Transformer Neural Networks

Matthias Karlbauer

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Credit: built on slides by Christian Lessig

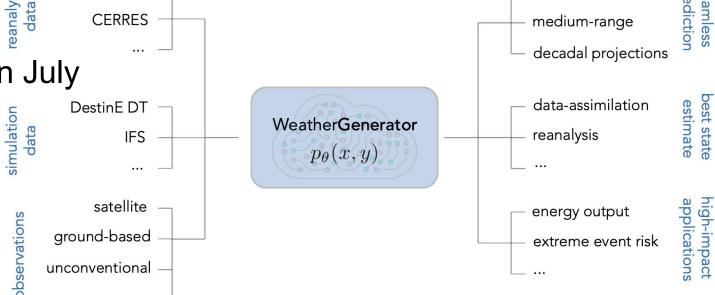


Introduction

- About me:
 - Cognitive scientist by training, specialised in machine learning

ERA5

- Worked a lot with recurrent neural networks (RNNs)
- PhD about global weather prediction with neural networks
- What I'm doing at ECMWF
 - Joined WeatherGenerator in July
 - Earth system predictability, extended range
 - Stabilizing rollout





nowcasting

Introduction

- What are transformers made for?
 - Seq2seq modelling: predict next token in a sequence, e.g., next word in a sentence:

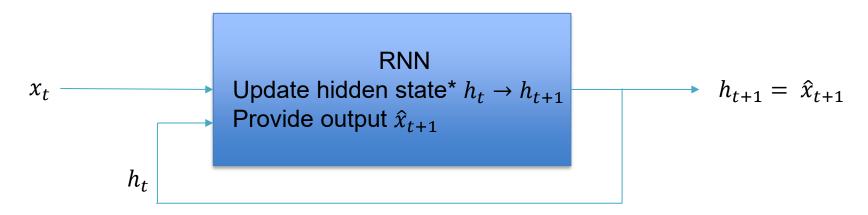
My house is ...?



- In this lecture:
 - What are the ingredients that make a transformer tick?
 - Why is the transformer architecture so prominent today?
- Transformers are nowadays building blocks in almost any deep learning model ("GPT" in ChatGPT stands for "generative pre-trained transformer")

Motivation

- Recurrent neural networks
 - Standard for temporal sequence problems (e.g. in natural language processing up to 2018). My house is ...



- Implicit connection to past states
- Training is difficult to parallelize

*Hidden state update:

$$h_{t+1} = W_{IH} x_t + W_{HH} h_t$$



Motivation

- Architecture that can be parallelized more efficiently
- More direct interaction between information, in particular "far away" one

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Attention Is All You Need

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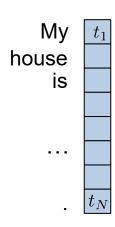
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Google Research

Aidan N. Gomez* †
University of Toronto

Łukasz Kaiser* Google Brain

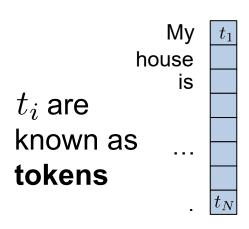


- Similarity measure between hidden/latent states $\{t_i\}_{i=1}^N$
 - Hidden/latent states are vectors in \mathbb{R}^E



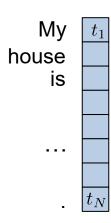


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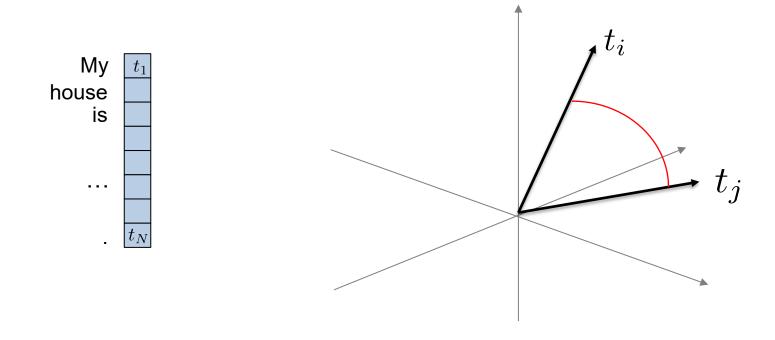


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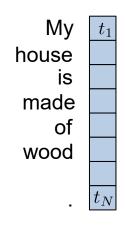


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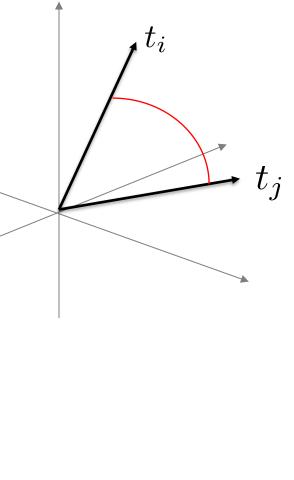
$$t_i \cdot t_j$$



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$$\tilde{t}_i = \sum_{j=1}^{N} (t_i \cdot t_j) t_j$$



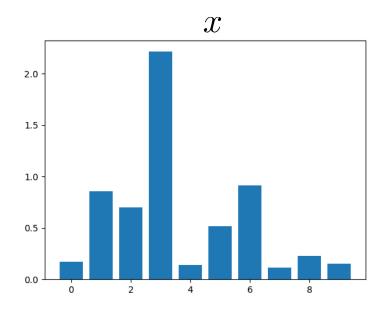
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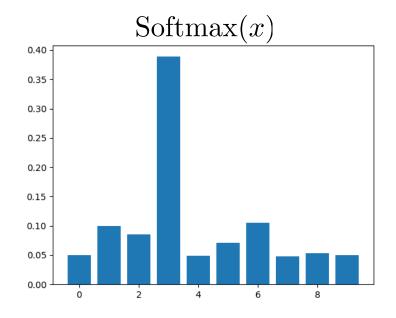
$$\tilde{t}_i = \sum_{j=1}^N \sigma(t_i \cdot t_j) t_j$$



