

# Coupling Earth System Model Components using the Atlas library

Workshop on surface process coupling and its  
interactions with the atmosphere

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Destination Earth

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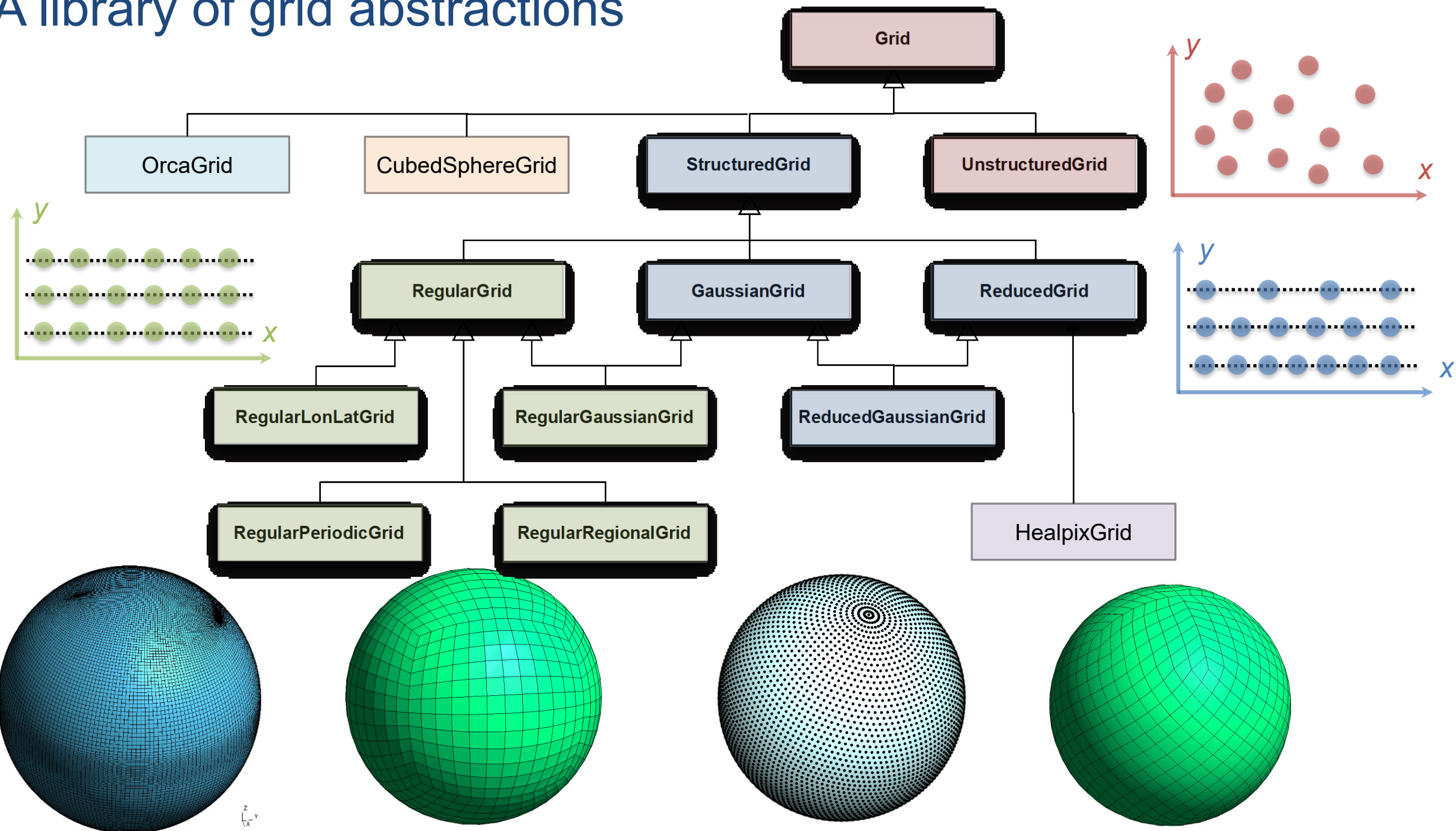


## Atlas, a library for NWP and climate modelling – *Deconinck et al. 2017, J-CPC*

- Open source (Apache 2) : [github.com/ecmwf/atlas](https://github.com/ecmwf/atlas)
- Data structures to enable **new numerical algorithms**, e.g. based on unstructured meshes
  - Support structured and unstructured grids
  - Support **global** as well as **regional** grids
  - Grids with projections
- Separation of concerns
  - Grids / Mesh generation
  - Parallelisation (domain decomposition, halo exchanges)
  - Accelerator-aware data structures (GPU/CPU/...)
- Readily available operators
  - Remapping and interpolation
  - Gradient, divergence, laplacian
  - Spherical Harmonics transforms



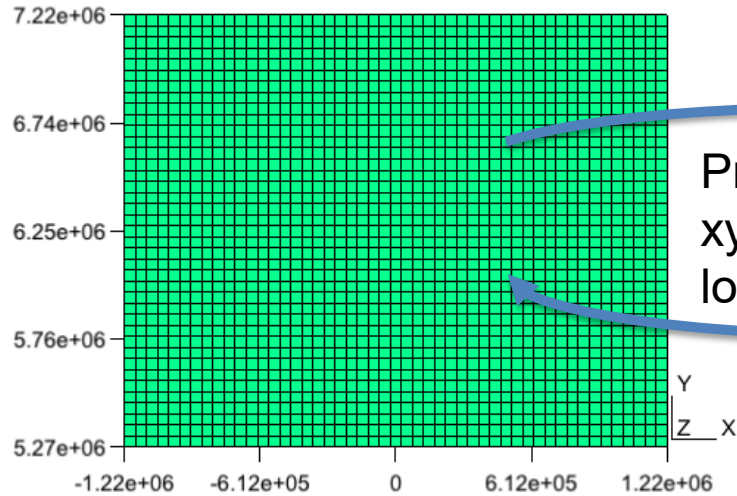
# A library of grid abstractions



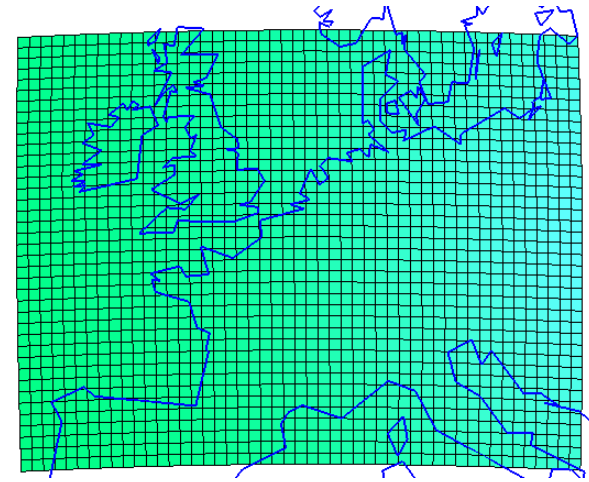
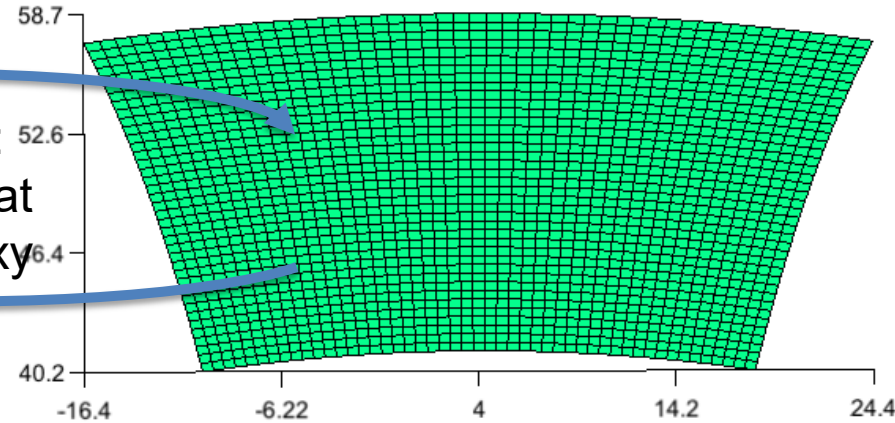
# Support for Projections and regional grids

## Grid coordinates

Lambert projection → metres



## Geographic coordinates (degrees)



## Grid creation:

```
Grid grid ( "O1280" );
```

Sample of grid identifiers:

O1280

octahedral reduced gaussian grid

H256

healpix grid

eORCA12\_T

extended ORCA 1/12 deg ocean grid, T arrangement

## Grid iteration:

Grid coordinates (x,y)

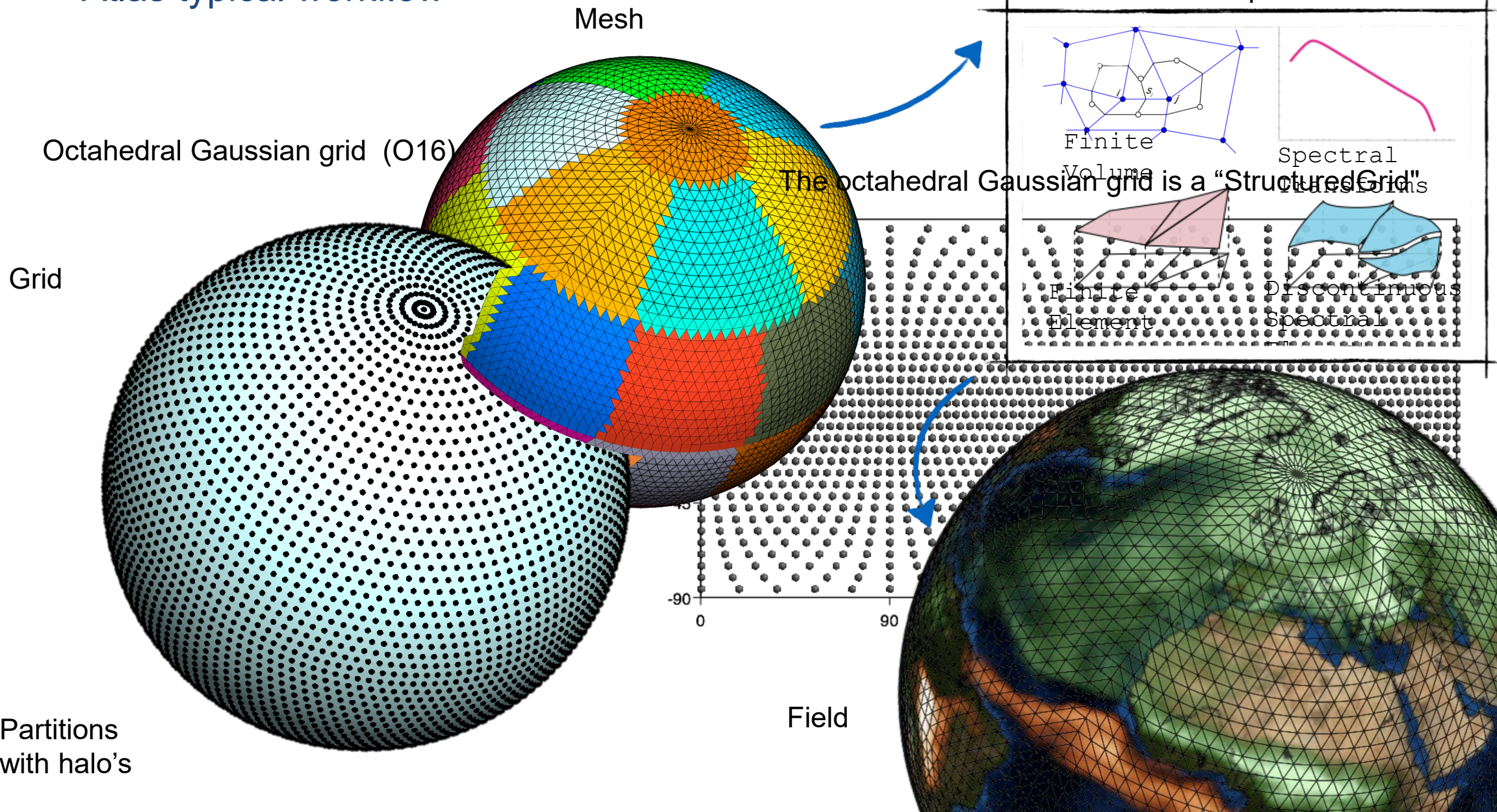
```
for( PointXY p : grid.xy() ) {  
    double x = p.x();  
    double y = p.y();  
}
```

