# Development of an offline and online hybrid model for the Integrated Forecasting System

Alban Farchi, Marcin Chrust, Patrick Laloyaux, Massimo Bonavita (ECMWF) and Marc Bocquet (ENPC)



#### **Outline**

- Methodology
- Offline pre-training
- Online forecast and training experiments



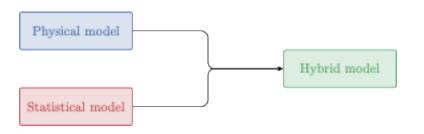
#### Why is model error so important?

- NWP models are affected by errors, e.g. unresolved small-scale processes
- Model error is one of the main limitations of forecast accuracy
- Growing interest of the DA community in weak-constraint methods:
  - Iterative EnKF in the presence of additive noise (Sakov et al. 2018)
  - Forcing formulation of weak-constraint 4D-Var (Laloyaux et al. 2020)
- More recent approaches to the model error issue rely on ML techniques to learn the model from data (Bocquet et al 2019, 2020; Brajard et al 2020).



# **Hybrid modelling**

- We propose to tackle model errors by using hybrid modelling
- The statistical part of the model is trained to learn and correct the error of the physical model.



- A typical NWP model rely on a set of ODEs or PDEs which define the tendencies:  $\frac{\partial x}{\partial t} = \phi(x)$
- A numerical scheme is used to integrate the tendencies from t to  $t + \delta t$ :  $x(t + \delta t) = \mathcal{I}(x(t))$
- Several integration steps are composed to build the resolvent from one analysis (or window) to the next:

$$\mathcal{M}: x_k \mapsto x_{k+1} = \mathcal{I} \circ \cdots \circ \mathcal{I}(x_k)$$



### Correcting the resolvent or the tendencies?

#### Resolvent correction

- Physical model and NN are independent
- NN must predict the analysis increments
- Adding a (potentially large) NN correction to the state can provoke initialisation shocks
- The hybrid model cannot be used for short-term predictions with ad-hoc approximations (e.g. linear growth of errors in time)

#### Hybrid approach to build the hybrid model

- 1. Train the NN offline as a resolvent correction
- 2. Rescale the correction from 1 DAW to 1 model time step
- 3. Fine-tune the NN online as a tendency correction

This methodology has been first validated using low-order models (Farchi et al. 2021, 2023)

#### **Tendency correction**

- Physical model and NN are entangled
- Need the adjoint of the physical model to train the NN!
   Requires online training.
- Can be used as is in DA experiments



### Online training with NN 4D-Var

• To train online the parameters of the NN, we propose to use a variant of weak-constraint 4D-Var (Farchi et al. 2021)

$$\mathcal{J}^{nn}(\theta, x_0) = \frac{1}{2} \left| \left| x_0 - x_0^b \right| \right|_{B^{-1}}^2 + \frac{1}{2} \left| \left| \theta - \theta^b \right| \right|_{P^{-1}}^2 + \frac{1}{2} \sum_{k=0}^L \left| \left| y_k - \mathcal{H}_k \circ \mathcal{M}_{k:0}^{\theta}(x_0) \right| \right|_{R_k^{-1}}^2$$

- The parameters  $\theta$  (e.g. NN weights and biases) are assumed constant over the DAW
- Information is flowing from one DAW to the next using the priors  $x_0^b$  and  $\theta^b$
- This approach is very similar to classical parameter estimation in DA and can be seen as a NN formulation of weak-constraint 4D-Var
- Similar approaches had already been developed within an EnKF context (Bocquet et al. 2020)



#### Implementation of NN 4D-Var within OOPS

- To implement NN 4D-Var, we can reuse most of the framework already in place for WC 4D-Var
- We only need a NN library to compute the forward, tangent linear, and adjoint operators of the NN
- The NN needs to be applied in the model core, which is implemented in Fortran
- We implemented our own NN library in Fortran: FNN
- FNN has been interfaced and included in OOPS