Softmax

Softmax
$$(x)_i = \frac{e^{x_i}}{\sum_j e^{x_j}}$$
, $x \in \mathbb{R}^n$







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k2	v2
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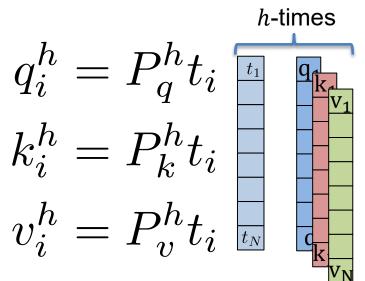
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$$\begin{aligned} q_i &= P_q t_i \\ k_i &= P_k t_i \\ v_i &= P_v t_i \end{aligned} \qquad \tilde{t}_i = \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{Learnable attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N \sigma(q_i \cdot k_j) v_j \qquad \text{attention module} \\ & \sum_{j=1}^N$$

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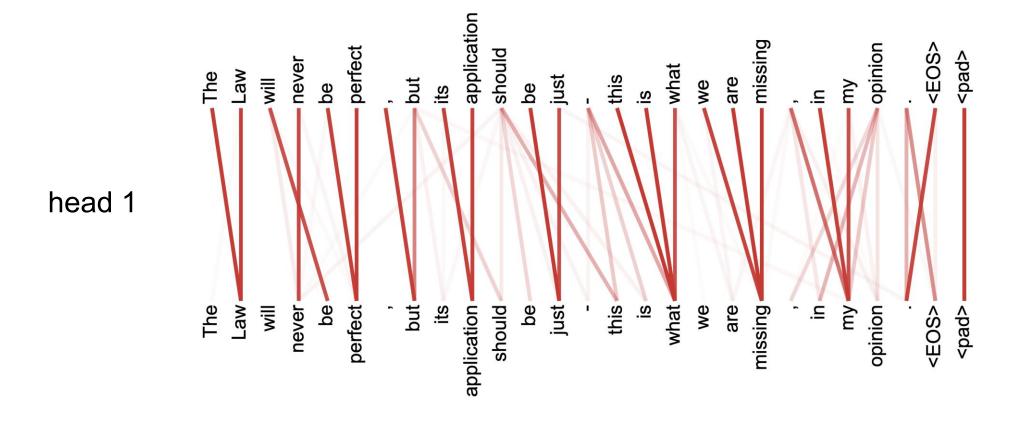
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Learnable attention module with multiple heads

head 1

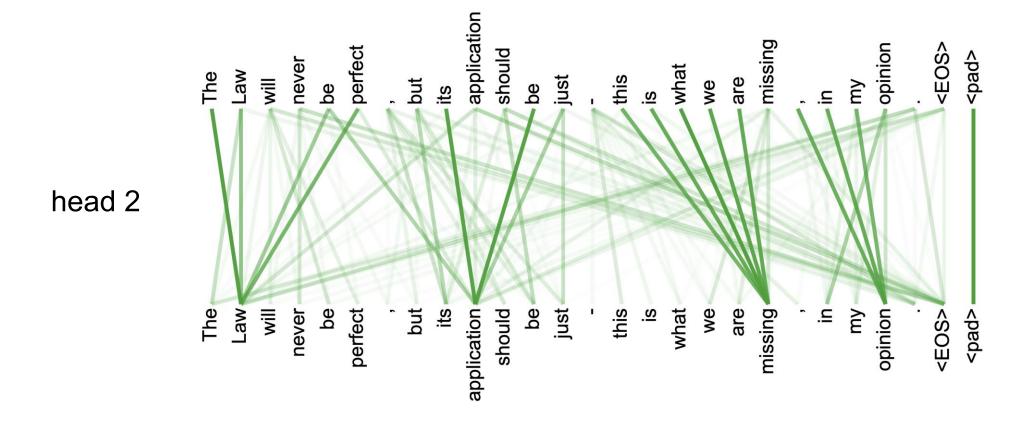
Vaswani et al., Attention is all you need, 2017, https://arxiv.org/pdf/2310.16764.pdf





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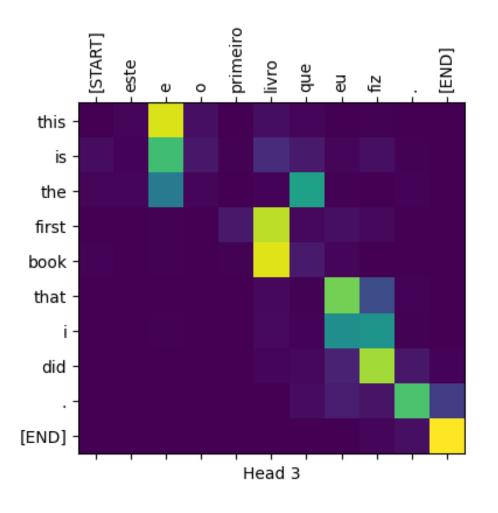


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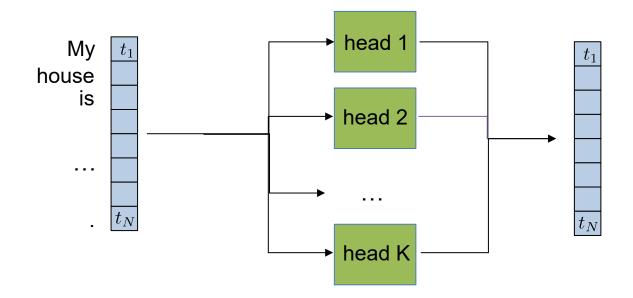
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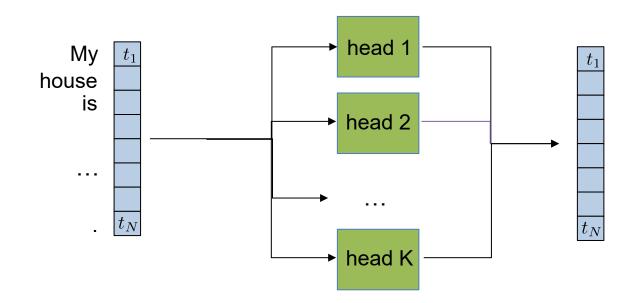
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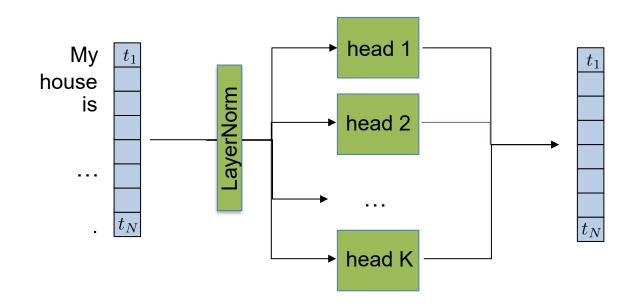


