



Plot:  $\frac{\partial E}{\partial U_{500}}(t = 0)$

## SENSITIVITY TO SURFACE TEMPERATURES

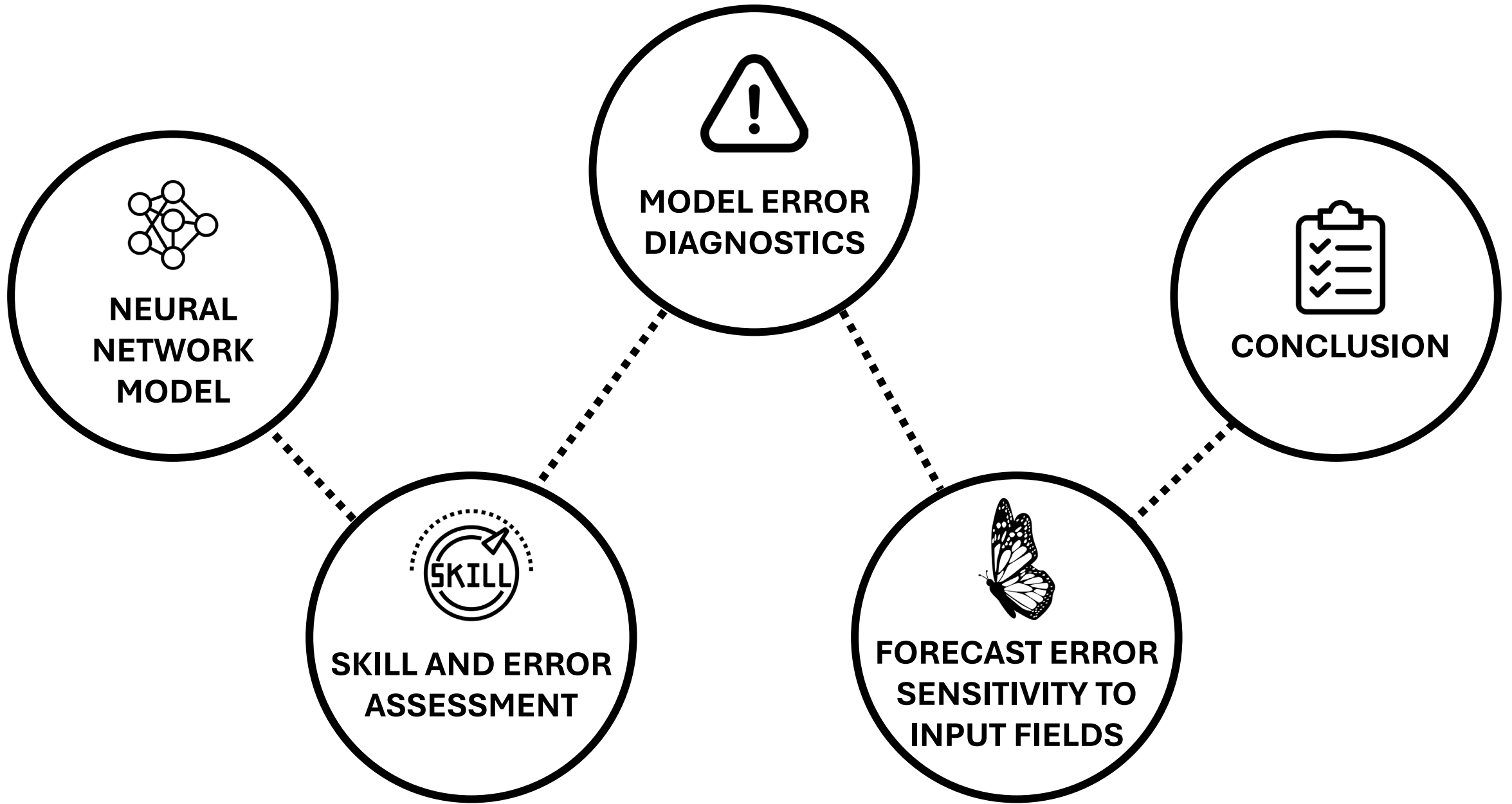


- In order to improve the forecast of hurricane Ian's tropical-to-extratropical transition we should improve initial condition at sensitive regions – especially at the Caribbean and the Bay of Mexico.