Geographic coordinates (lon,lat)

```
for( PointLonLat p : grid.lonlat() ) {  
    double lon = p.lon();  
    double lat = p.lat();  
}
```



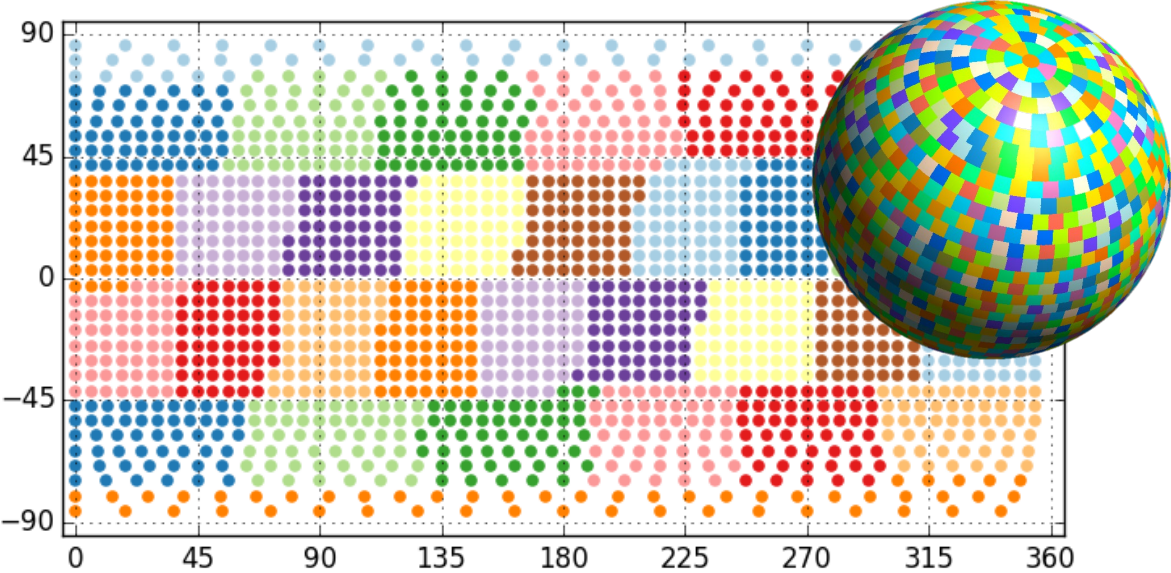
# Atlas typical workflow



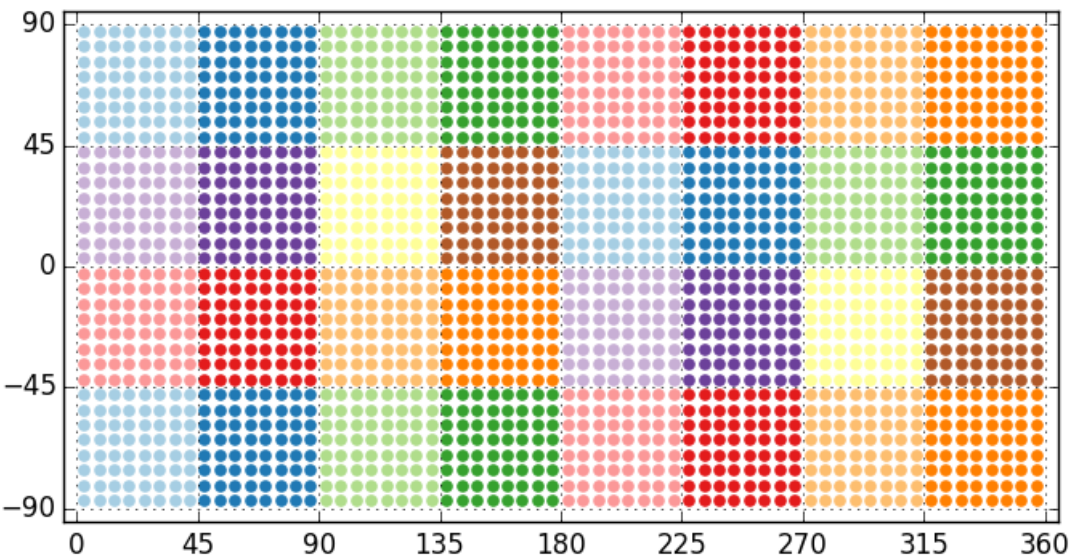


# Multiple domain decomposition strategies

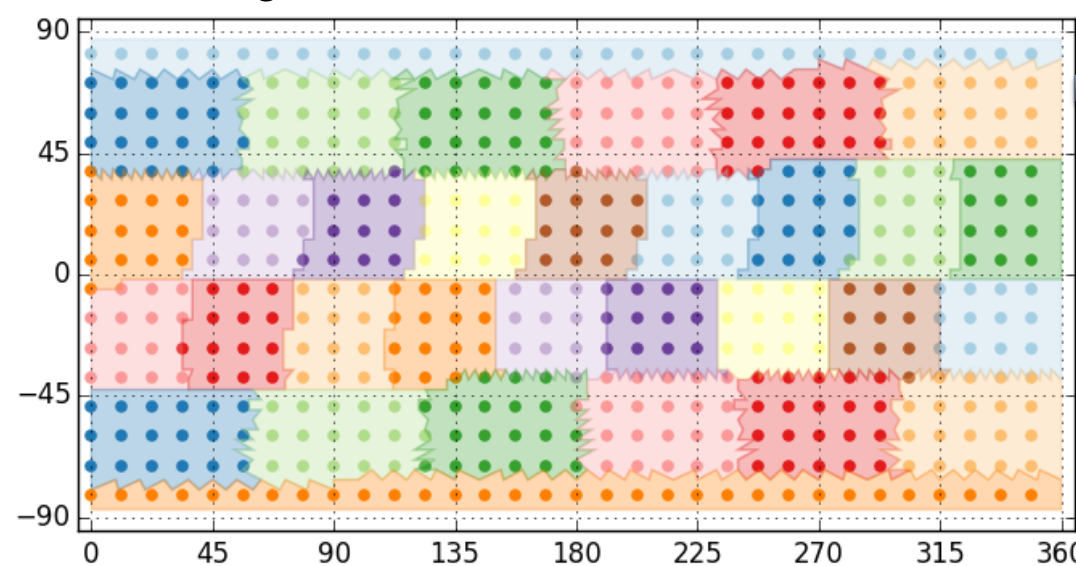
Equal Regions ( typical for IFS grids )



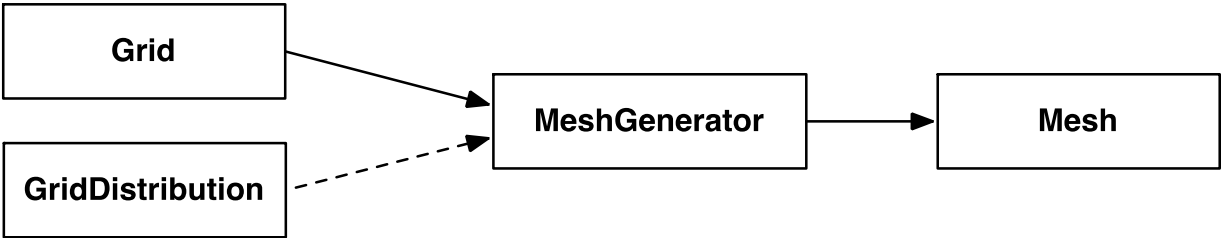
Checkerboard ( typical for regional grids )



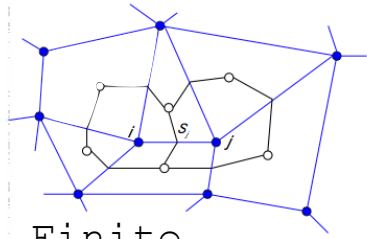
Matching



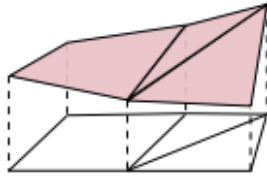
Any grid can follow the domain decomposition of an already distributed mesh or function space



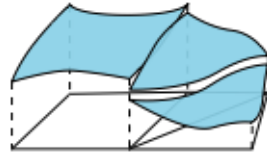
# FunctionSpaces: Discretisation specific knowledge