$$t_i \in \mathbb{R}^E$$

$$P_*^h : \mathbb{R}^E \to \mathbb{R}^{E/H}$$

$$\tilde{t}_i = \tilde{P}(\tilde{t}_i^1, \dots, \tilde{t}_i^H)$$

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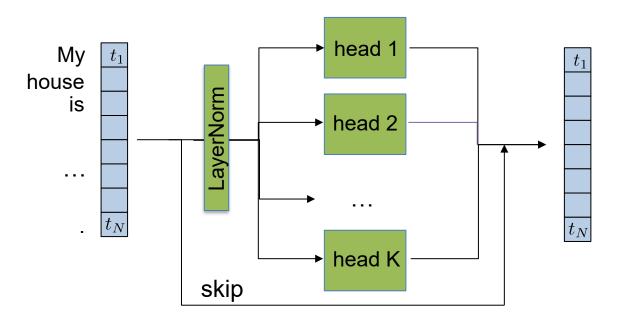


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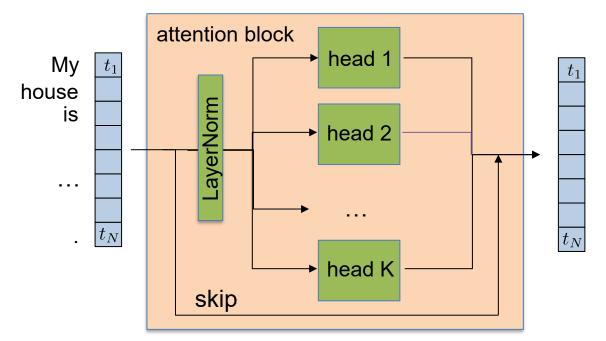
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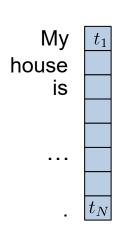


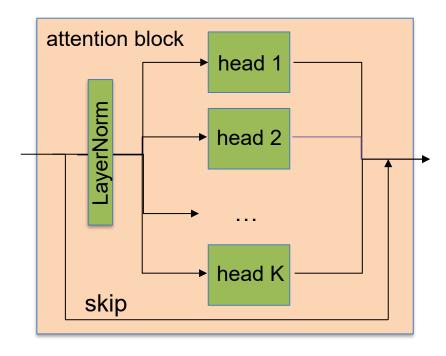
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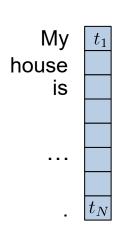
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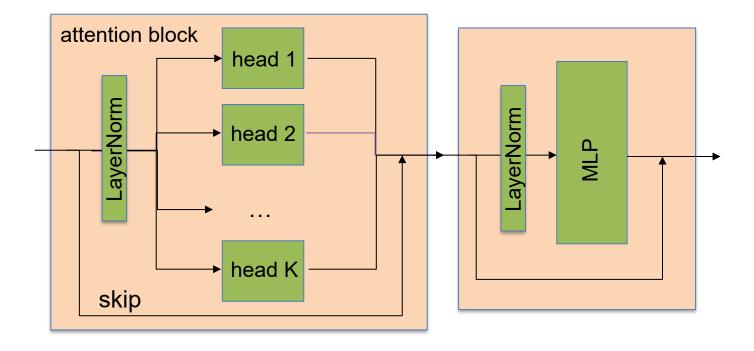




