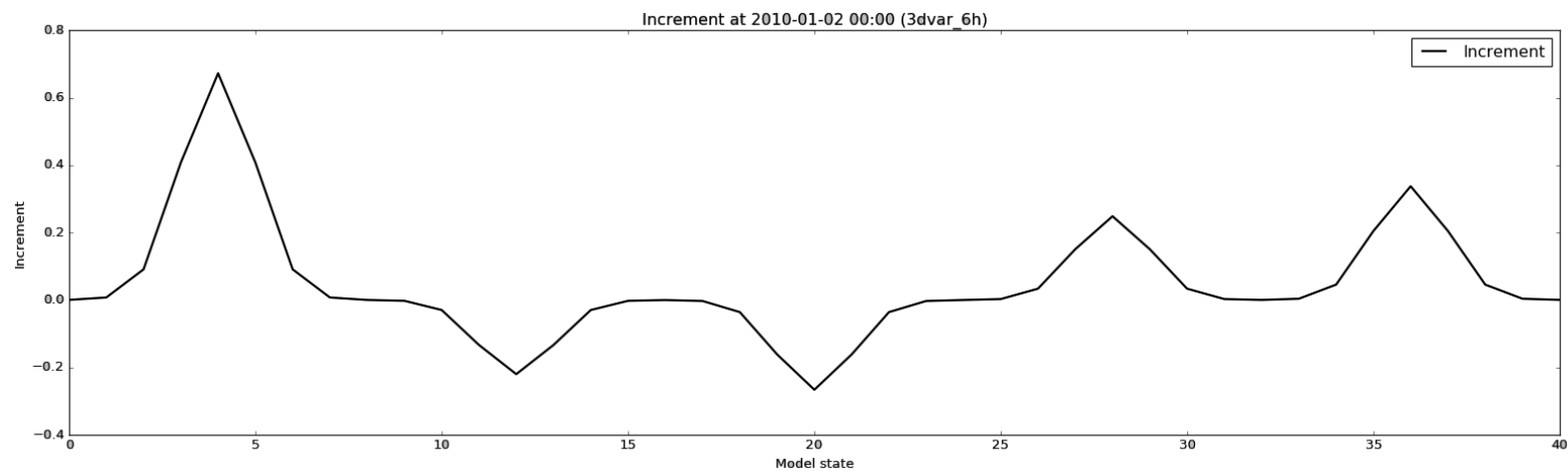
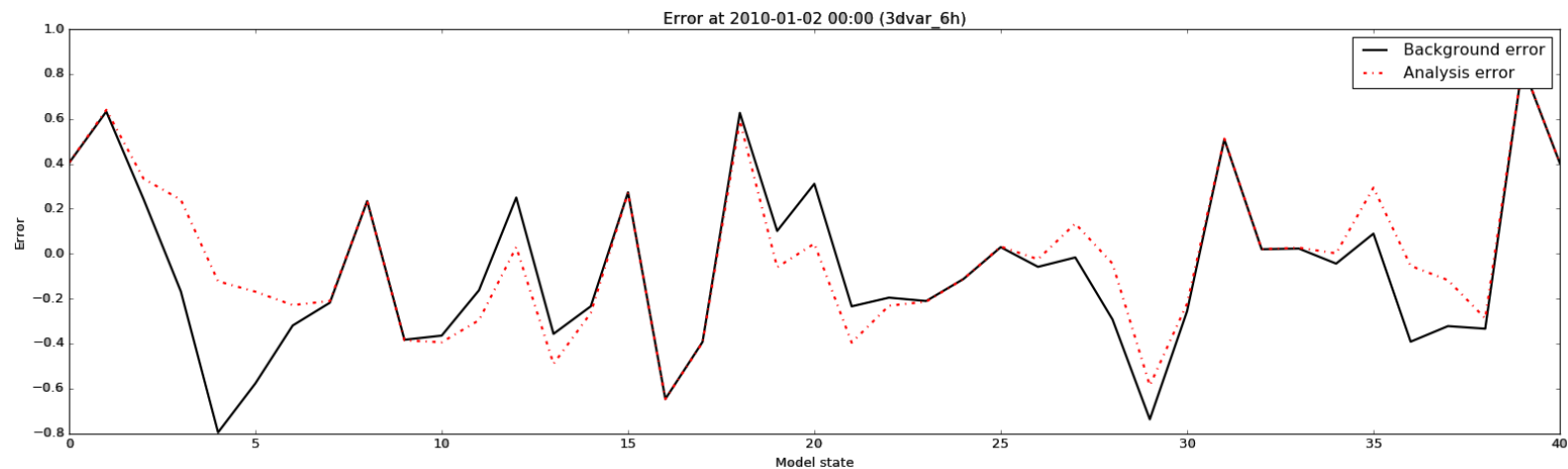