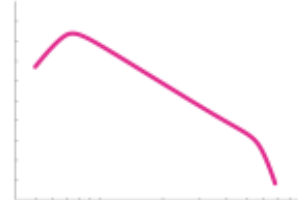
Finite  
Volume



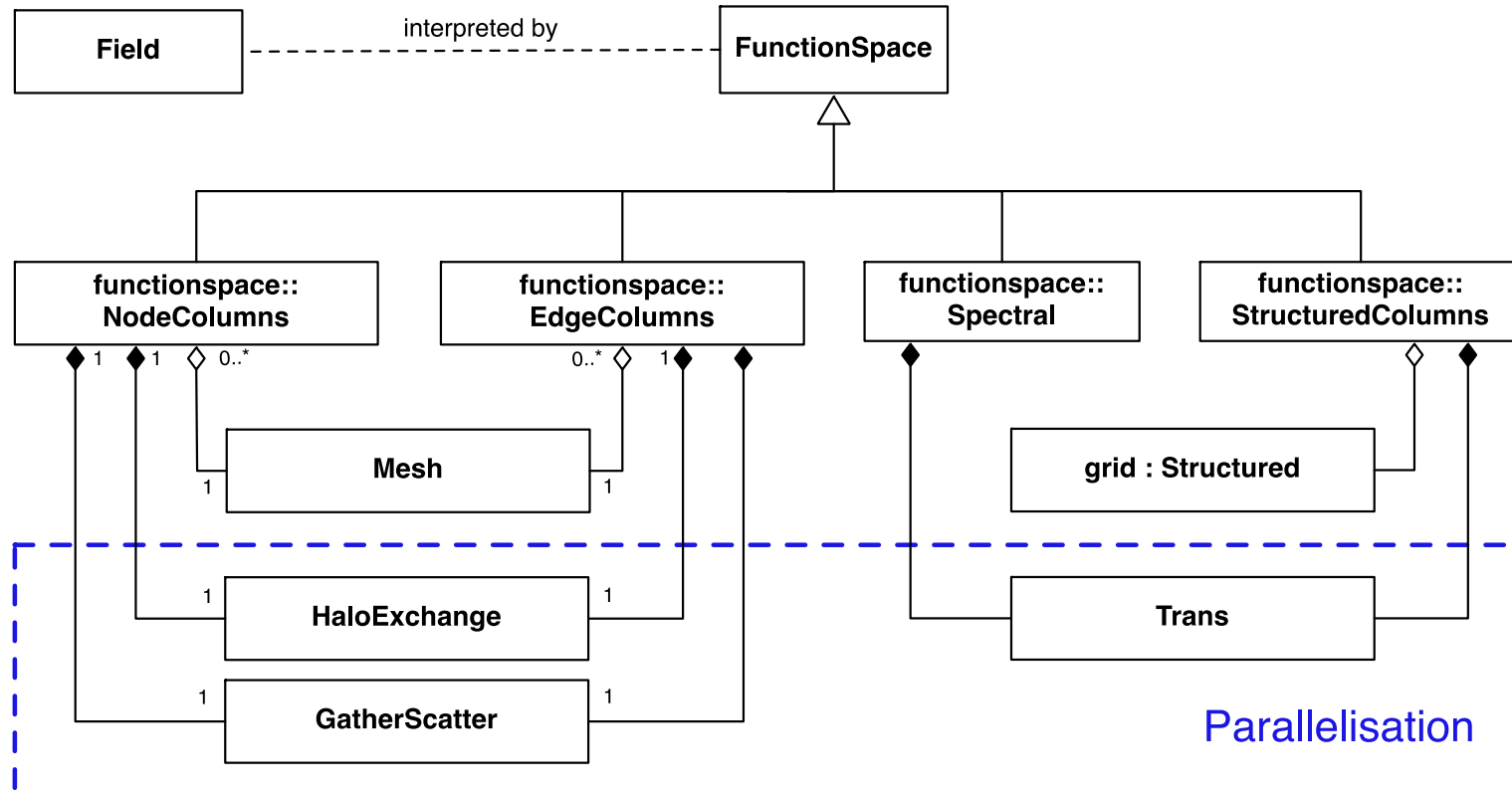
Finite  
Element



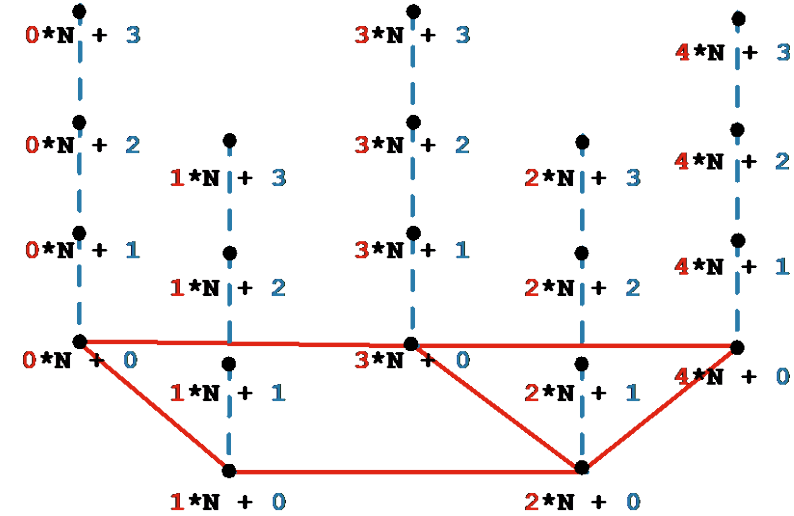
Discontinuous  
Spectral  
Element



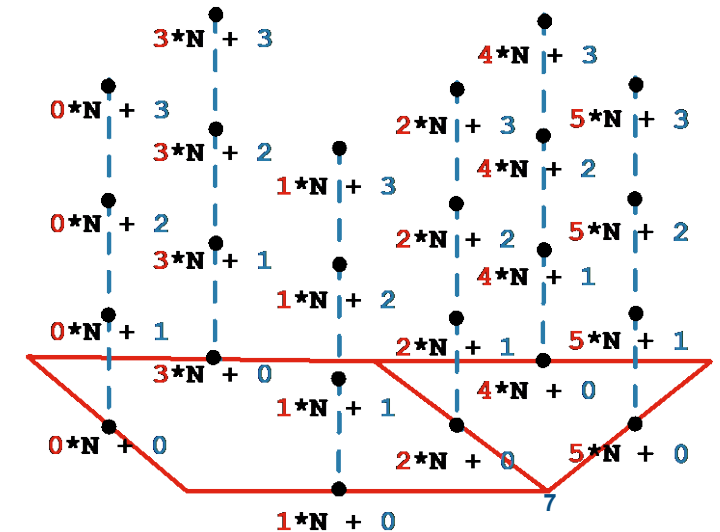
Spectral  
Transforms



NodeColumns



EdgeColumns



# Interpolation

Interpolators can be setup with two functionspaces: for source and target:

```
Interpolation interpolation( configuration, source_functionspace, target_functionspace);
```

Atlas provides a number of interpolation methods

“structured”: bilinear, quasicubic, cubic

- Meshless, for structured grids (functionspace=StructuredColumns)
- Matches IFS semi-lagrangian interpolation schemes
- Computed in lonlat coordinates.

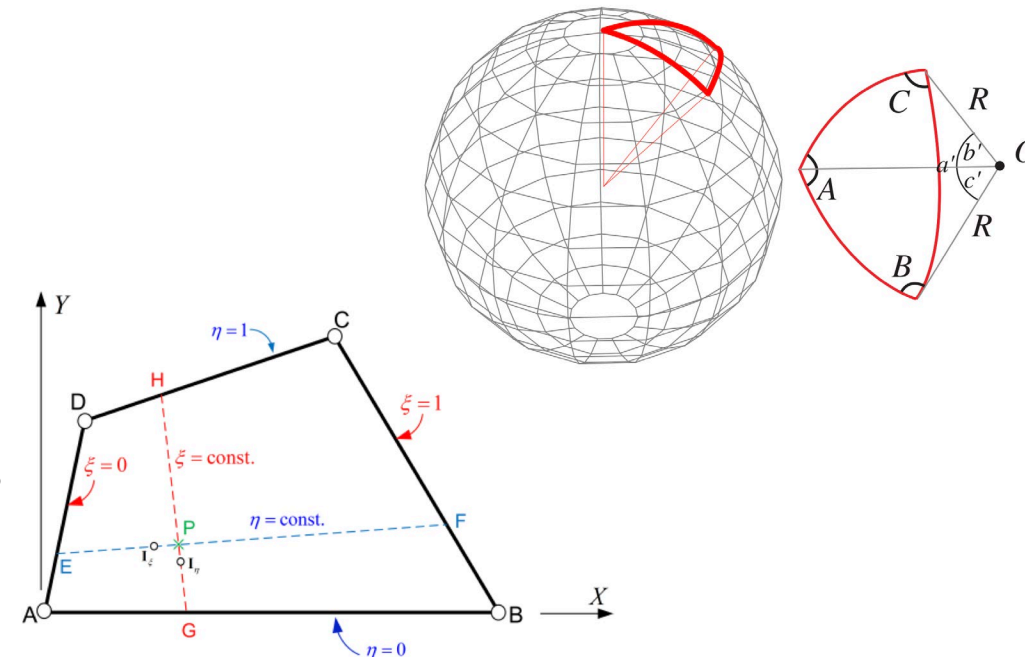
```
j0 : i0----i1---+i2----i3
      |
j1 : i0---i1---+i2---i3
      *P
j2 : i0----i1---+i2----i3
      |
j3 : i0---i1---+i2---i3
```

“finite-element”:

- Requires mesh (functionspace=NodeColumns)
- Find point in spherical elements, and use linear interpolation
- Computed in 3D coordinates

“unstructured-bilinear-lonlat”:

- Follows “finite-element” approach but adapted to match NEMO’s bilinear interpolation method
- Computed in lonlat coordiantes





# Interpolation

## “(k-) nearest neighbour”:

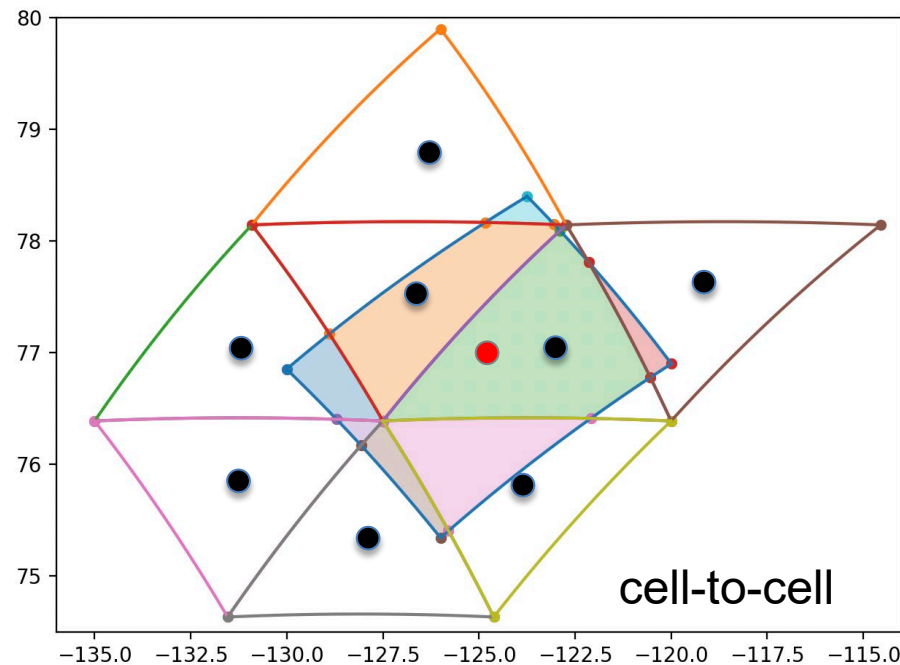
- Meshless, kD-tree based. Functionspace=any
- Closest “k” points are collected
- Distance based weighting

## “conservative-spherical-polygon”

- Can be used for unstructured grids
- Conservative with option for 1st and 2nd order accuracy, based on spherical polygon intersections
- Source and target must be mesh-based with convex spherical polygon elements;
- Source and Target values may be either defined as a element-quantity or a node quantity.