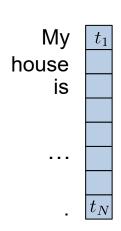


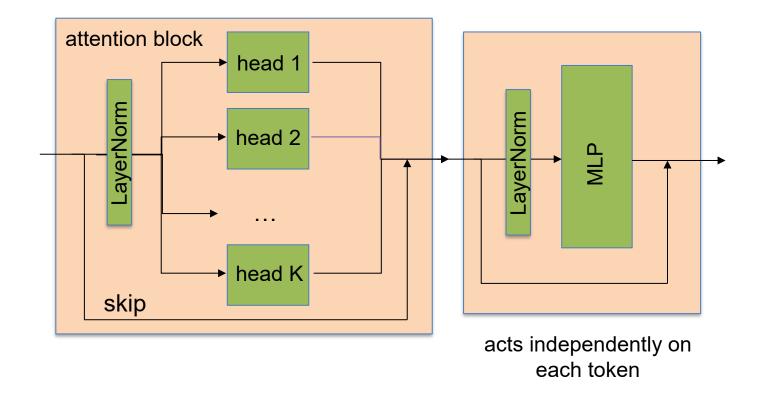




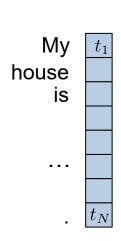


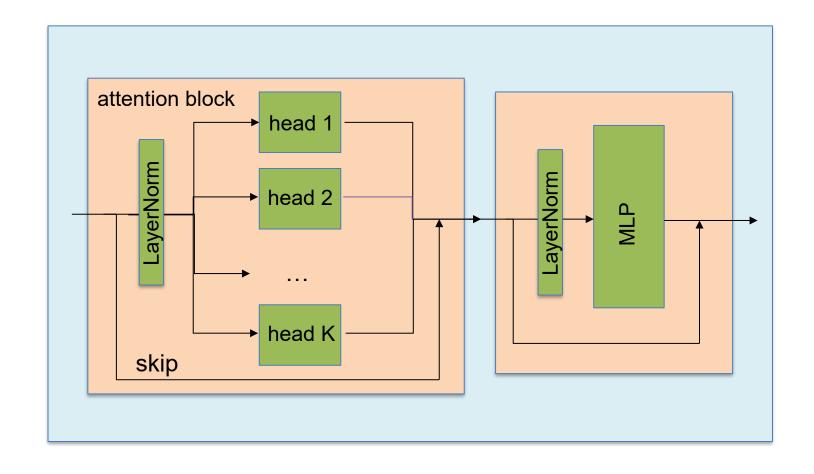






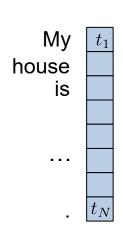


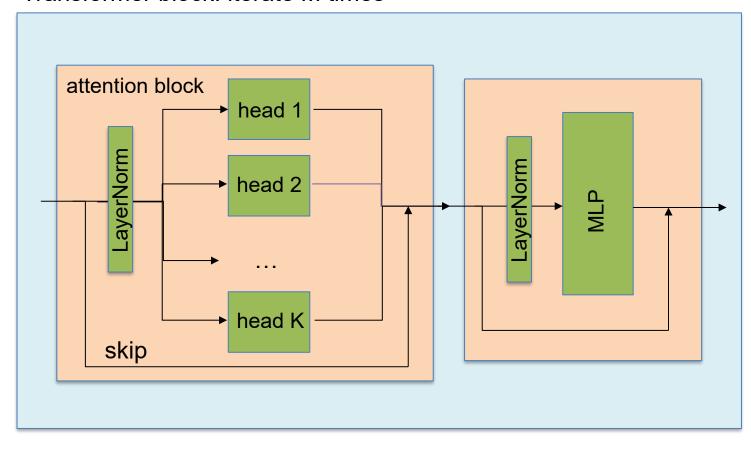




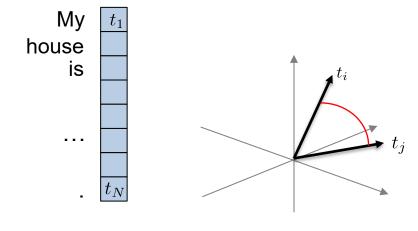


Transformer block: iterate M times



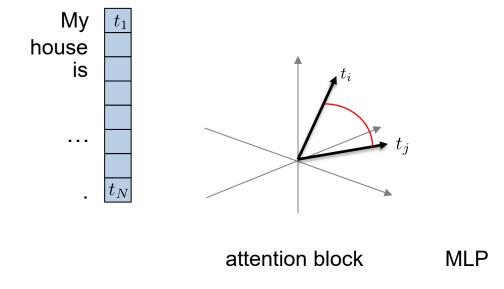




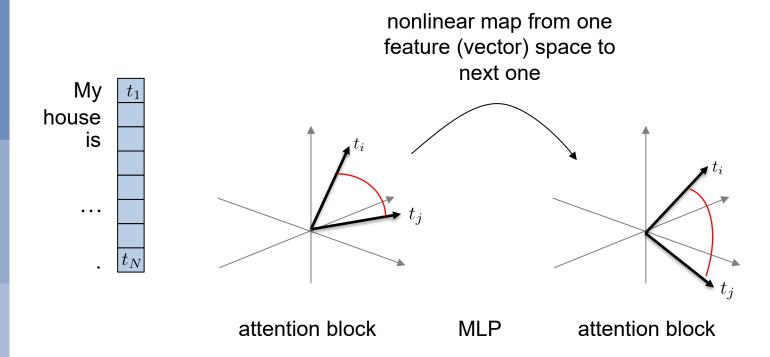


attention block

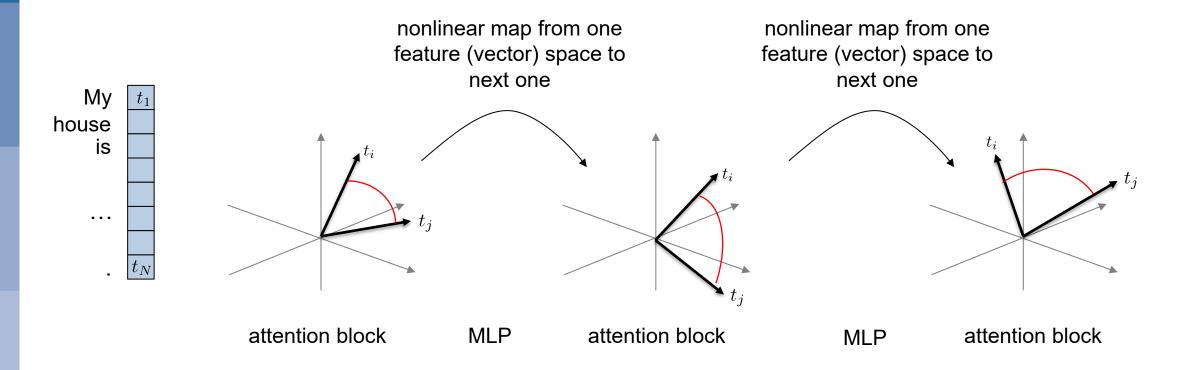




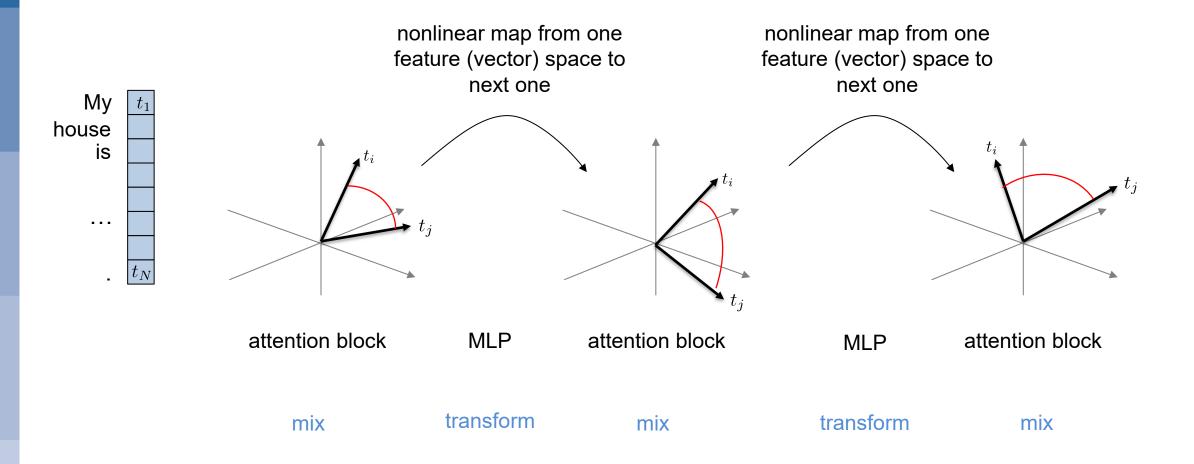






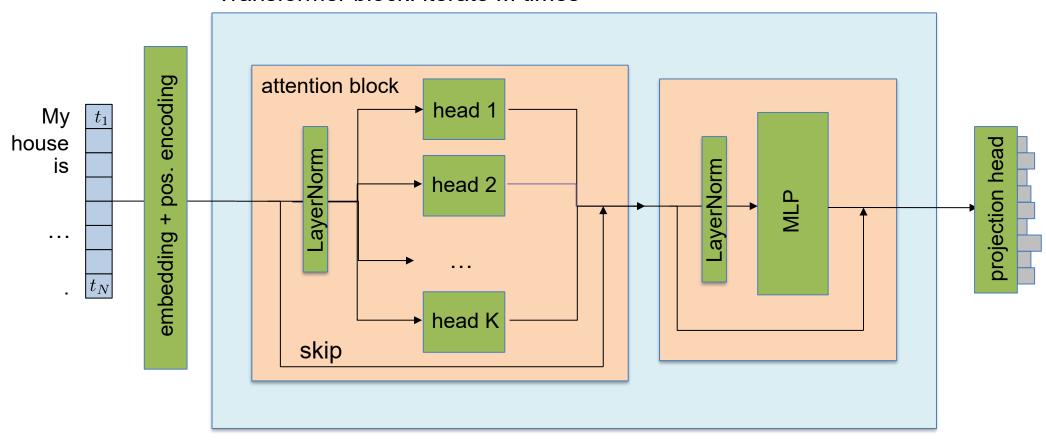