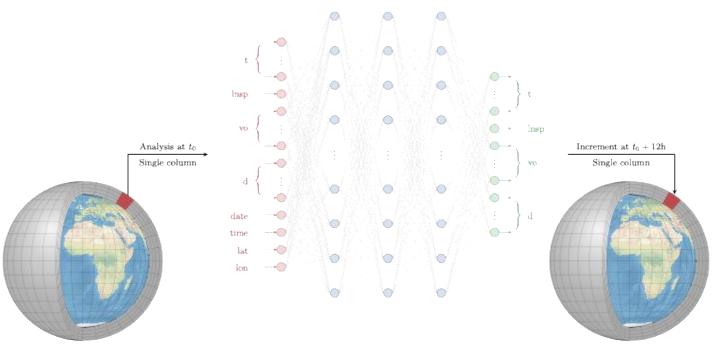
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#### A NN correction for the IFS

- We extend the preliminary work of Bonavita and Laloyaux (2020)
- We compute a correction for 4 atmospheric variables in the same NN: temperature (t), logarithm of surface pressure (lnsp), vorticity (vo), and divergence (d)
- We use a vertical architecture, where the NN processes independently each atmospheric column
- We include all 137 model levels in both input and output, for a total of 412 channels



- Once trained, the NN can be applied on any grid
- The num. of parameters is relatively small compared to the size of the control vector (<2%) and to the size of the training dataset (<1%)
- Horizontal information is partially lost



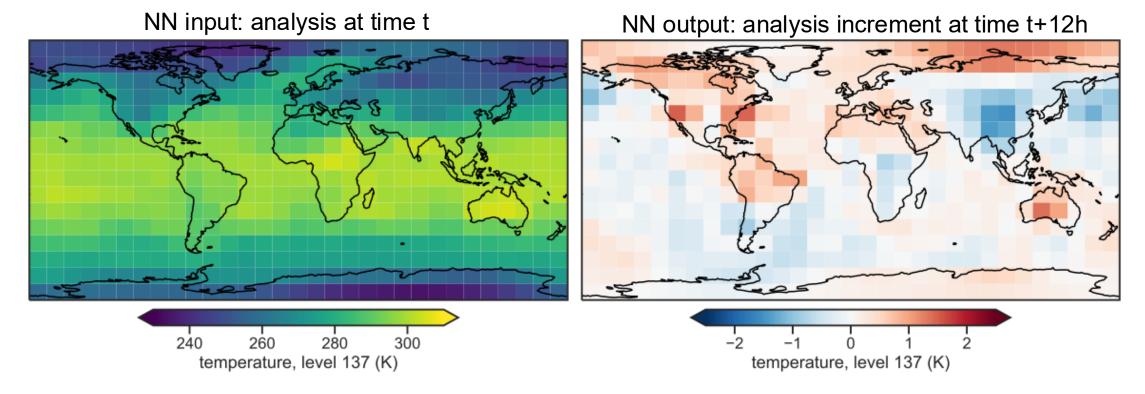
### **Description of the training dataset**

- We use data from the operational archive between 2021 and 2023:
  - Training set: 2021 and 2022 (cycles 47R1 to 47R3)
  - Validation set: 2023 (cycles 47R3 to 48R1)
- 2024 is set aside for online evaluation
- Pre-2021 data is discarded because the implementation of WC 4D-Var (in June 2020 with cycle 47R1) significantly modified the increments
- The NN is trained to predict the sum of the analysis increments and the model error diagnosed by WC 4D-Var (1 sample every 12h)

$$\mathcal{F}_{\theta}: x_k^a \mapsto x_{k+1}^a - x_{k+1}^f + 12 * w_k^a$$



### Choice of the spectral truncation



- To focus on large-scale model error, we truncate the data at T15 and interpolated in a 16x32 Gaussian grid
- We then investigate the effect of resolution by progressively increasing the truncation: T31, T63, and T95