# Highlights of the data assimilation practical session

Patrick Laloyaux, Marcin Chrust, Massimo Bonavita

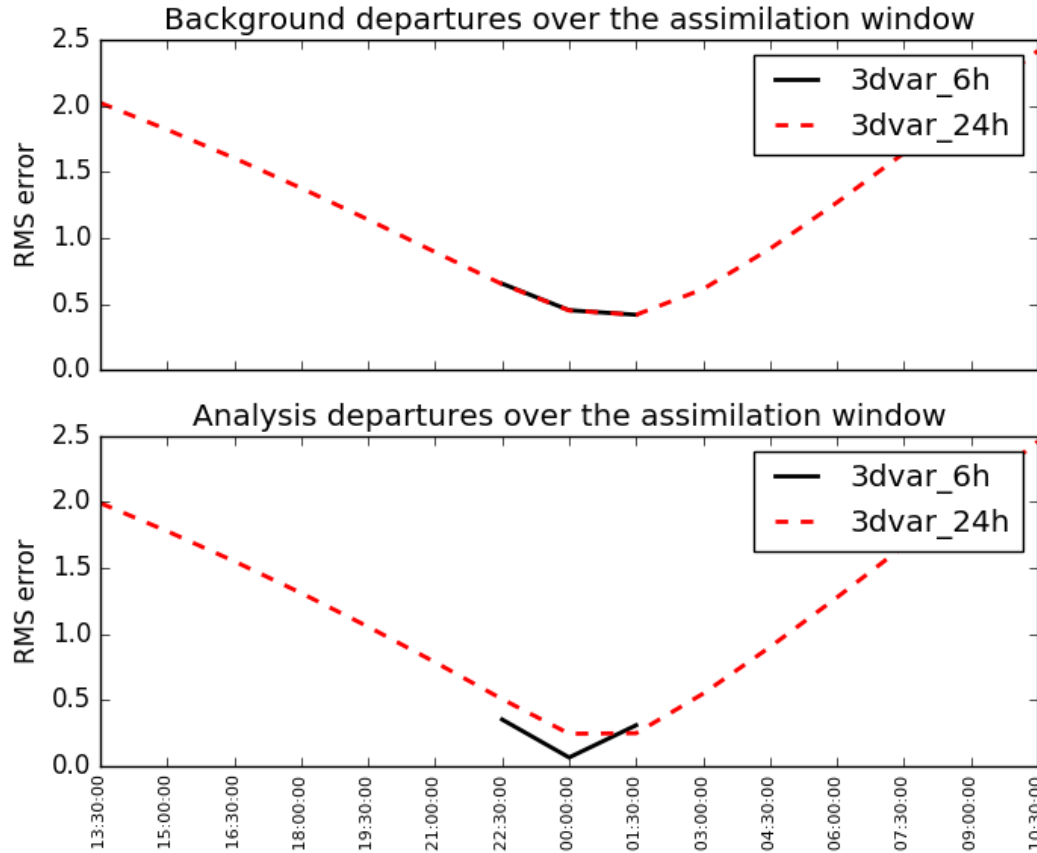
# Assimilating observations



Increment corrects the background and produce an analysis closer to the observations