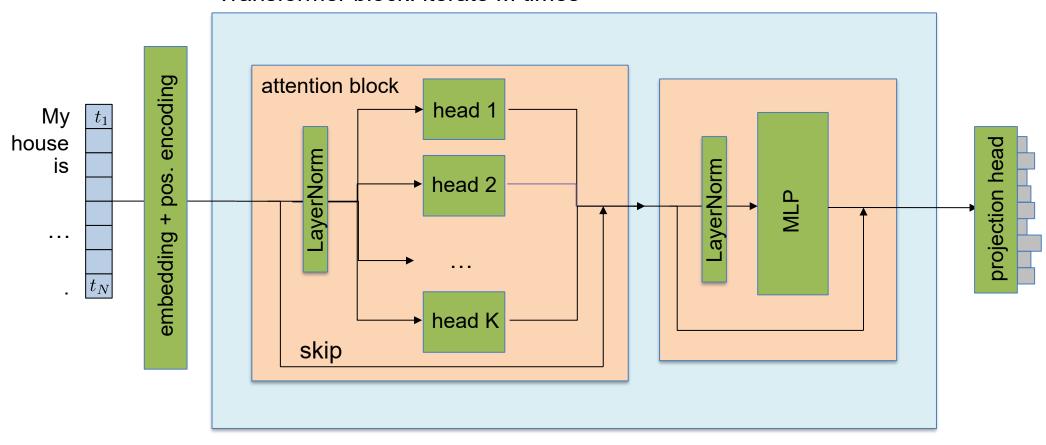
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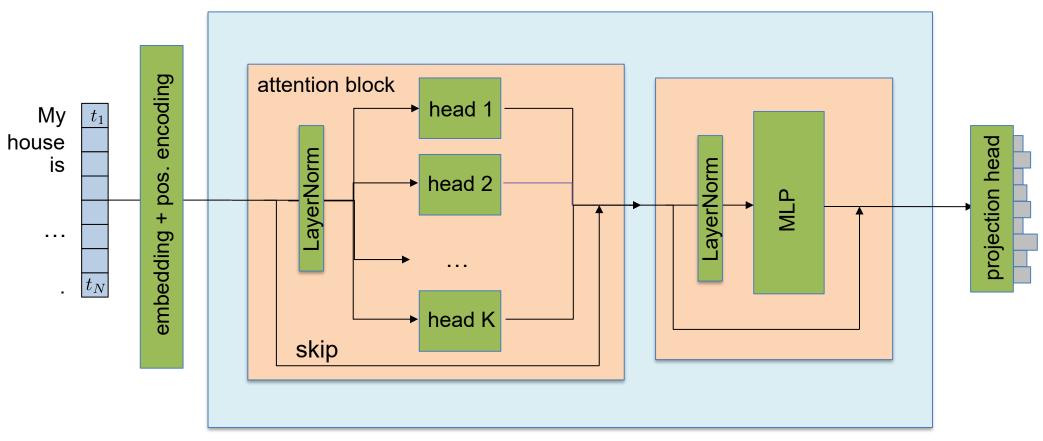
- Positional encoding
 - Tokens after embedding form a set without ordering
 - Structure/relationship between tokens needs to be encoded separately
 - Encoding can be fixed or learned
 - Classical approach: harmonic positional encoding that overlays sine/cosine oscillations with frequency that depends on position

Transformer block: iterate M times





Transformer block: iterate M times



How to define a token when one has a pixel image instead of discrete words?