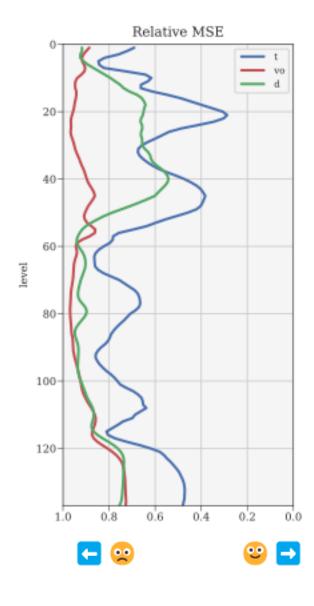


#### Validation scores at T15

Relative MSE on the validation set

Name	Lnsp	Т	Vo	D
No correction	1.000	1.000	1.000	1.000
Mean increment	1.000	0.968	1.000	1.000
Climatological increment	0.769	0.659	0.976	0.804
Trained NN	0.764	0.619	0.917	0.783

- Overall, the NN can predict 10 to 40% of the increments
- The increments for t, Insp, and d are more predictable than for vo
- The predictions are in general most accurate close to the surface and in the stratosphere (where WC is active)



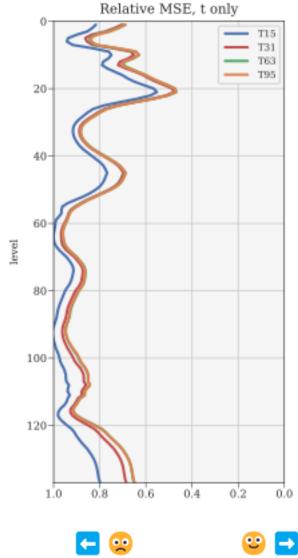


### Validation scores at higher resolution

Relative MSE on the validation set at T127

Training truncation	Lnsp	Т	Vo	D
T15	0.969	0.835	1.000	0.997
T31	0.900	0.757	0.996	0.993
T63	0.880	0.740	0.996	0.994
T95	0.882	0.739	0.996	0.994

- To ensure fairness, all NNs are evaluated at the same truncation, T127
- At higher resolution, vo and d are almost unpredictable for this NN architecture
- For t and Insp, training at higher resolution is beneficial, until ~T63





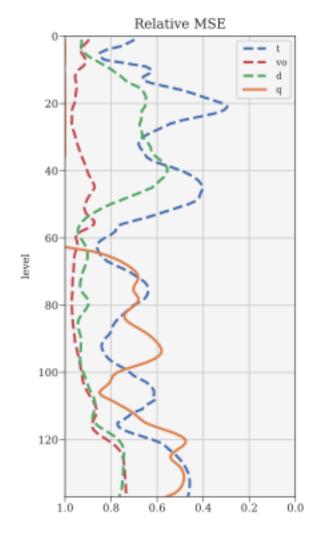


### **Extension 1: include q**

#### Relative MSE on the validation set

Name	Lnsp	Т	Vo	D	Q
No correction	1.000	1.000	1.000	1.000	1.00
Mean increment	1.000	0.968	1.000	1.000	0.956
Climatological increment	0.769	0.659	0.976	0.804	0.620
Trained NN wo q	0.764	0.619	0.917	0.783	
Trained NN w. q	0.766	0.619	0.924	0.788	0.570

- Originally, our choice of 4 atmospheric variables (t Insp vo d) is based on the results from Bonavita and Laloyaux (2020)
- Later results (Chen et al 2022) indicate that it could be relevant to include specific humidity in the corrected variables
- In our experiments, the increments for q are highly predictable