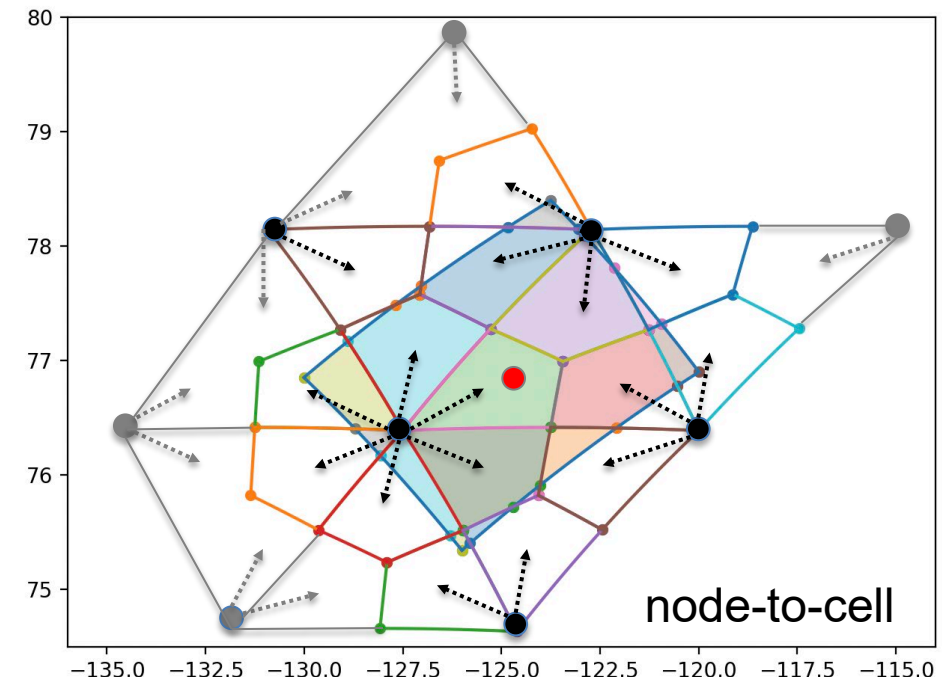
Stencil for  
octahedral to  
healpix grid.

Shaded are the  
intersections that  
form the target cell

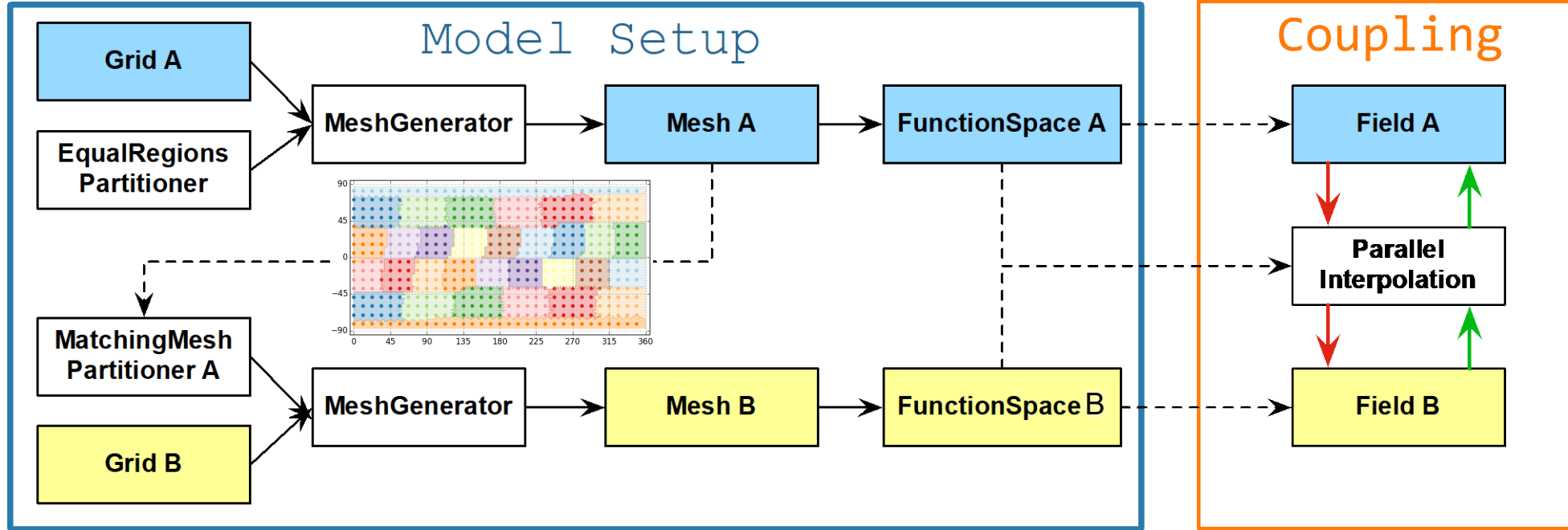


## “grid-box-average”:

- Conservative interpolation
- Source AND target must be a StructuredGrid
- Grid-boxes around source and target grid points are created and intersecting areas are used to compute weights.



# Interpolation using matching domain decompositions



```
grid_A      = atlas_Grid("01280")
partitioner_A = atlas_EqualRegionsPartitioner()
mesh_A      = meshgenerator % generate(grid_A, partitioner_A)
fs_A        = atlas_functionspace_NodeColumns(mesh_A)

grid_B      = atlas_Grid("0640")
partitioner_B = atlas_MatchingMeshPartitioner(mesh_A)
mesh_B      = meshgenerator % generate(grid_B, partitioner_B)
fs_B        = atlas_functionspace_NodeColumns(mesh_B)

interpolation_AB = atlas_Interpolation(type="finite-element",
                                       source=fs_A, target=fs_B)
```

```
call interpolation_AB %
      execute(field_A, field_B)
```

## Caveats:

- Grid A must contain Grid B
- Mesh A must have sufficiently large halos for interpolation stencil computation

# Interpolation with caching

In many instances computing the interpolation stencils and weights is costly, especially for high-resolution grids and limited parallelisation. This cost can be reduced when optionally using caching.

## 1. Write cache

- Create interpolator, which contains a partitioned interpolation matrix on each MPI rank
- Extract and gather global interpolation matrix to 1 MPI rank (mpi\_root)
- Write global interpolation matrix with 1 MPI rank (mpi\_root)

```
Interpolation interpolator(config, source, target);  
  
InterpolationMatrix global_matrix = assemble_interpolation_matrix(interpolation, mpi_root);  
  
write_interpolation_matrix("interpolation_matrix.dat", global_matrix, mpi_root);
```

## 2. Create interpolator using cache

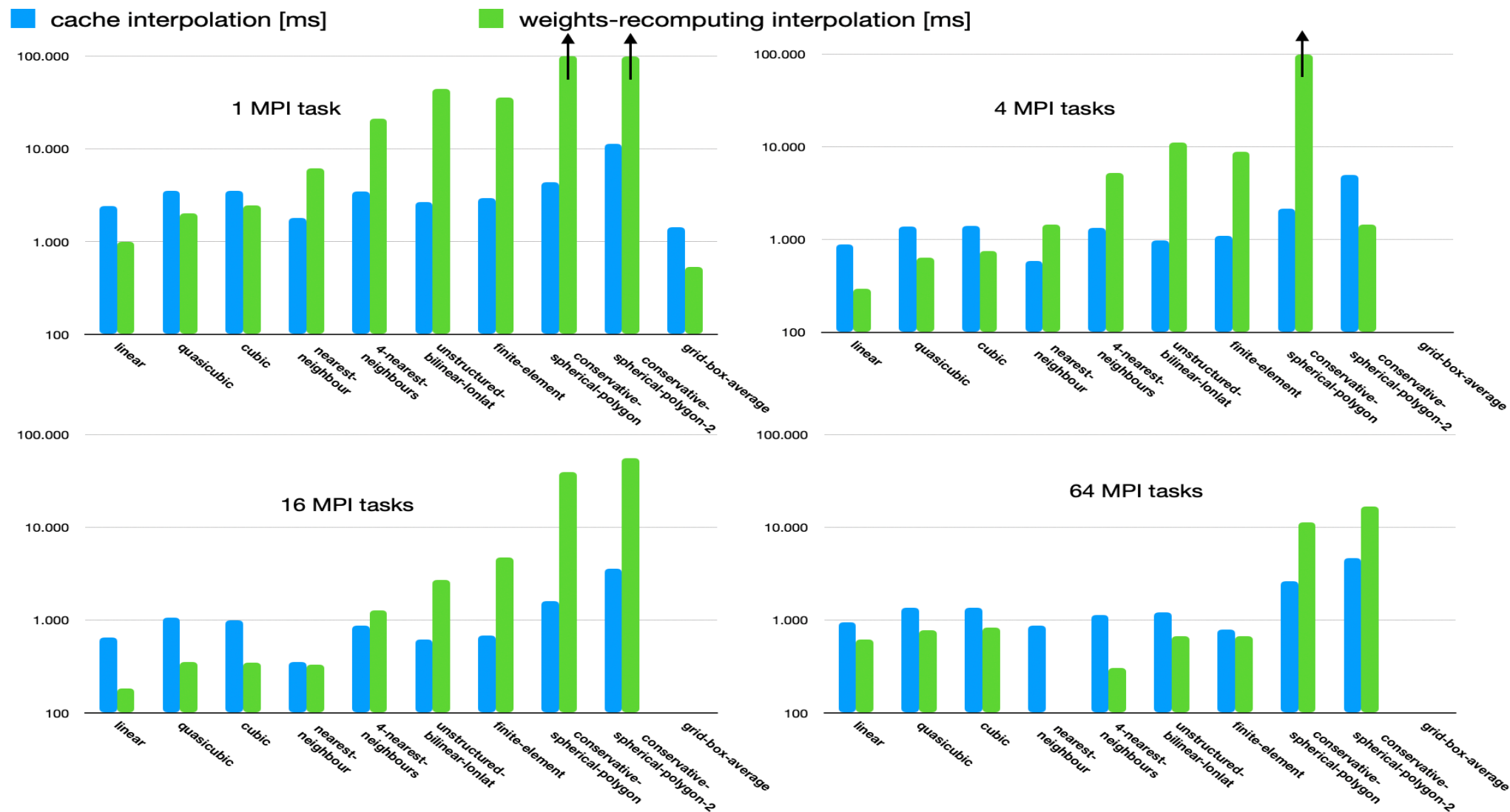
- Read global interpolation matrix with 1 MPI rank (mpi\_root)
- Distribute global interpolation matrix to partitioned interpolation matrices on each MPI rank
- Create interpolator but use already provided matrix

```
InterpolationMatrix global_matrix = read_interpolation_matrix("interpolation_matrix.dat", mpi_root);  
  
InterpolationMatrix matrix = distribute_interpolation_matrix(global_matrix, source, target);  
  
Interpolation interpolator (config, source, target, matrix);
```



# Interpolation with caching

Various timings and speed-ups can be reported. For some methods, like structured interpolation methods, weight and stencil computations are very fast, and caching does not increase performance. Reading and distributing matrix also costs!