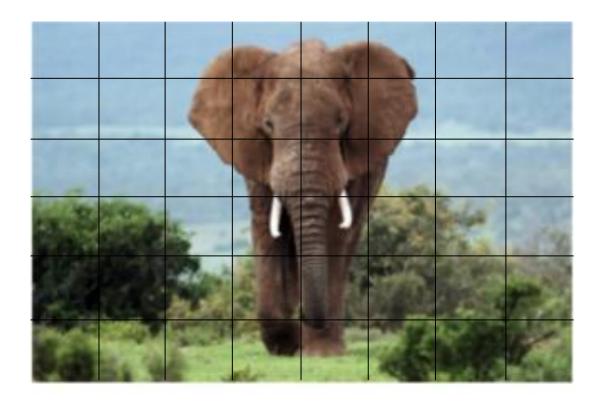
How to define a token when one has a pixel image instead of discrete words?

Dosovitskiy et al., An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale, 2021, https://arxiv.org/abs/2010.11929



token is small image patch

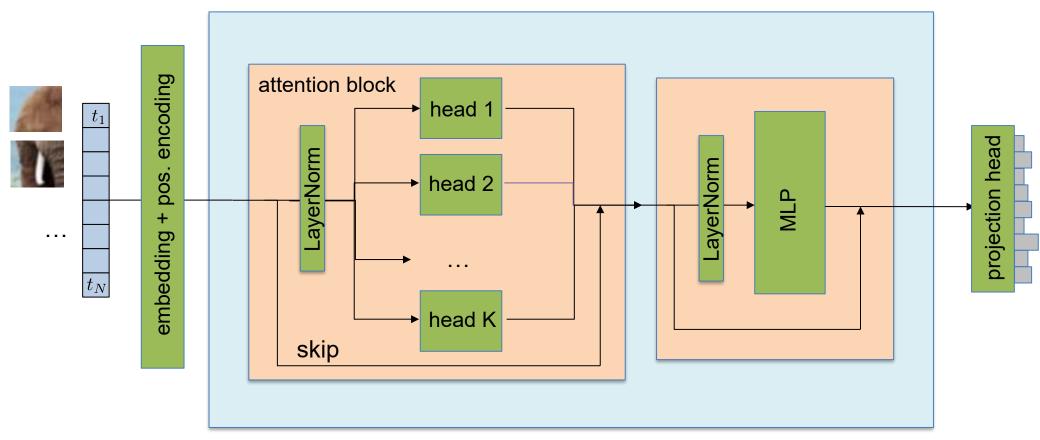
- enough structure
 for dot product to
 make sense
- small enough for attention to provide rich structure



How to define a token when one has a pixel image instead of discrete words?



Transformer block: iterate M times

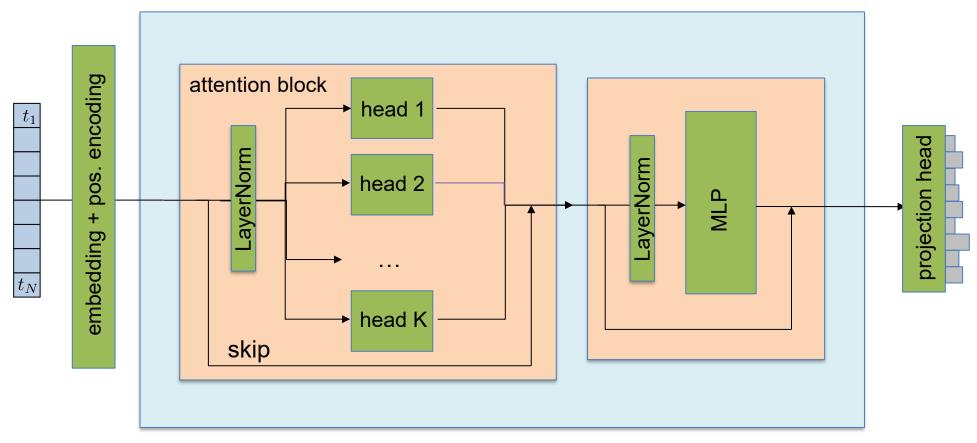


Vision transformer: token is small but non-trivial image patch



X transformer (encoder)

Transformer block: iterate M times

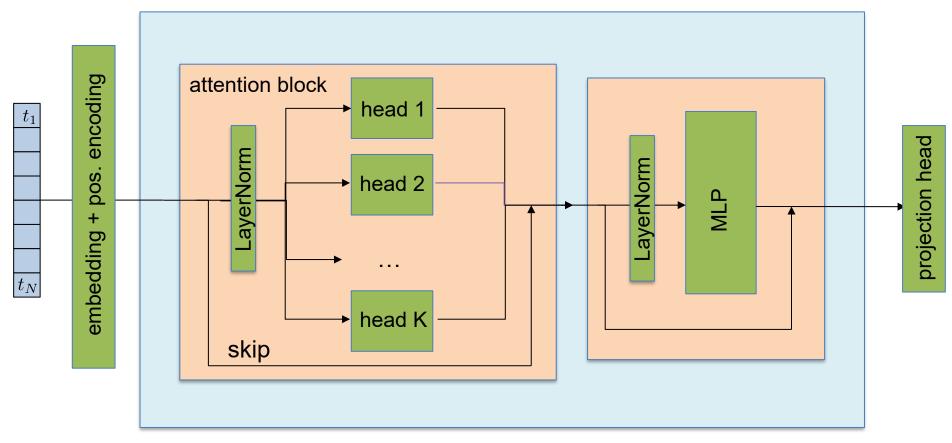


Central (only) question: what is a token, i.e. what is small information "nugget"?



X transformer (encoder)

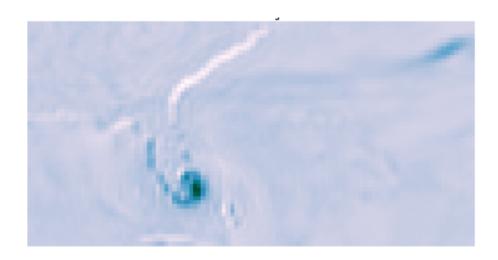
Transformer block: iterate M times



Atmosphere: token as information from small space-time neighborhood



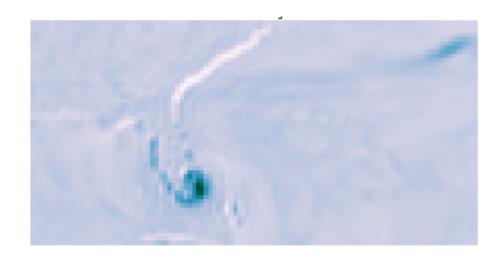
What is attention?