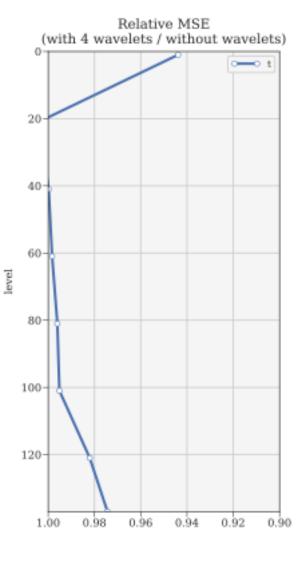






#### **Extension 2: include horizontal information**

- The choice of a column architecture is driven by computational constraints: in the online system, each atmospheric column is stored in the same processor unit
- Even within the column framework, it is possible to include horizontal information, beyond the latitude and longitude extra predictors:
  - Use the horizontal gradients as extra predictors of the NN (Kochkov et al. 2023)
  - Use a wavelet decomposition of the predictors
- Challenge: how to deal with the increased input dimension?
- Results from a toy experiment with 14 years of ERA-5 data using a selection of model levels at T63 resolution indicate that using a wavelet decomposition of the predictors is beneficial.













### Extension 3: increase the frequency of the NN correction

- In the offline training dataset, we have samples every 12h, at 09:00 and 21:00
- In the online experiments, the NN correction is used as a tendency correction, but for consistency, the correction is updated only every 12h
- We believe that updating the correction more frequently should be beneficial, because it would allow us to better represent the daily variability of model error

#### Challenges:

- Is it necessary to update the offline training step? Most probably yes.
- What offline training data can be used? Analysis and first-guess within the window?



#### **Outline**

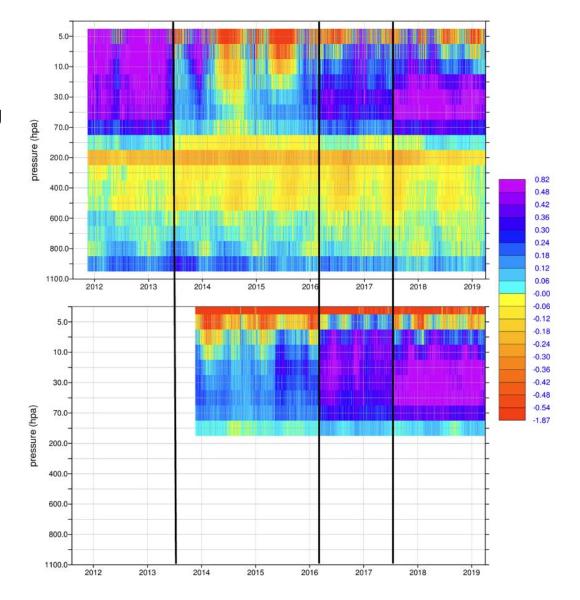
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### Motivation for online training

#### Offline Training

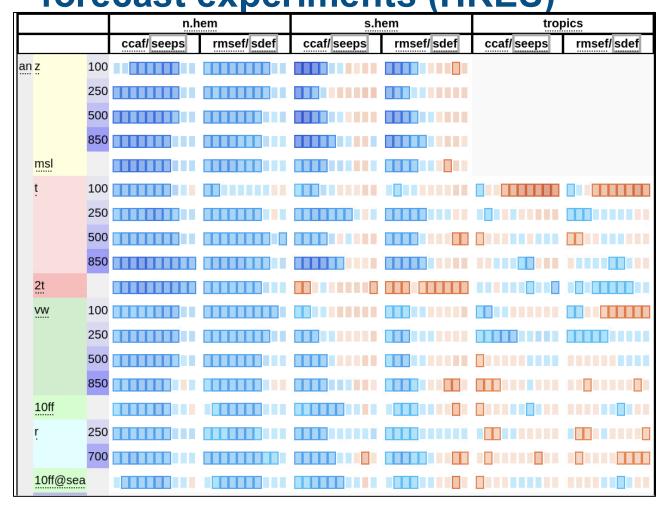
- Uses historical data (reanalysis same model, long dataset record, 0001 – short record or changing model)
- Static correction model with fixed parameters
- Can become outdated as model and model error evolve (numerical model updates, slowly evolving model climate)
- Requires periodic retraining
- Why train model error online?
  - Continuous adaptation to changing model error
  - Model error diagnosed using latest observations
  - Model error correction constrained by and consistent with TLM dynamics
  - Mitigated model error in data assimilation



**Fig.** Time series of the difference between observations and temperature first-guess trajectory from the ECMWF operational analysis cycle for radiosonde (top) and RO (bottom). From Laloyaux et al., 2020.