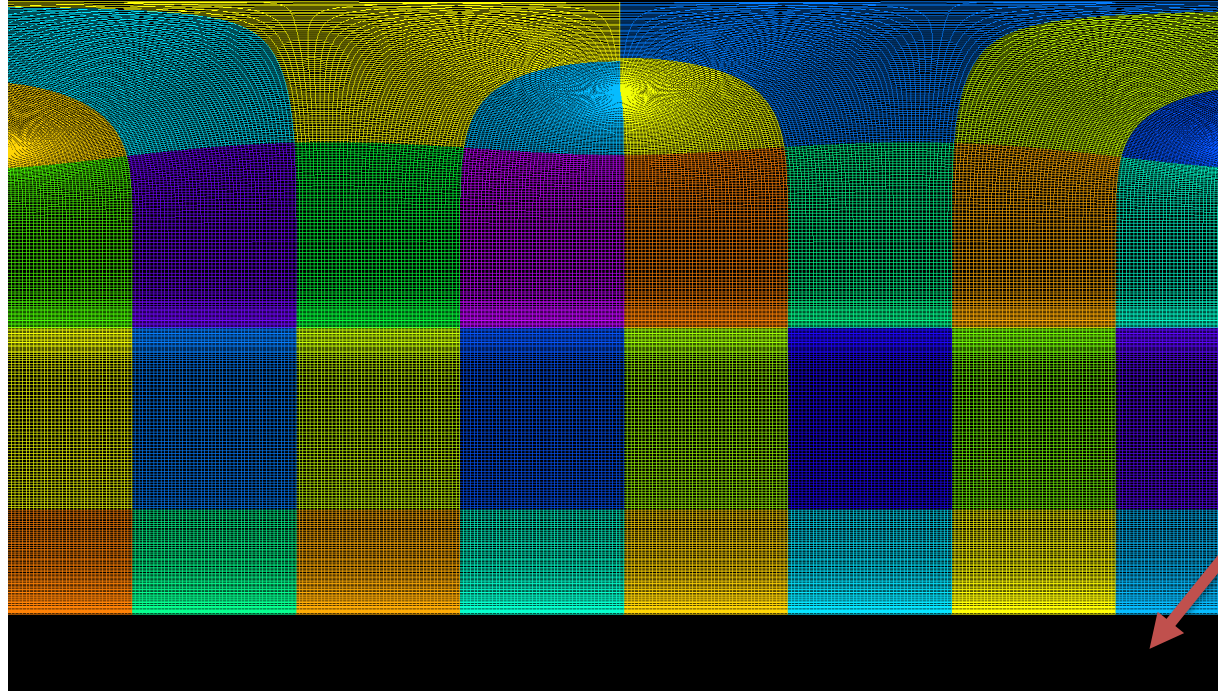


## Benefits using Matching partitioner

1. Interpolation weights are computed in parallel, staying within each MPI rank
2. Source fields may only require a halo-exchange → minimum parallel communication

## Drawbacks

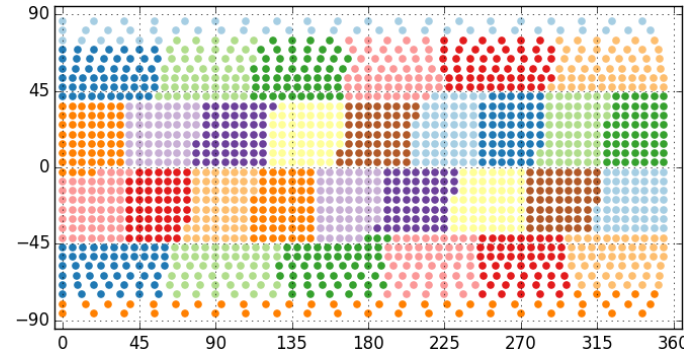
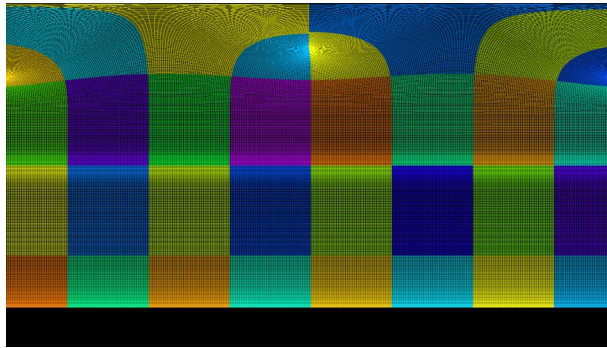
1. Possibly very large and sometimes unknown source halo requirements (e.g. conservative interpolation)
2. In general model components use their own domain decomposition matching the numerics and grid best
3. ORCA grid does not span entire globe.  
ORCA to Gaussian grid → ERROR: Several Gaussian grid points cannot be assigned a matching partition



Points on target grid that fall here cannot be assigned any partition

# Non-matching domain decomposition

1. Source and Target may have independent domain decomposition



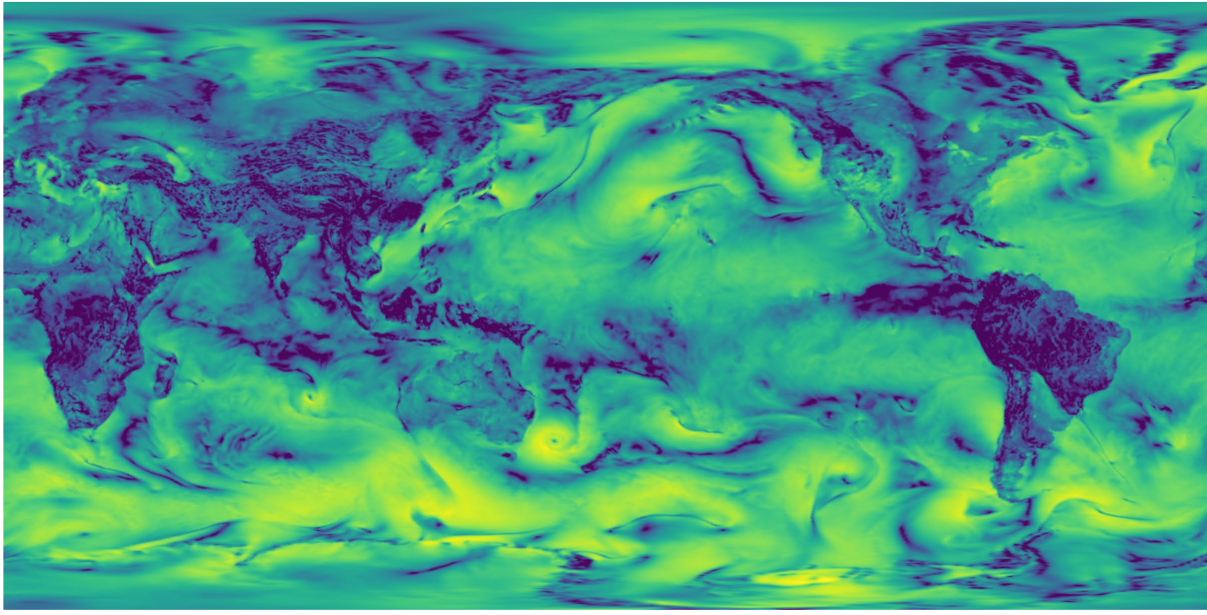
2. No halos are required.
3. Reuse same cached global interpolation matrix described earlier!
4. Distribute the global interpolation matrix to target domain decomposition.
5. Collect information on each target partition on which MPI ranks the source stencils are located, and create a “Collect” communication pattern, which collects source field values from all required MPI ranks to satisfy the interpolation stencils
6. Apply an interpolation operator using the weights and collected source field values

Some interpolation algorithms which only implement computation of interpolation weights in serial may now find use in parallel applications.



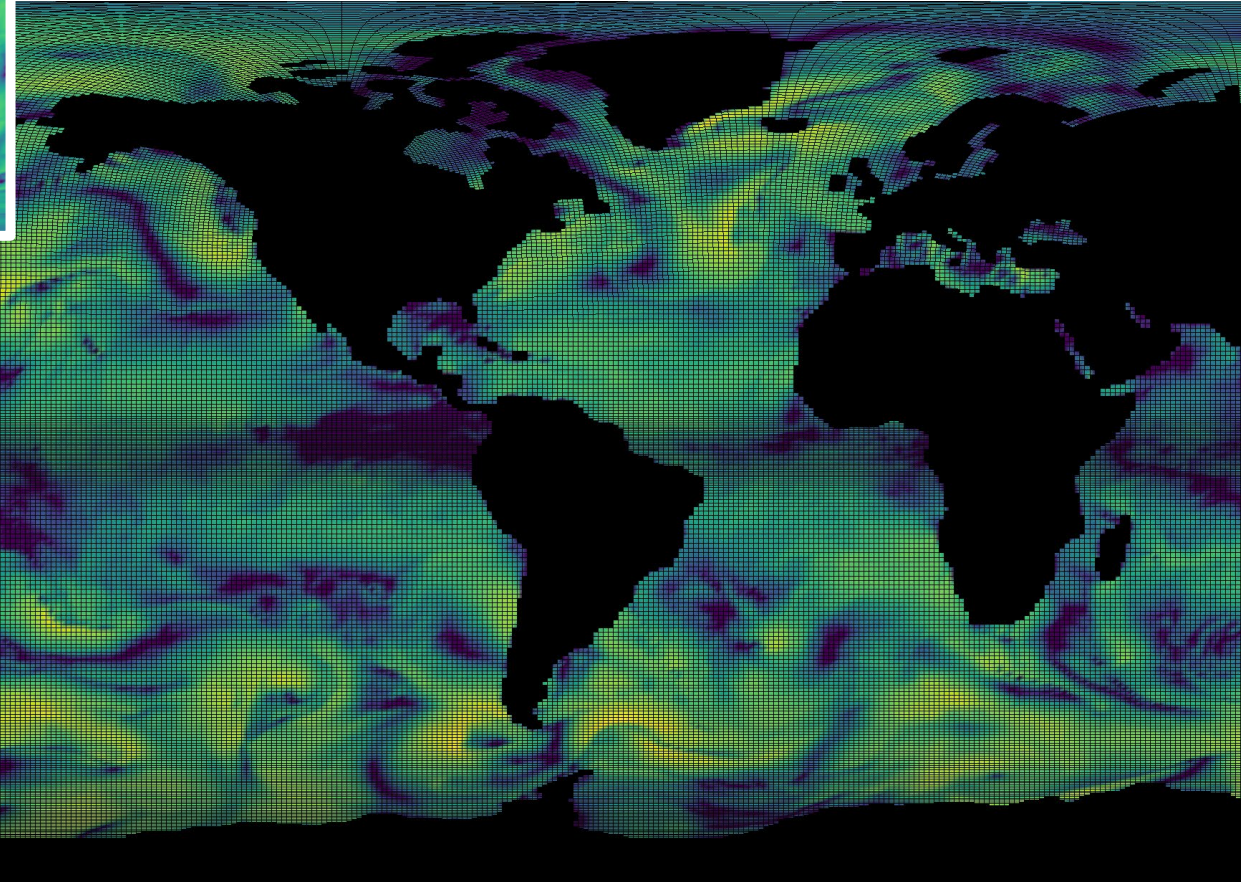
## Example 1: From atmosphere to ocean

Field: 10m wind magnitude, reanalysis 2025.04.01 at 00:00

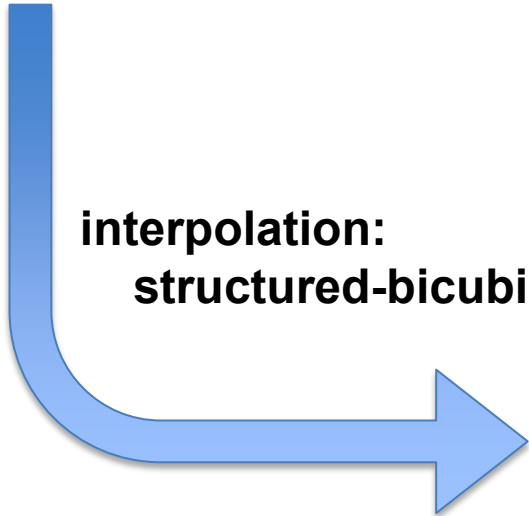


source:  
O360 (0.25 deg)