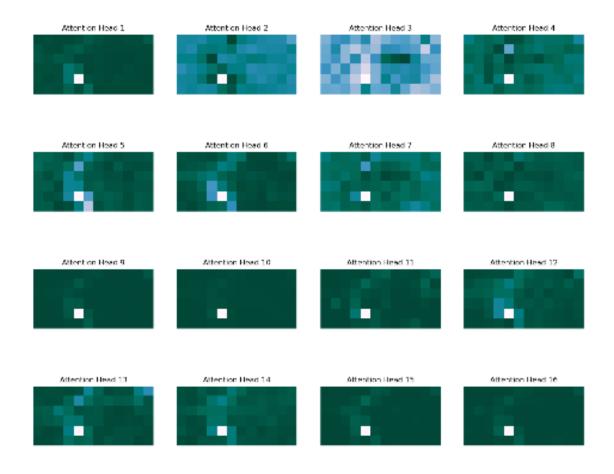


Lessig et al., AtmoRep, 2023, https://arxiv.org/abs/2308.13280



What is attention?



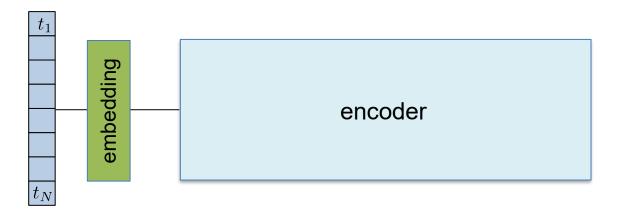


Lessig et al., AtmoRep, 2023, https://arxiv.org/abs/2308.13280

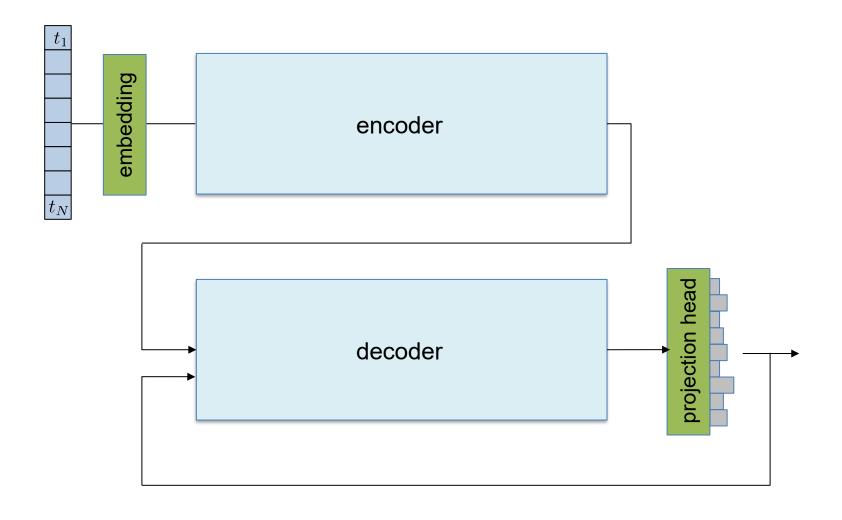


- Introduced in the original transformer paper (Vaswani et al., 2017) for translation tasks
 - Encode: input and encode language A
 - Decoder: decode and output language B