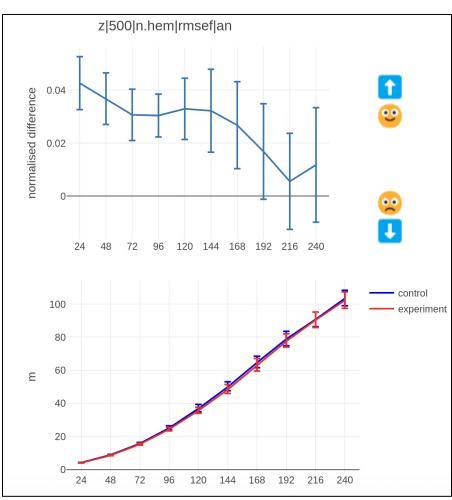


Performance of the model error trained offline in the forecast experiments (HRES)



**Fig.** NN trained offline. Scorecard showing the change in forecast anomaly correlation and RMSE as a function of lead time. 20240101-20240228.

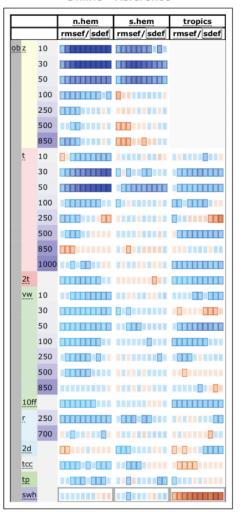




**Fig.** NN trained offline. Z500hPa NH RMSE. 20240101-20240228.

### Training online with the standard DA setup (12h window)

Online - Reference



Online - Offline



- The neural network is trained online at a resolution that is lower or equal to the inner loop resolution
- The neural network correction is applied at the resolution consistent with online training
- We obtained the best impact on forecast skill when training online/applying the correction online at the T31 resolution
- The largest impact is visible in the stratosphere

**Fig.** Score cards showing the change in forecast RMSE verified against independent observations. Left panel: the impact of online training (Online) with respect to the standard weak-constraint configuration (Reference). Right panel: the impact of online training (Online) with respect to offline training (Offline). From Farchi et al. (2024).



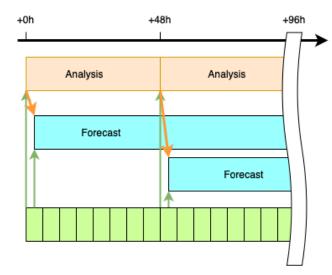
# Training online with long DA window

- Why would we want to train the model of model error with a long DA window?
  - Improved constraint on model error more observational information able to better constrain evolving model errors
  - Stronger coupling between observations and model dynamics – enhance the ability to identify systematic model errors
  - Helps capture model errors that develop over longer timescale
- What are the obstacles?
  - Cannot run in the critical path unless past observations are used
  - The quality of the initial conditions may significantly deteriorate for the very long window (observation usage, QC)
  - Computational cost



#### Long DA window (48h)

- Only the parameters of the neural network are optimised
- Background state from reference experiment (0001)



#### Operational anlaysis (0001)

Fig. Online training setup with a long DA window (48h).

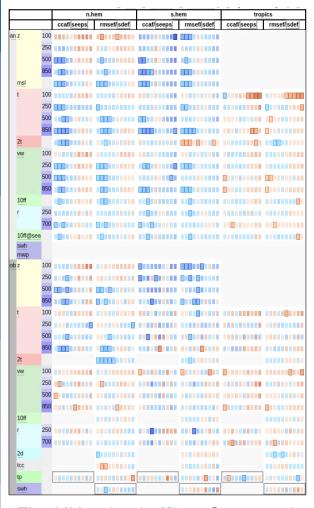
$$\mathcal{J}^{nn}(\boldsymbol{\theta}) = \frac{1}{2} \left| \left| \boldsymbol{\theta} - \boldsymbol{\theta}^{\mathrm{b}} \right| \right|_{P^{-1}}^{2} + \frac{1}{2} \sum\nolimits_{k=0}^{L} \left| \left| \boldsymbol{y}_{k} - \mathcal{H}_{k} \circ \mathcal{M}_{k:0}^{\boldsymbol{\theta}}(\boldsymbol{x}_{0}) \right| \right|_{R_{k}^{-1}}^{2}$$

Fig. Modified cost function for the long DA window (48h).