target: ORCA1\_F



interpolation:  
structured-bicubic

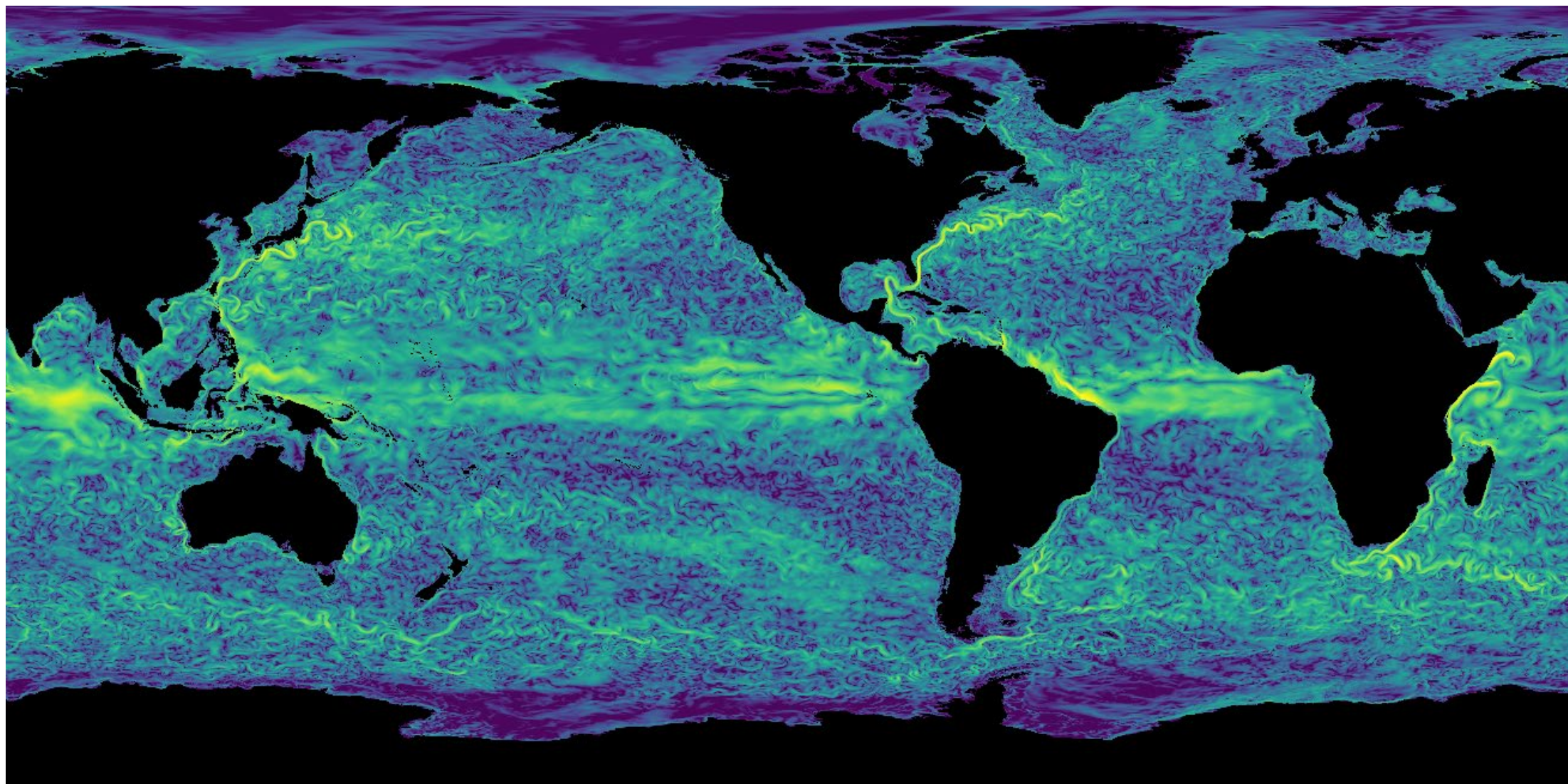




## Example 2: From ocean to atmosphere

IFS CY49R2

TcO1279 atmosphere + eORCA12 ocean



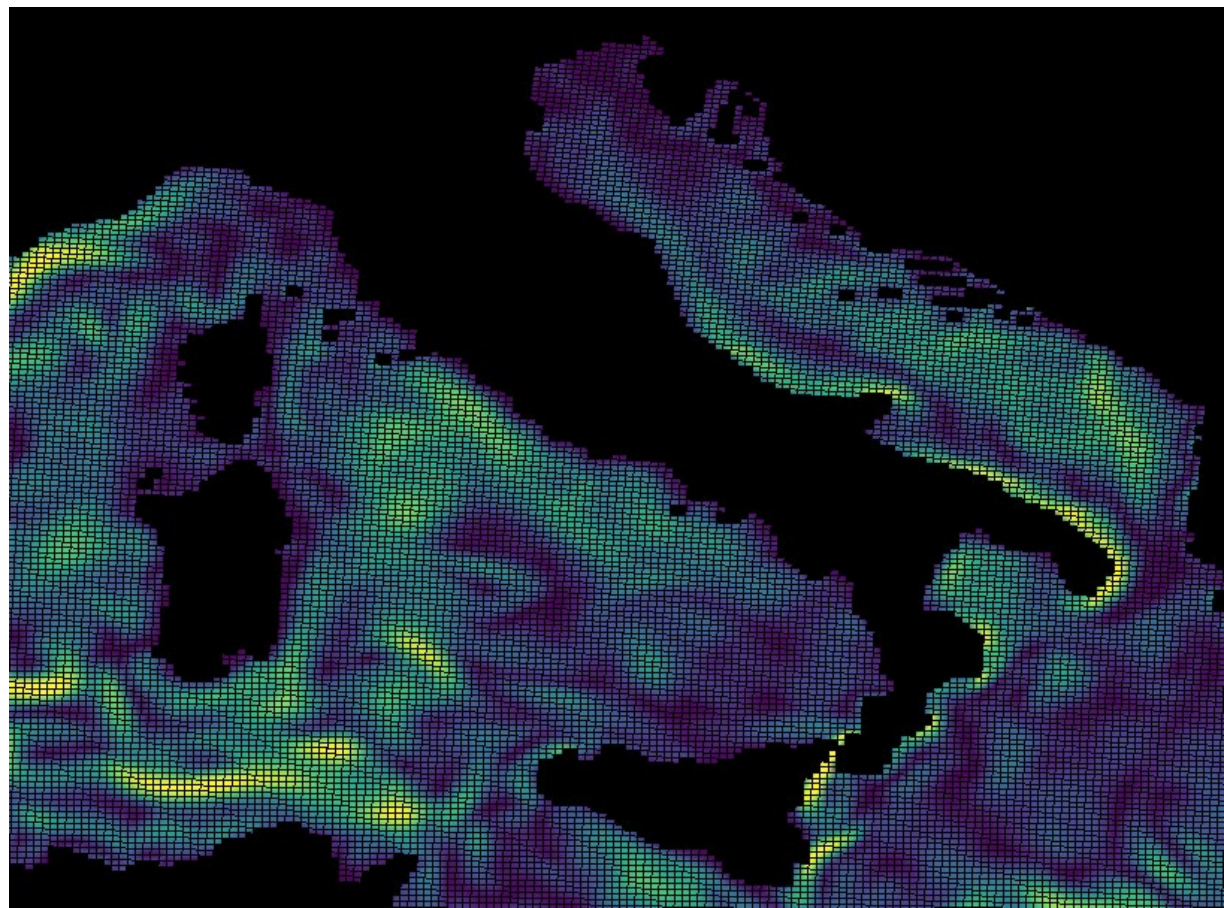
source: eORCA12\_T (1/12 degree)