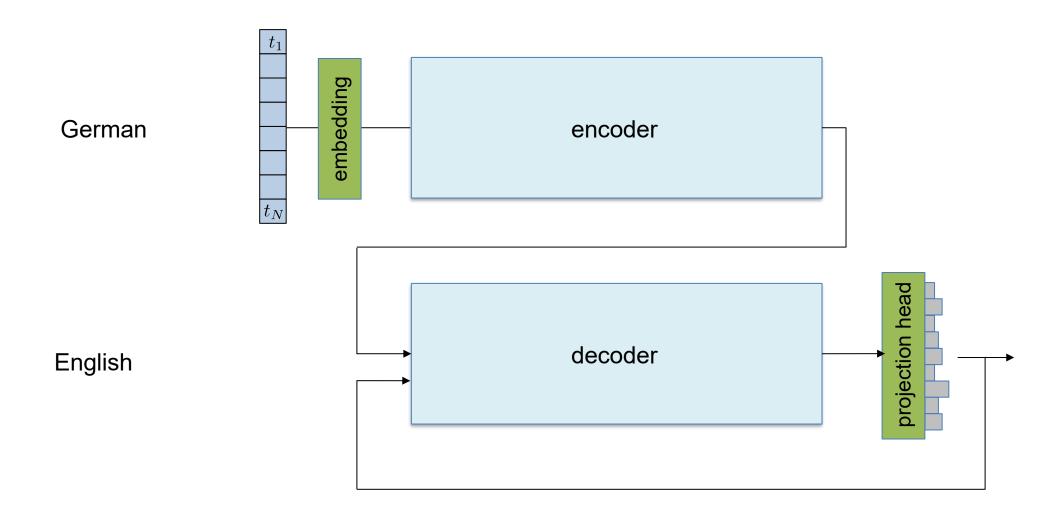




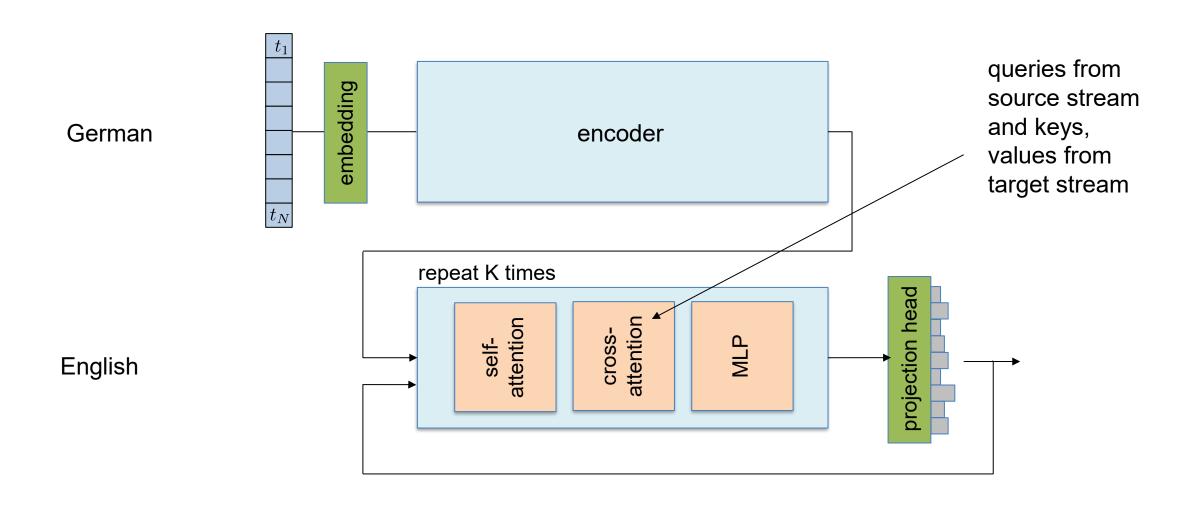




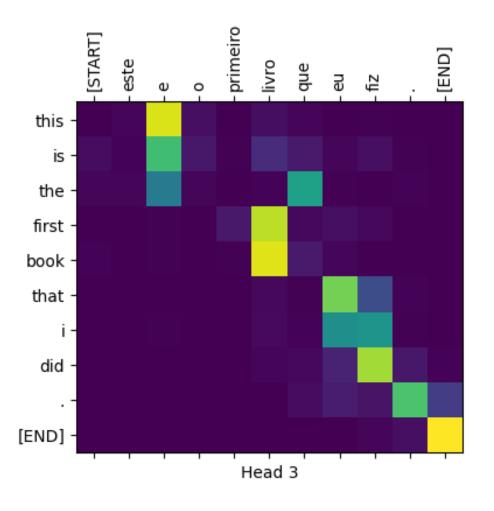




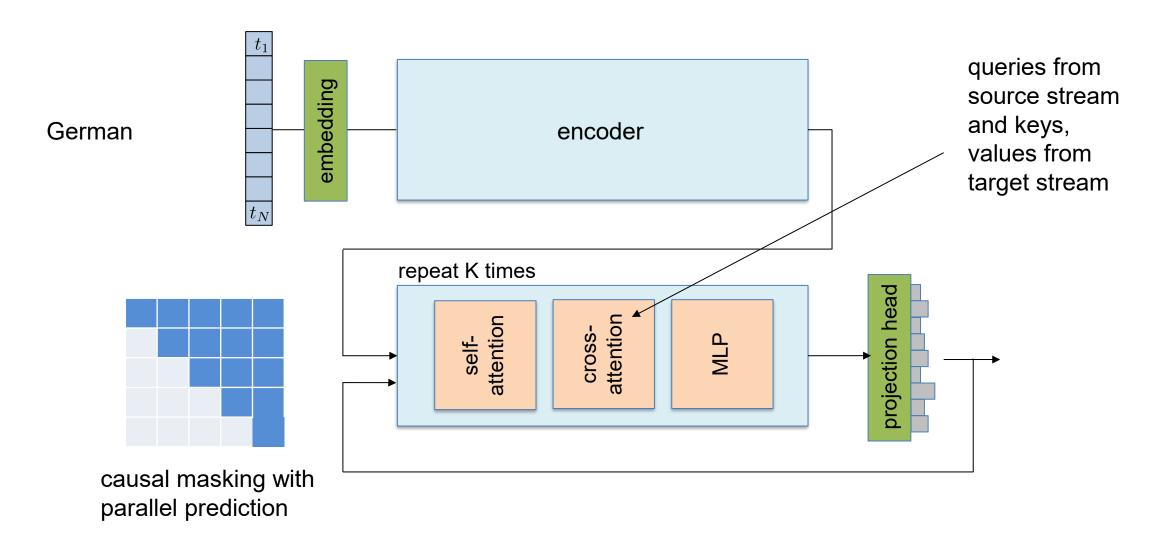














Extensions

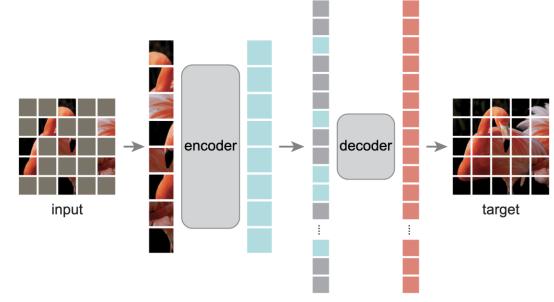
Sparse attention

- Problem to solve: Attention is quadratic which quickly limits the number of tokens one can process
- Sparse attention computes attention only between "likely" relevant tokens, e.g. nearby ones in a temporal stream
- Shared kv's between heads
- qk LayerNorm
 - Additional layer norm in attention head (important for large models)



Why Use Transformers?

- The pros: Flexibility
 - Agnostic to the structure of the problem at hand
 - Missing values can be handled naturally
 - Scalable through parallelization



He, K., Chen, X., Xie, S., Li, Y., Dollár, P., & Girshick, R. (2022). Masked autoencoders are scalable vision learners. In *Proceedings of the IEEE/CVF conference on computer vision and pattern recognition* (pp. 16000-16009).

- The cons: Cost
 - Little inductive bias (requires more data to learn the task at hand)
 - High memory footprint



Diminishing Role of Architecture

"Our work reinforces the bitter lesson. The most important factors determining the performance of a sensibly designed model are the compute and data available for training. [...]"

Smith et al., ConvNets match Vision Transformers at Scale, https://arxiv.org/pdf/2310.16764.pdf



Summary

- Transformer are standard neural network in many applications
- Sequence-to-sequence model operating on a set/sequence of tokens
- Versatile since only the definition of a token and the embedding network is domain specific
- Computationally highly efficient since software and hardware is optimized for them
 - But sparse attention required in general