Plot:  $\frac{\partial E}{\partial ST}(t = 0)$

# POSSIBLE USE IN WEATHER PREDICTION

- Determine regions where more measurements are needed to decrease forecast uncertainty at later times
- Error calculation: use ensemble model spread as a proxy for model error
- **Pros** 😊:
  - Sensitivity is calculated using a fully nonlinear model (instead of an adjoint model – which is valid for a limited amount of time)
- **Cons** 😞:
  - We assume the perfect model





**CONCLUSION**



**CONCLUSION**

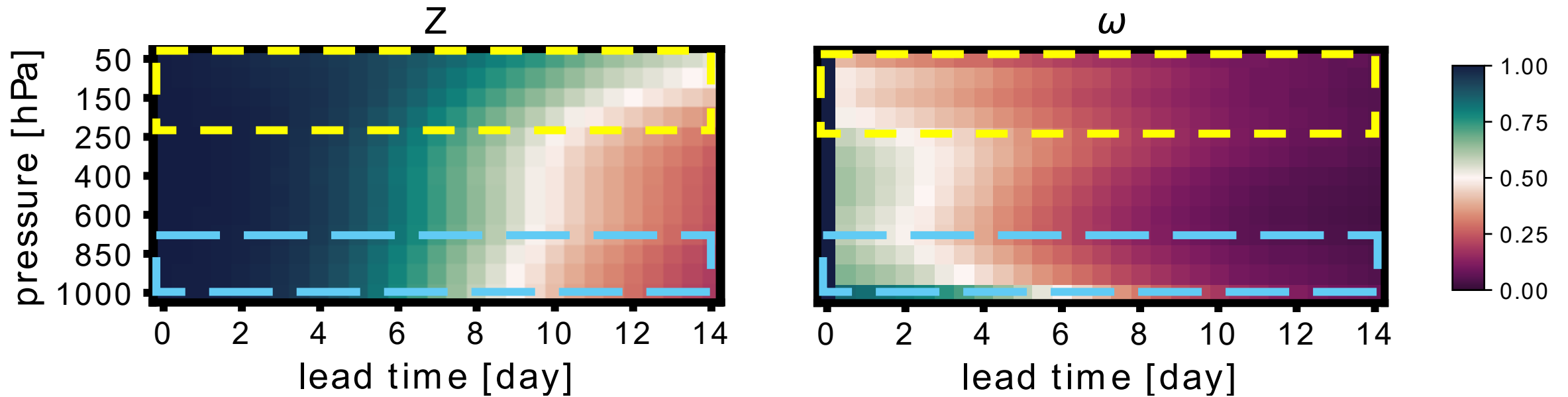


# CONCLUSION

1. Regional overwriting of model forecast with the „truth“ is a simple yet efficient way for ML model error diagnostics
2. Error backpropagation could be a useful tool for:
  - Physical consistency evaluation
  - Improving initial conditions

The full analysis will be published soon.

## ACC at different lead times and pressure levels

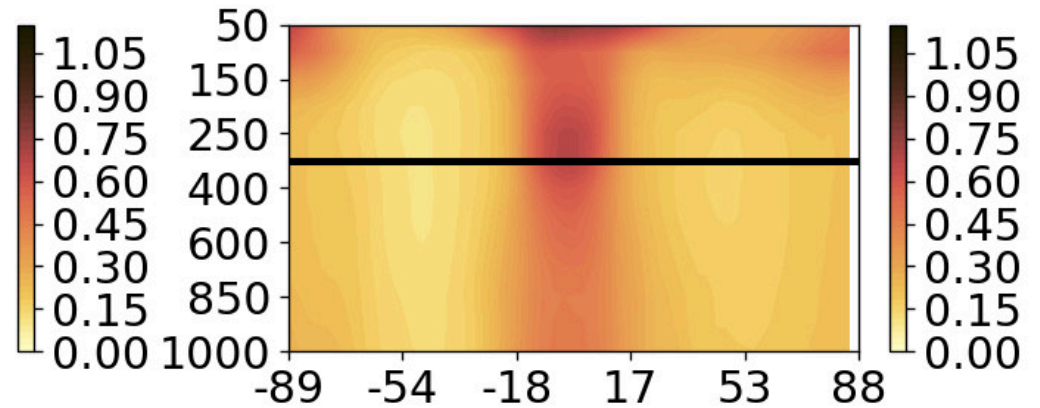
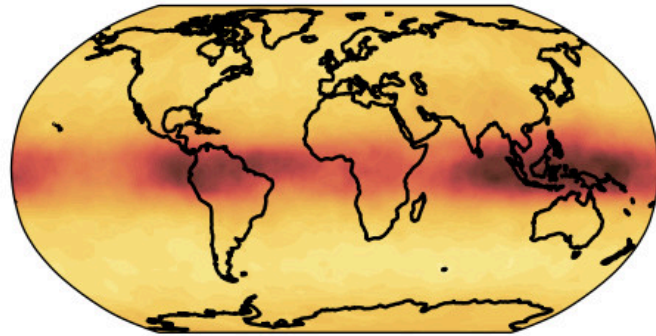