#### Long DA window training setup:

- Only the parameters of the NN are optimized
- The atmospheric background state is not cycled and in each cycle is replaced with the operational analysis (0001).

# Training online with long window



z|500|n.hem|rmsef|an

0.1

0.05

0.05

0.05

0.05

0.1

24 48 72 96 120 144 168 192 216 240

120

120

120

24 48 72 96 120 144 168 192 216 240

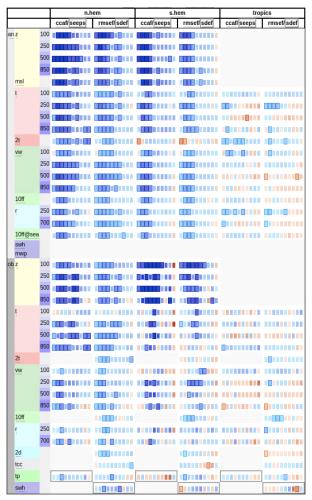
E 60

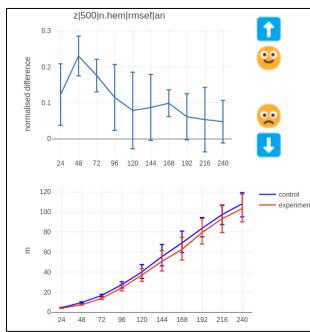
40

20

24 48 72 96 120 144 168 192 216 240

**Fig.** NN trained offline, Z500, NH, RMSE.





**Fig.** NN trained online, Z500, NH, RMSE.

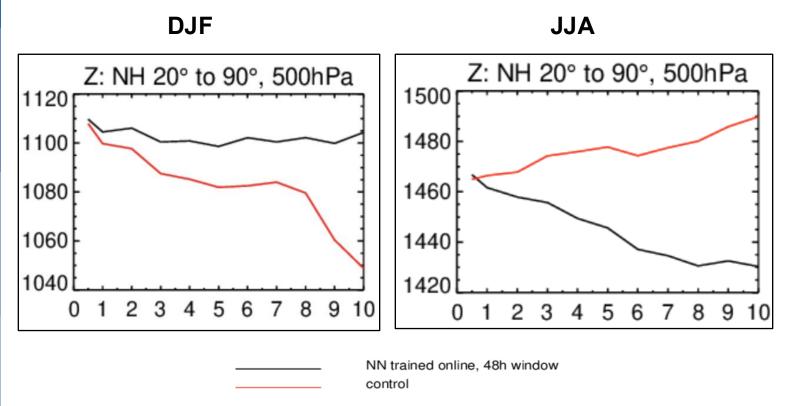
Fig. NN trained online. Scorecard.





- Training/Evaluation period: 20240101 20240331
- Window length: 48h

### Impact on forecast activity in Northern Hemisphere



**Fig.** Impact of applying a NN model error correction on Z500 NH forecast activity. **Left**: DJF period and **Right**: JJA period.