The background error covariance matrix  $B$  spreads the information in space

# 3D-Var with a 6-hour and 24-hour assimilation window

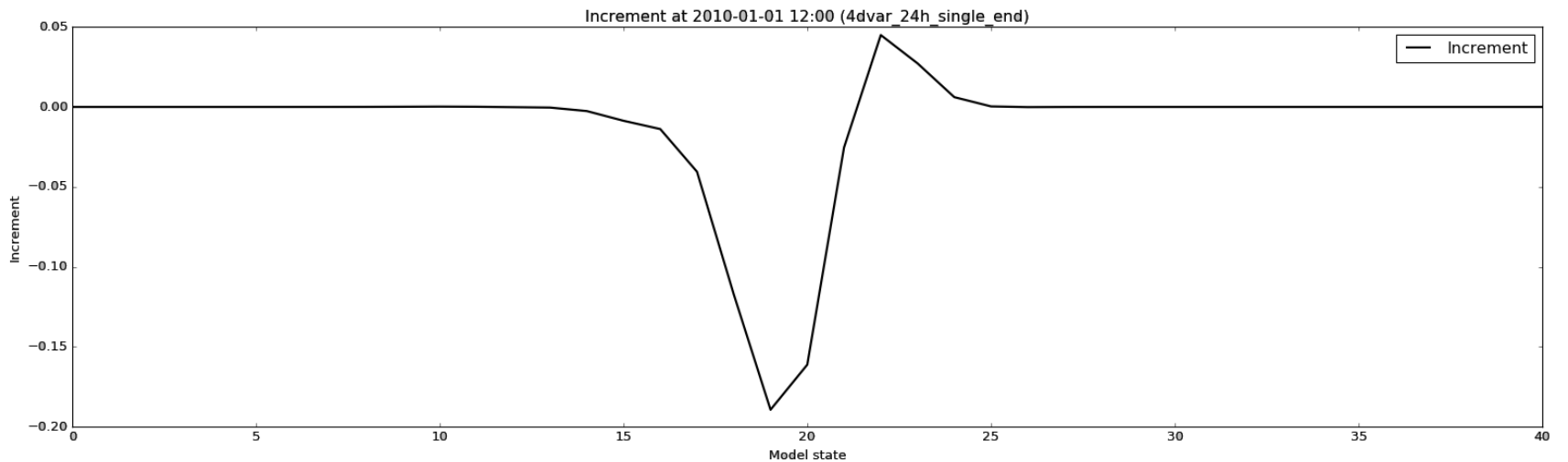
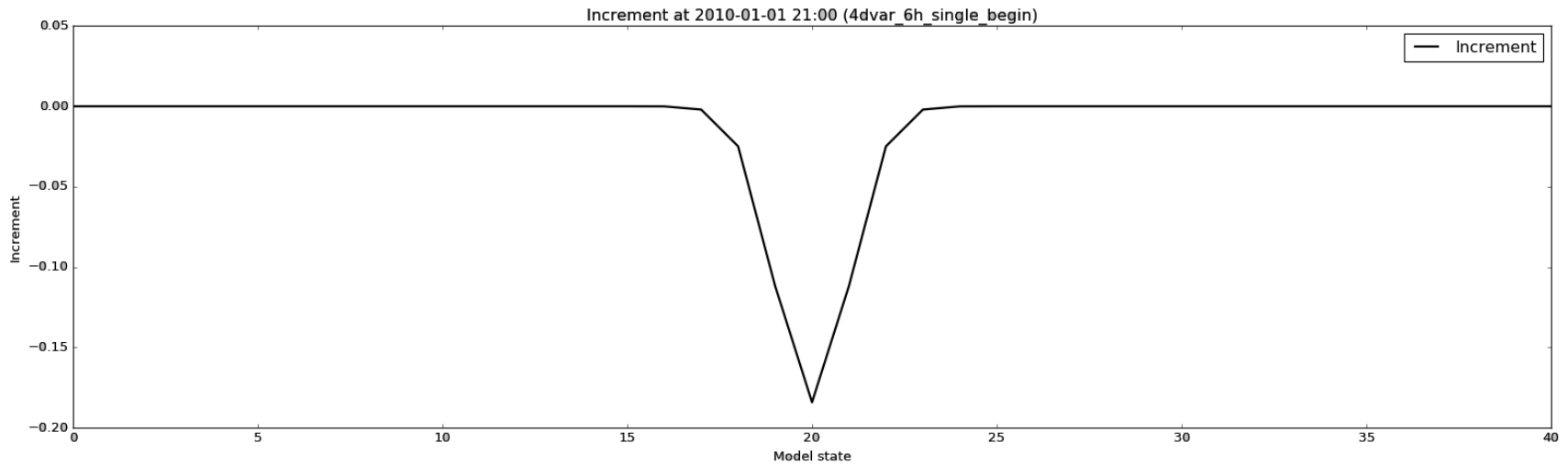


3D-Var assumes that all observations are available at the middle of the window

When the window is increasing, the background departures are large as the dynamical model is not taken into account

3D-Var cannot fit the observations at the beginning/end of the window

# How information is spread in 3D-Var and 4D-Var



Information is spread with B in 3D-Var

Information is spread with B and M in 4D-Var