**Sea velocity magnitude**

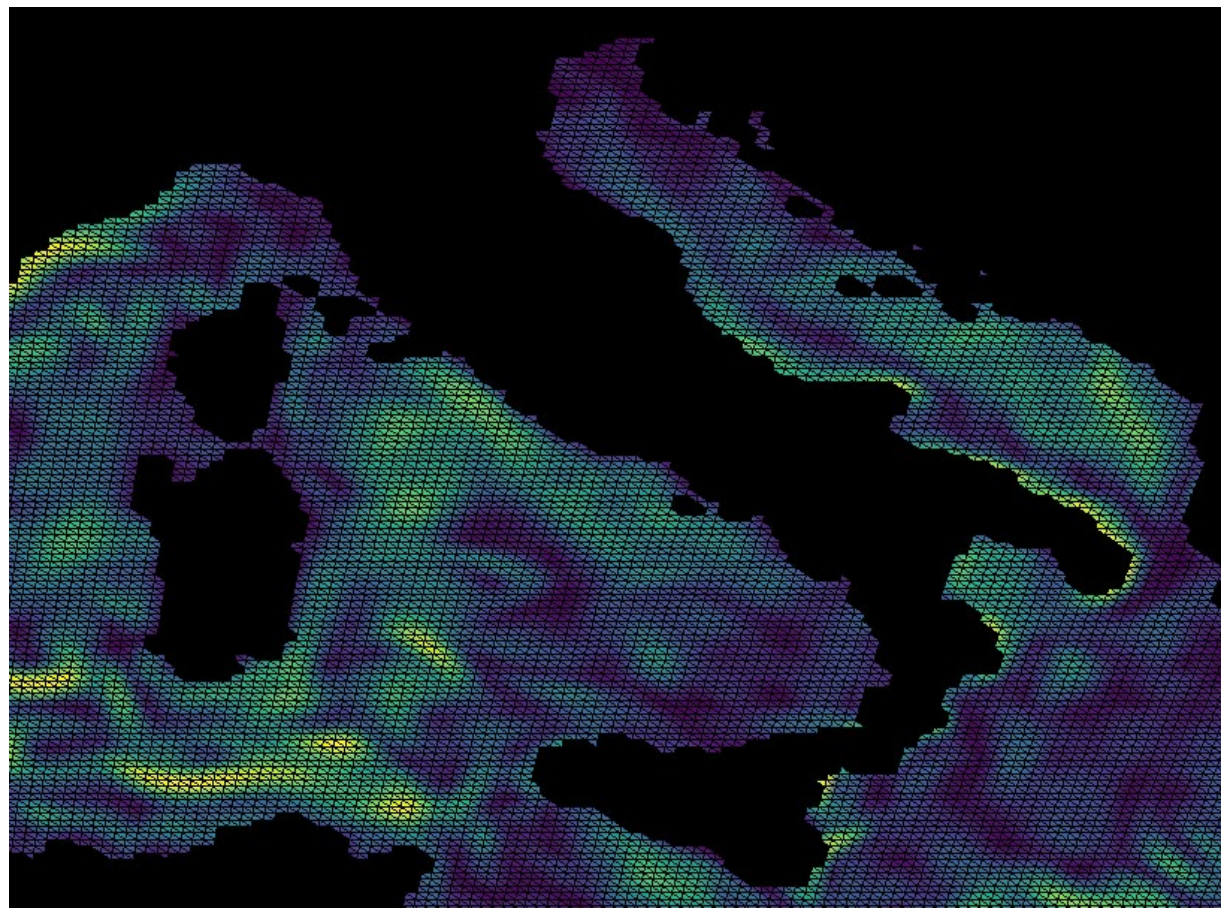


## Example 2: From ocean to atmosphere

**Ocean: eORCA12 (1/12 degree)**



**Atmosphere: O1280 (9km)**



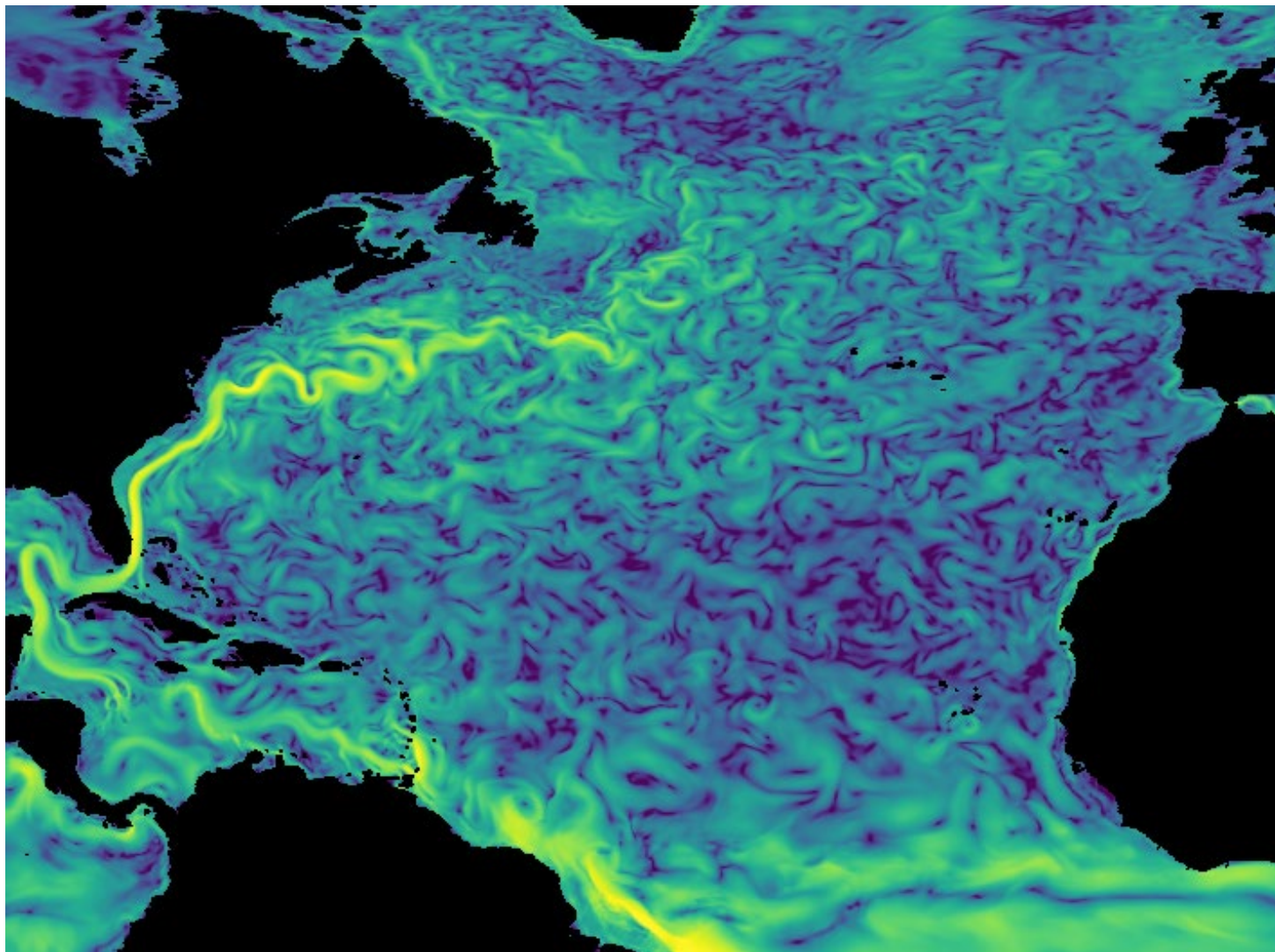
similar in resolution



## Example 2: From ocean to atmosphere

Interpolation method: conservative-spherical-polygon

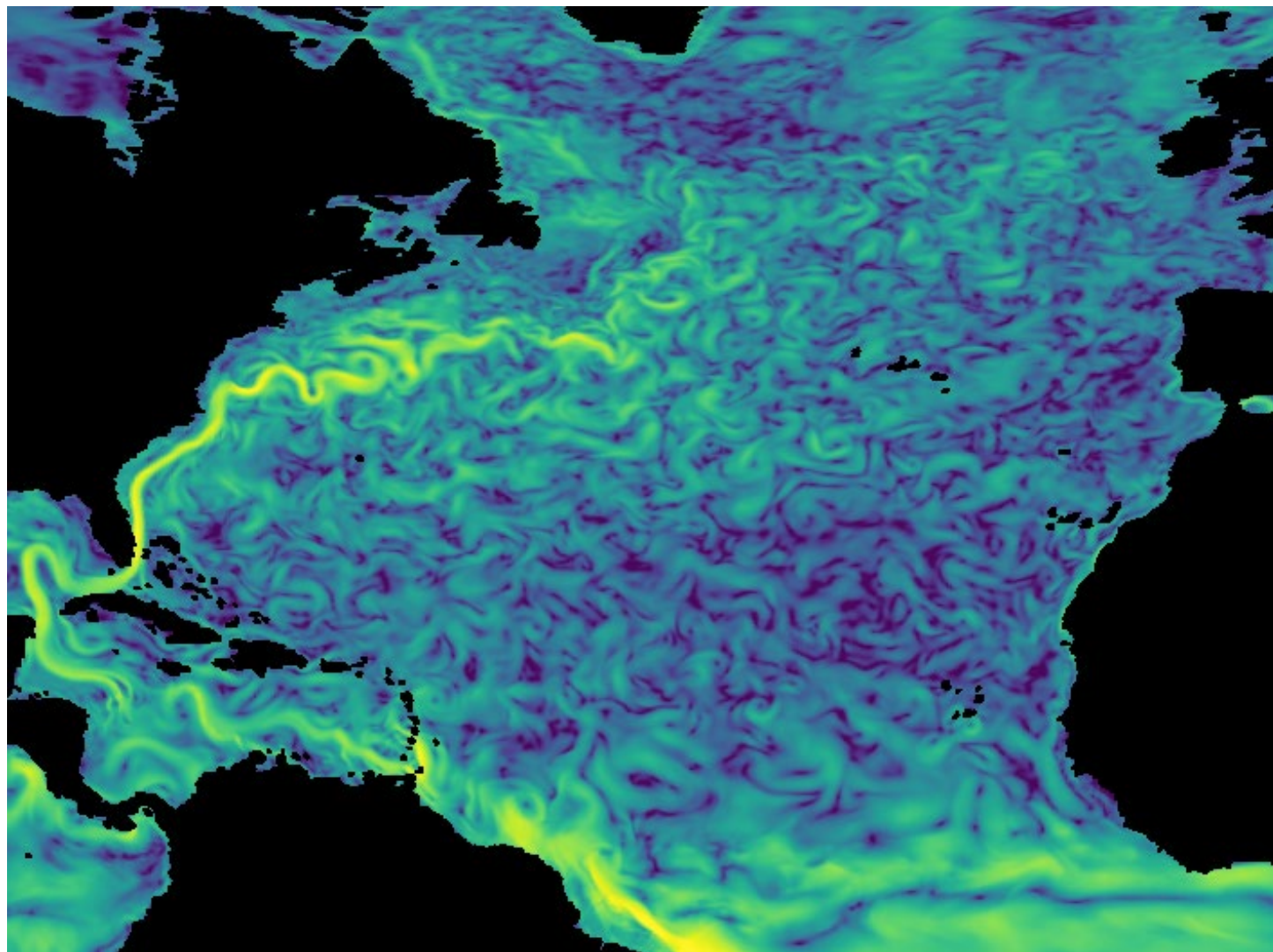
O1280



## Example 2: From ocean to atmosphere

Interpolation method: conservative-spherical-polygon

O640

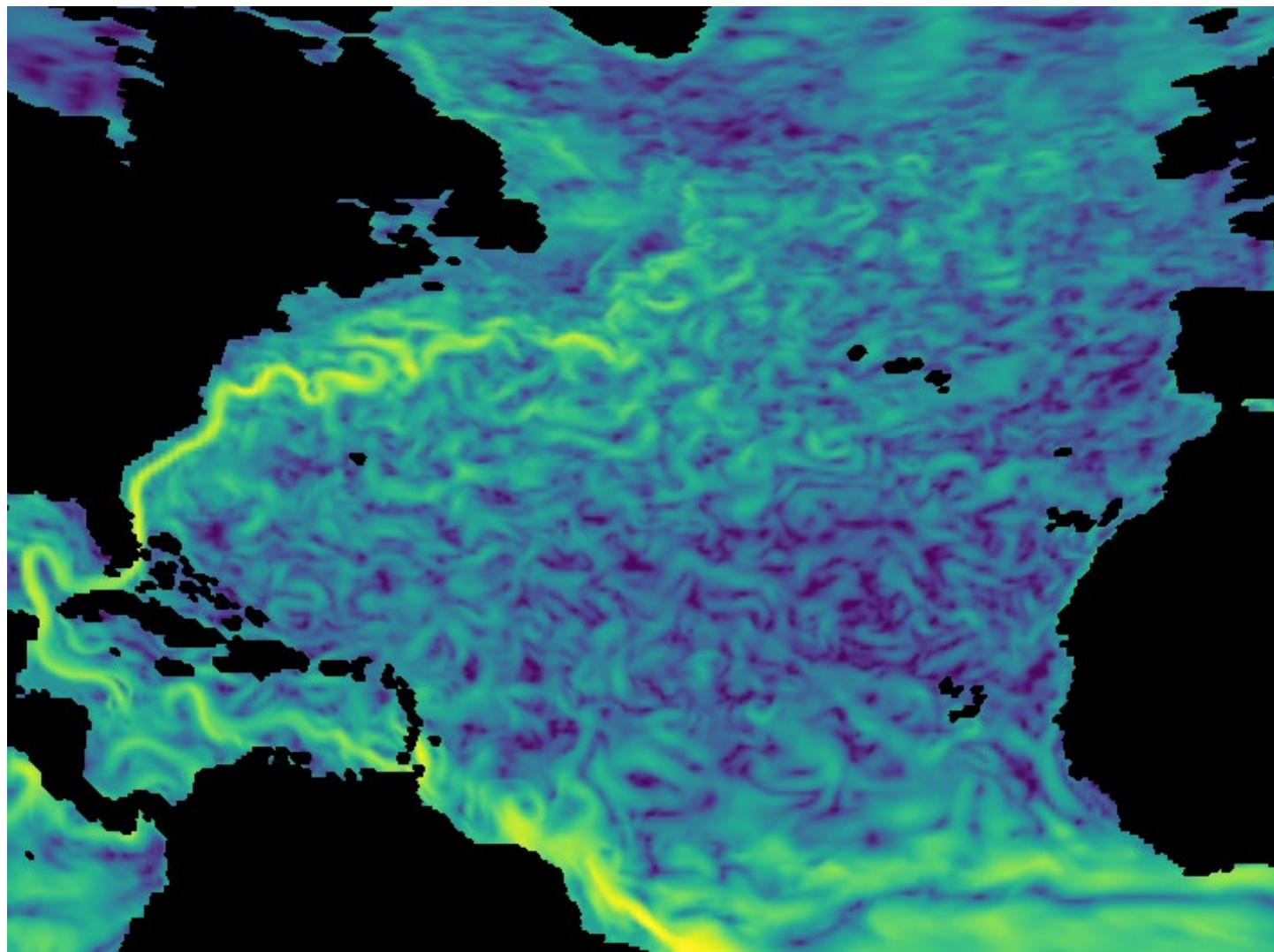




## Example 2: From ocean to atmosphere

Interpolation method: conservative-spherical-polygon

O320

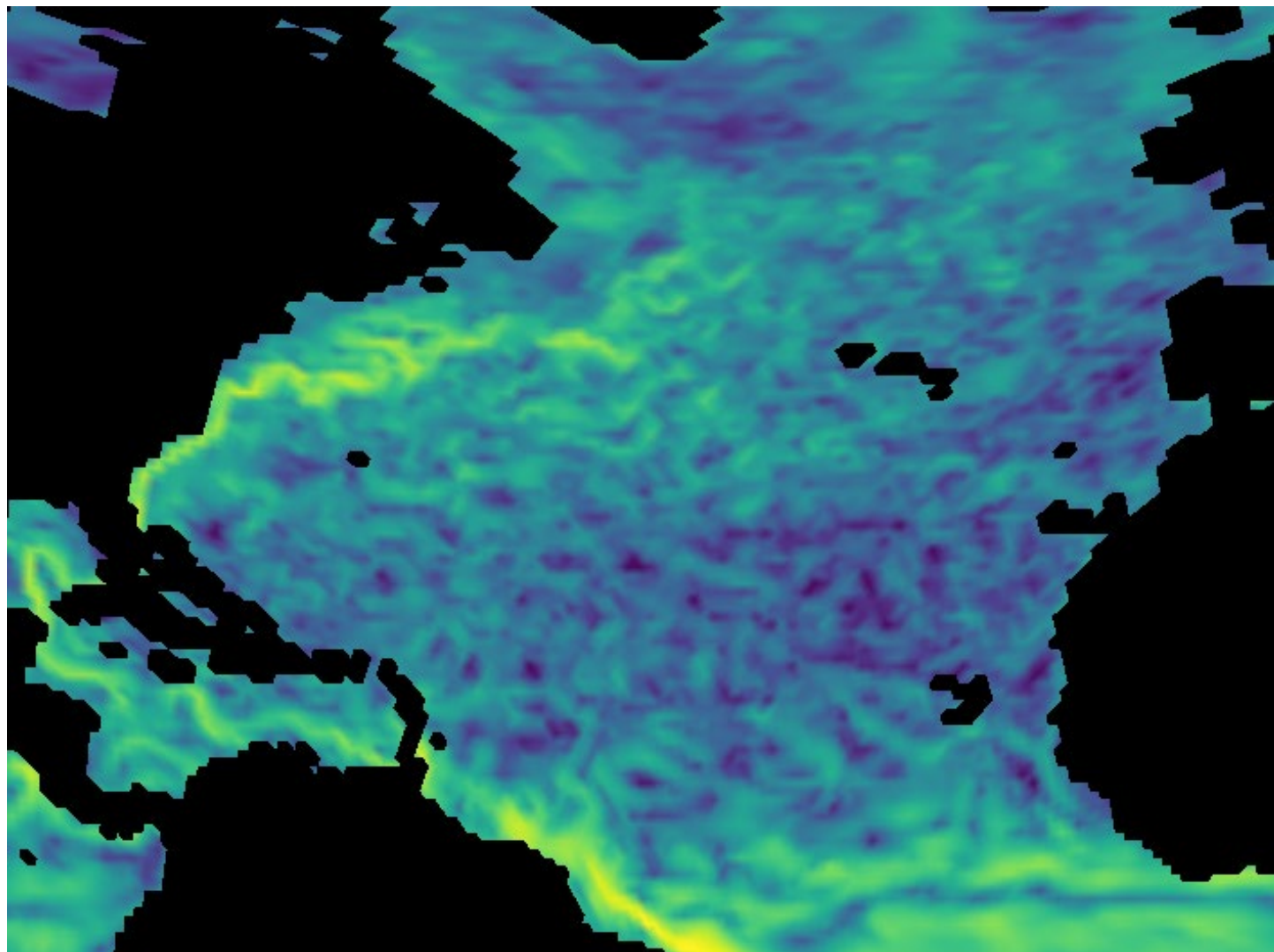




## Example 2: From ocean to atmosphere

Interpolation method: conservative-spherical-polygon

O160

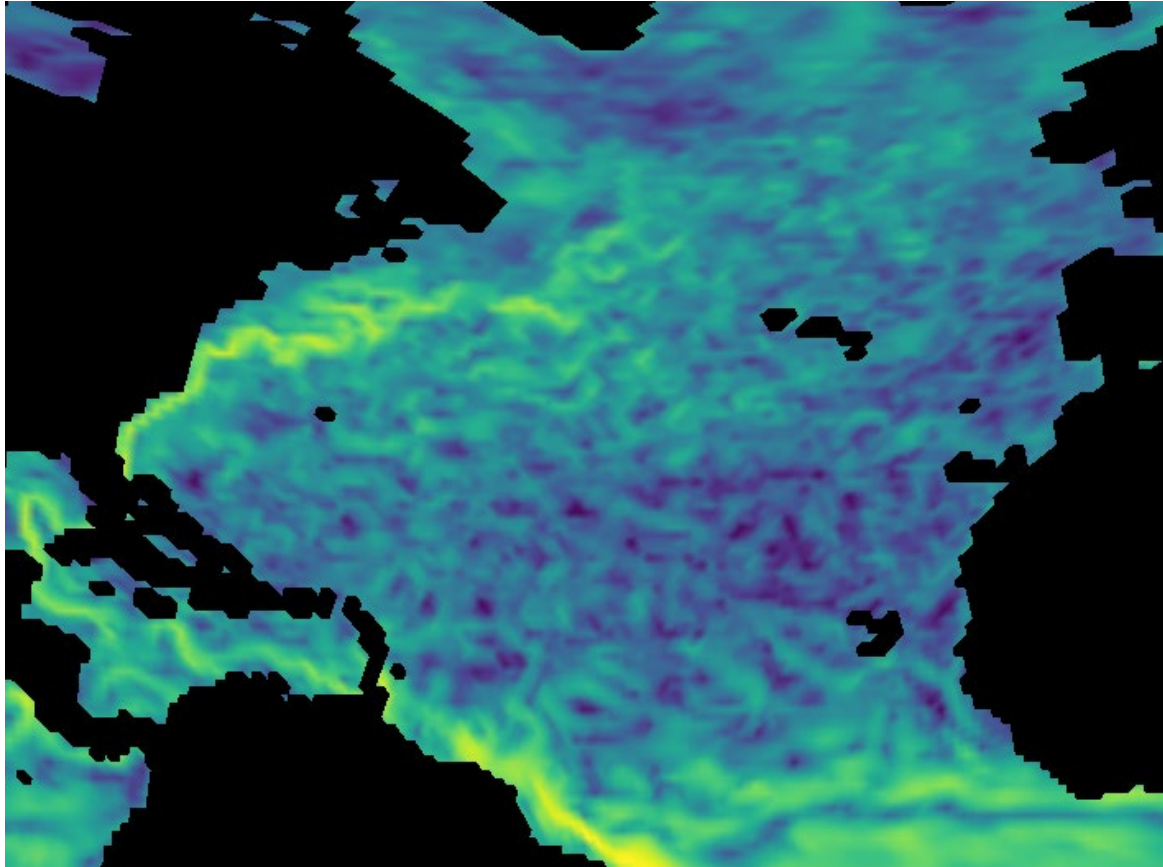


## Example 2: From ocean to atmosphere

Field: Sea velocity magnitude, from