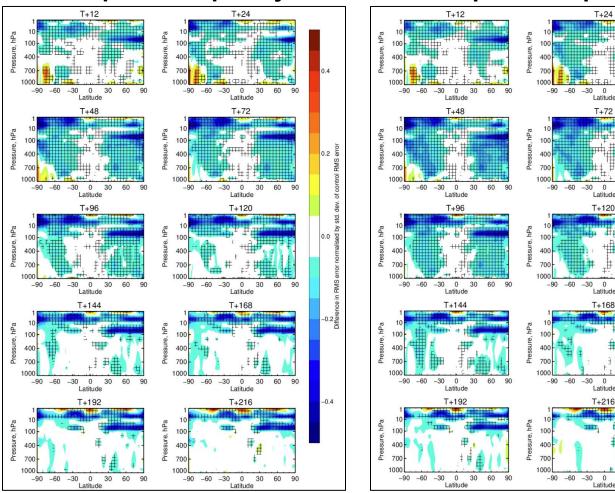
- Applying NN-based model error correction impacts forecast activity:
  - Forecast activity is maintained in Northern Hemisphere (NH) winter
  - Forecast activity is suppressed in NH summer
- What are the reasons behind affecting the forecast activity in NH:
  - Only large-scale tendencies are corrected, while summer variability is driven by smallerscale processes
  - The same correction is applied uniformly throughout 12h which may affect diurnal variability



### Effect of the temporal resolution

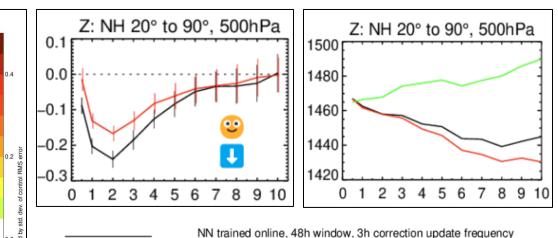
12h update frequency

3h update frequency



**Fig.** Change in RMS error in T. Online training with 48h DA window. **Left**: 12h correction update frequency. **Right**: 3h correction update frequency.





**Fig.** Impact of the correction update frequency on **Left**: Z500hPa NH RMSE, **Right**: forecast activity Z500hPa NH RMSE.

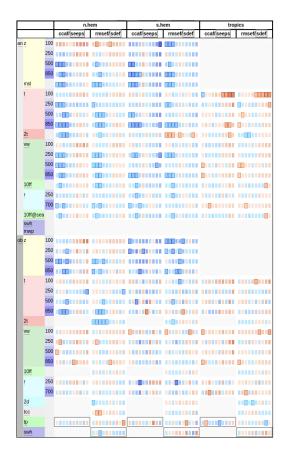
NN trained online, 48h window, 12h correction update frequency

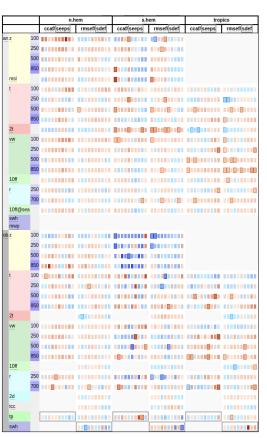
Increasing the frequency of the correction update:

- Improves forecast scores
- Is positive for the forecast activity

control

# Challenges: performance in out-of-training dates







- A long DA window (48h) is not feasible in operations due to unavailable observations and timeliness constraints
- The online training would require years of training for the NN to generalise well beyond the training dataset
  - Significant changes to the ECMWF suites would be required to pursue this avenue
- A lagged system using previous 48h observations could be implemented

NN trained offline



NN trained online in **lagged mode** with a large learning rate

NN trained online in **lagged mode** with a moderate learning rate

Training/Evaluation period: 20240101 – 20240331

#### **Conclusions**

- Developed a physically consistent hybrid model that enhances the purely physics-based model
- Two step training of the neural network correction: offline followed by online fine-tuning within the framework of 4D-Var owing to the differentiable model and observation operators
- The neural network is directly constrained with observations in the online training step
- Online training with a long DA window:
  - Significant forecast improvements across the board
  - Weak generalisation of the NN to out of training samples
  - Need to train on multi-year datasets rather than 3 months

- Lagged DA window:
  - Feasible to implement in an operational environment
  - NN constantly updated with the latest observations
  - Improved performance with respect to the NN trained offline

#### Next steps:

- Offline pre-training at a 3h frequency
- Integration of specific humidity online
- Integration of the wavelet transformation online
- Development of non-sequential online learning?