3 distinct predictability regimes:

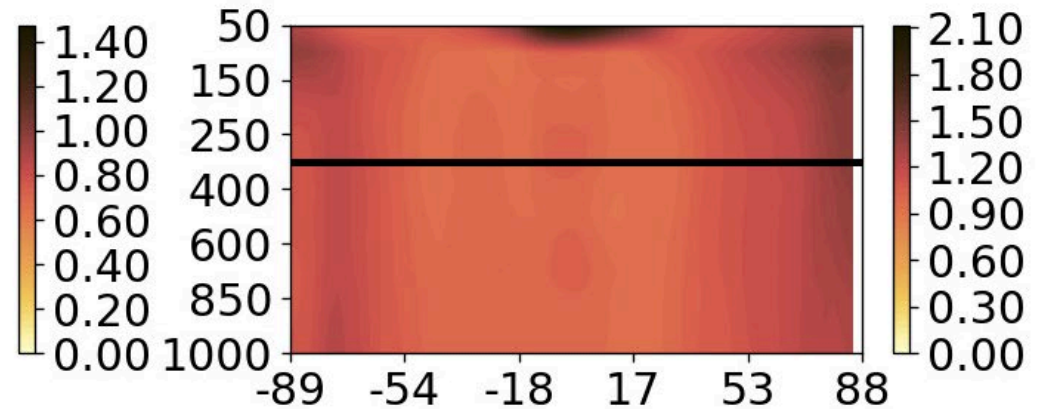
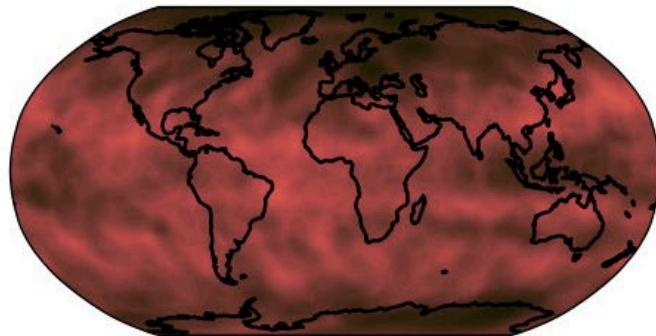
- Stratosphere
- Free troposphere
- „Planetary boundary layer“