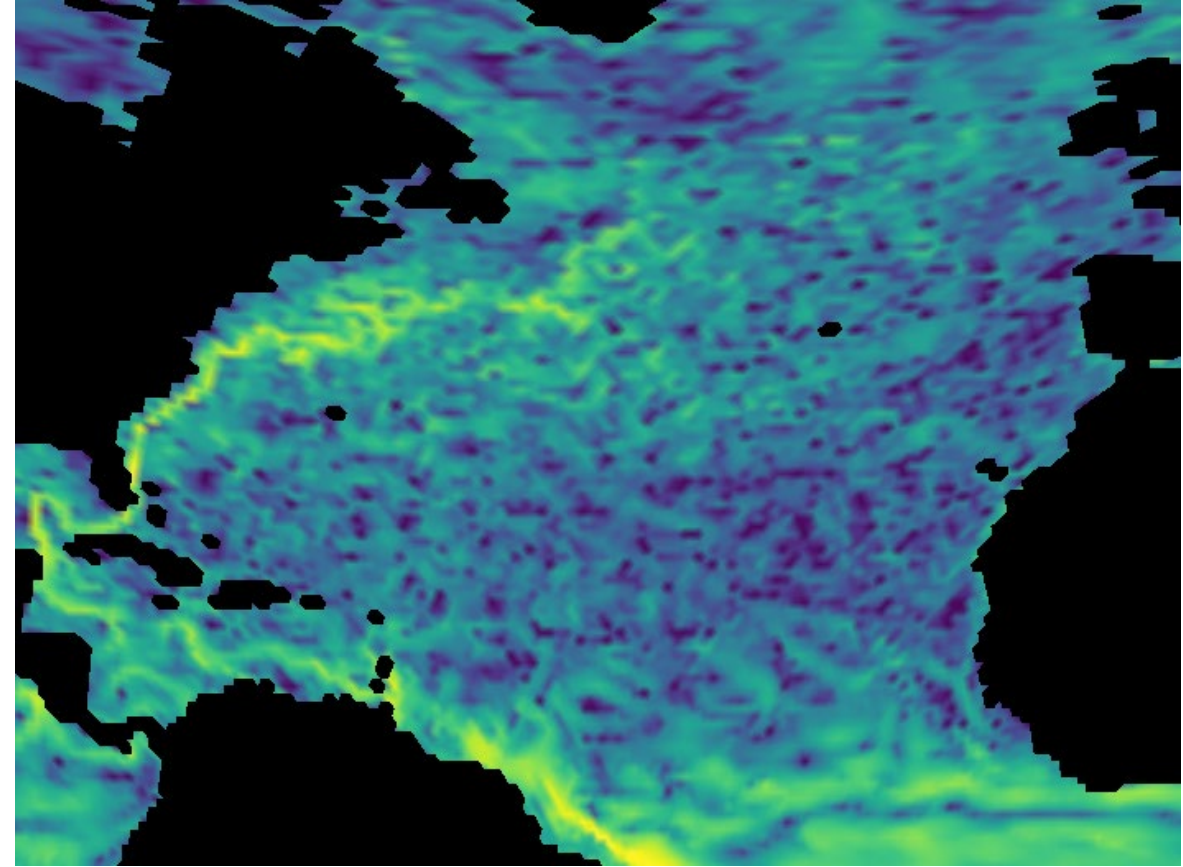
**Compare interpolation eORCA12 to O160: conservative vs non-conservative:**

conservative-spherical-polygon



- Smooth, filtering the high-frequencies
- Shape preserving

unstructured-bilinear-lonlat



- Preserves maxima / minima
- Noisy, unfiltered

## Next steps, near term

- Implement use of land-sea mask
- Use alternative fallback interpolation method at coast-lines
  - where target elements are not fully covered by source elements
  - where source fields contain missing values
- Integrate with IFS
- Warmworld project: Use FESOM unstructured ocean mesh
- Use Atlas to couple ecrad (radiation model)

## Next steps, longer term

- Implement capability to couple ESM components which use different MPI communicators with different MPI\_SIZE.



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