# LEAD TIME DIFFERENCE

Z: lead day 2



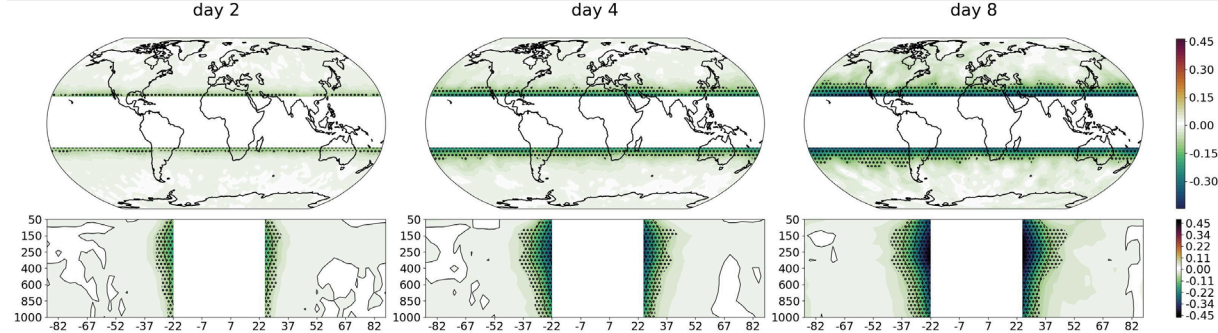
Z: lead day 10



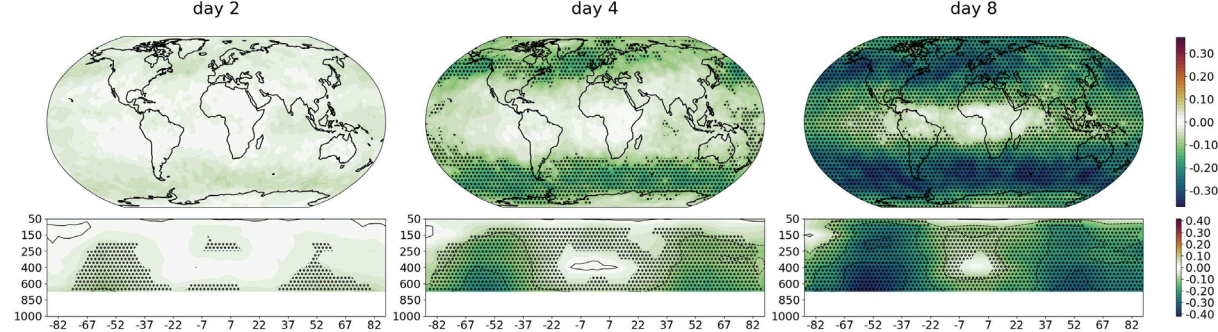
Lead day 10 normalised error difference:

- Mid-to-high latitude errors become prevailing
- Stratospheric errors become more prominent

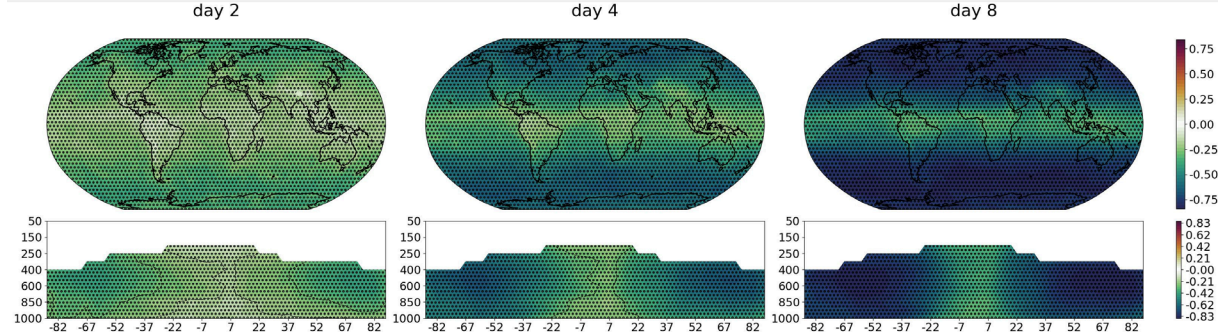
a) Tropics



b) Boundary layer



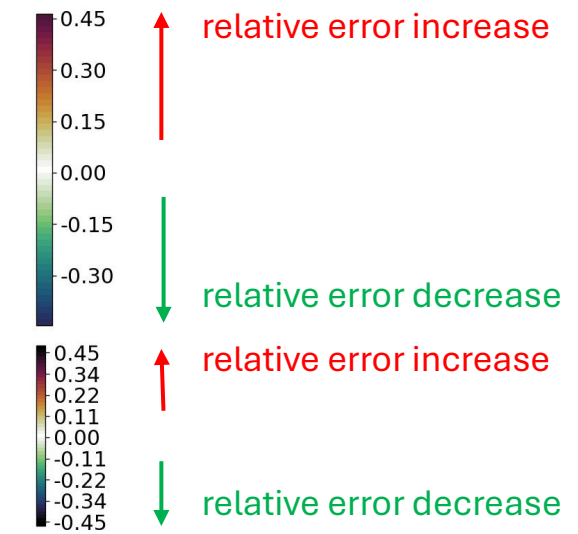
c) Stratosphere



Plot:

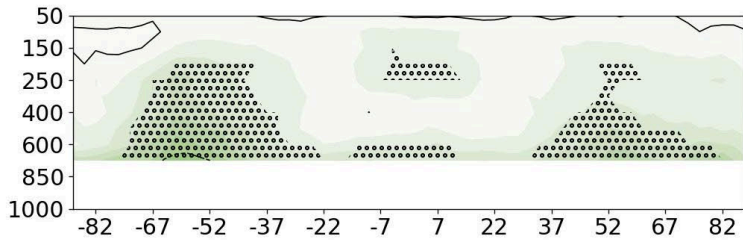
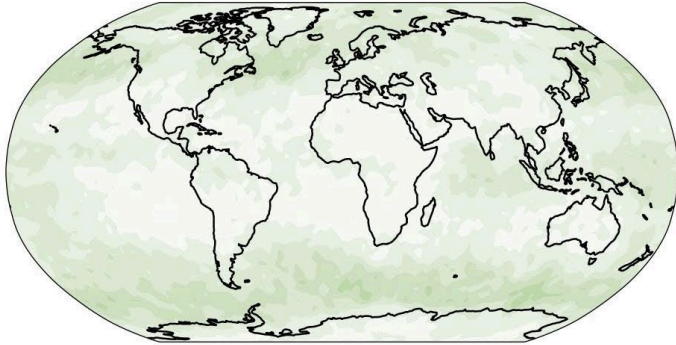
- Vertically and zonally averaged relative temperature error comparison

$$1 - \frac{\text{error}(M(x))}{\text{error}(M(x_{forced}))}$$

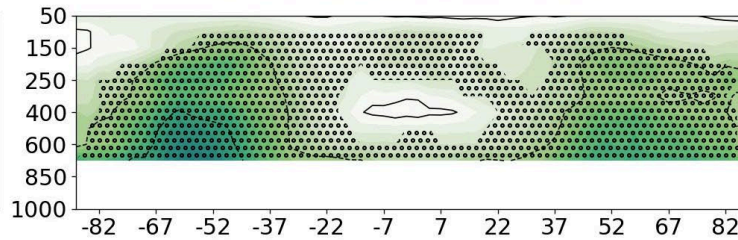
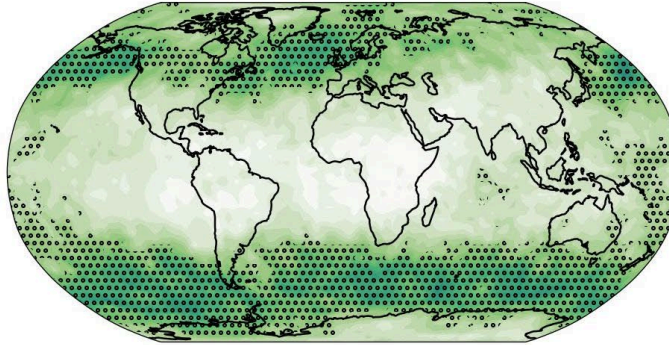


## b) Boundary layer

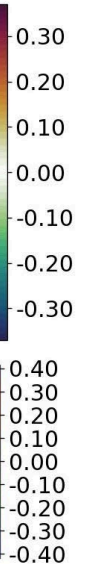
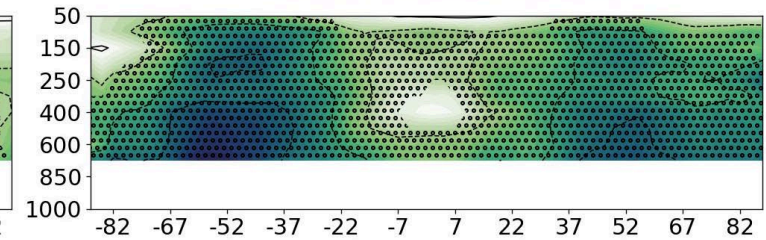
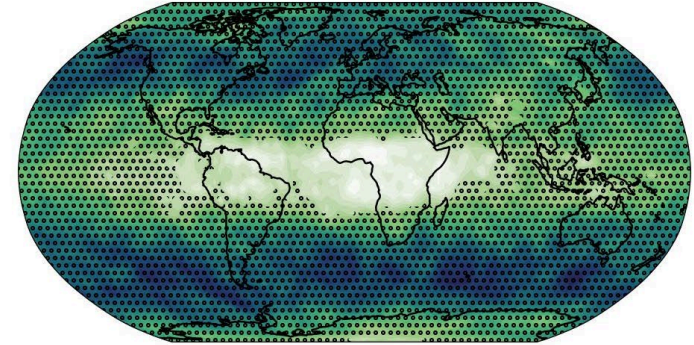
day 2



day 4



day 8



- Statistically significant improvements spread with time:
  - Starting from mid-latitude 850 hPa ERA5 boundary
  - Surrounding tropical mid-troposphere
  - Reaching stratosphere after lead day 4
- Big improvements in mid-latitudes

# MODEL FORCING METHODOLOGY

autoregressive input field

ERA5 „truth“ term

Model forecast term

$$x(\lambda, \varphi, p, t + \Delta t) = \text{weight}_\tau(\lambda, \varphi, p) \cdot \text{ERA5}(\lambda, \varphi, p, t + \Delta t) + (1 - \text{weight}_\tau(\lambda, \varphi, p)) \cdot \mathcal{M}_{t \rightarrow t + \Delta t}(s(t))(\lambda, \varphi, p)$$

Vertical weights equation:  $\text{weight}_p = \frac{1}{2} \tanh \frac{p-p_0}{\Delta p} + \frac{1}{2}$

Latitude weights equation:  $\text{weight}_\varphi = \frac{1}{2} \tanh \frac{\varphi - \varphi_{\min}}{\Delta \varphi} - \frac{1}{2} \tanh \frac{\varphi - \varphi_{\max}}{\Delta \varphi} + 1$

# FORECAST ERROR

Sum over predetermined domain

Standardized ERA5 fields

Standardized input fields

$$\text{error} = \sum_{\lambda, \varphi, p \in \mathcal{D}} | \mathcal{S}(\text{ERA5}(\lambda, \varphi, p, t + \Delta t)) - \mathcal{M}_{t \rightarrow t + \Delta t}(s(t))(\lambda, \varphi, p) |$$

$$\frac{\partial \text{error}}{\partial s(t)} = \sum_{\lambda, \varphi, p \in \mathcal{D}} \text{sgn} \left[ \mathcal{S}(\text{ERA5}(\lambda, \varphi, p, t + \Delta t)) - \mathcal{M}_{t \rightarrow t + \Delta t}(s(t))(\lambda, \varphi, p) \right] \frac{\partial \mathcal{M}_{t \rightarrow t + \Delta t}(s(t))(\lambda, \varphi, p)}{\partial s(t)}$$

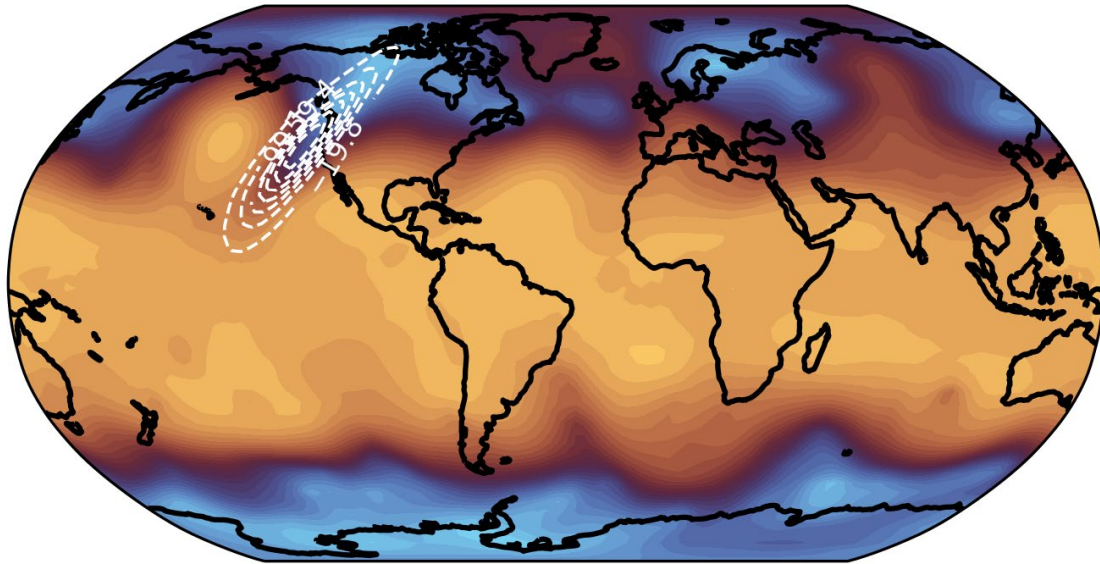
Error derivative with respect to standardized input fields

Sign function

Diferentiation of the model with respect to standardized input fields

# ADJUSTMENT EXPERIMENTS

Z500 initial condition perturbation

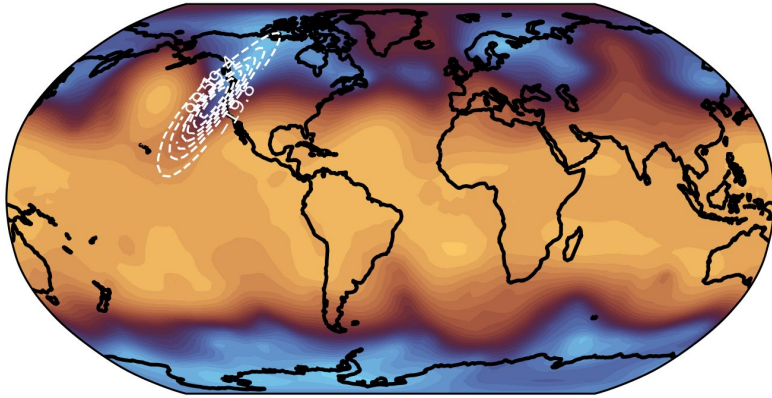


Goal:

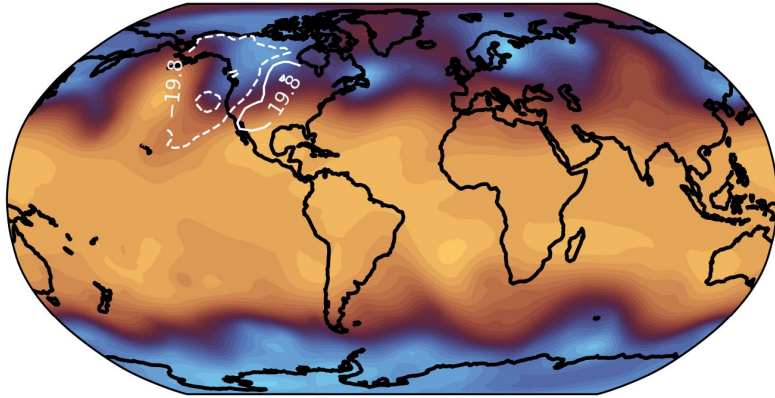
- Compare model response with dynamics expectations
- ML models not so sensitive to instability  
=> easy to initialize forecast



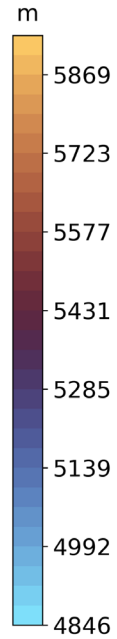
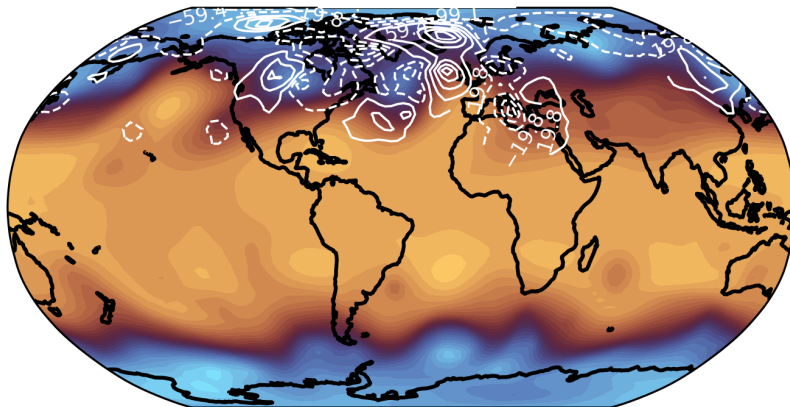
day 0



day 1



day 6



Propagation features:

- Propagates downstream
- Faster than Rossby wave phase speed
- Confined to Northern Hemisphere for first 6 forecast days