

Evolution of observations usage in the ECMWF Operational atmospheric NWP system

Mohamed Dahoui, Anthony McNally, Ersagun Kuscu
ECMWF, Shinfield Park, Reading, UK

Evolution of data counts and availability

Observations play a crucial role in Numerical Weather Prediction (NWP). They are the primary input to the data assimilation, the process that combines observational data with the dynamical and physical information represented in numerical models. The resulting analysis is used to initialise weather forecasting models. Observations availability and usage evolved rapidly since the establishment of ECMWF. Over the years, the volume and diversity of data have increased significantly. Data assimilation techniques have also evolved from simple Optimal Interpolation algorithms to sophisticated variational methods that make extensive use of satellite observations. The evolution was marked by small incremental changes, and major upgrades implemented in between allowing substantial improvements in forecast skill.

Currently, ECMWF receives 800 million observations daily, and 60 million quality-controlled observations are available daily for use in the Integrated Forecasting System (IFS). The vast majority of these are satellite measurements, but ECMWF also benefits greatly from all available observations from non-satellite sources, including surface-based and aircraft reports. The evolution of in-situ observations is slow but has a steady upward trend. Satellite data availability varies with mission lifetime, outages/failures and the launch of new satellites. The exploitation of a new instruments is influenced by the scientific and technical readiness which are complex for novel data and relatively simple for data with known heritage technology.

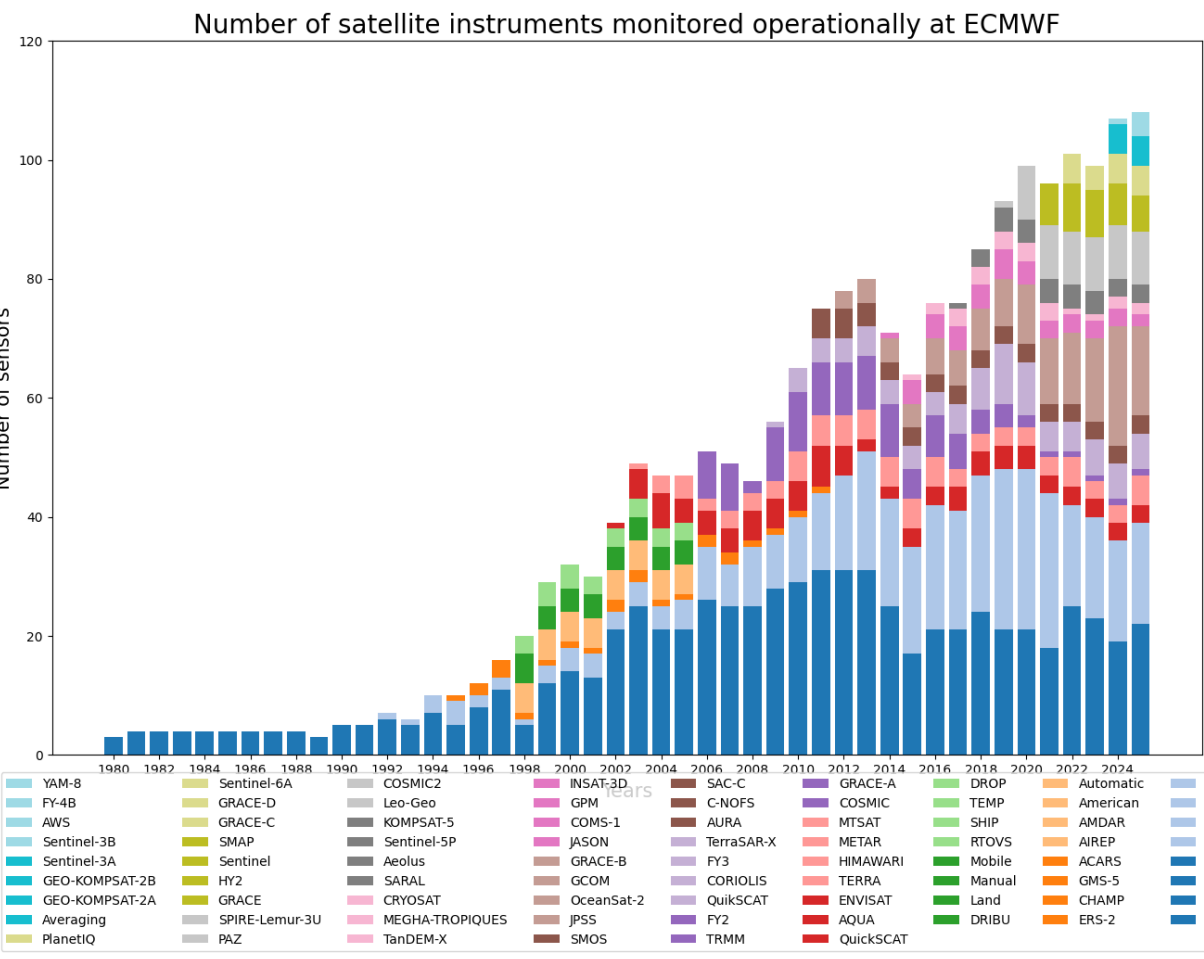


Fig 1: Evolution of data sources operationally monitored at ECMWF

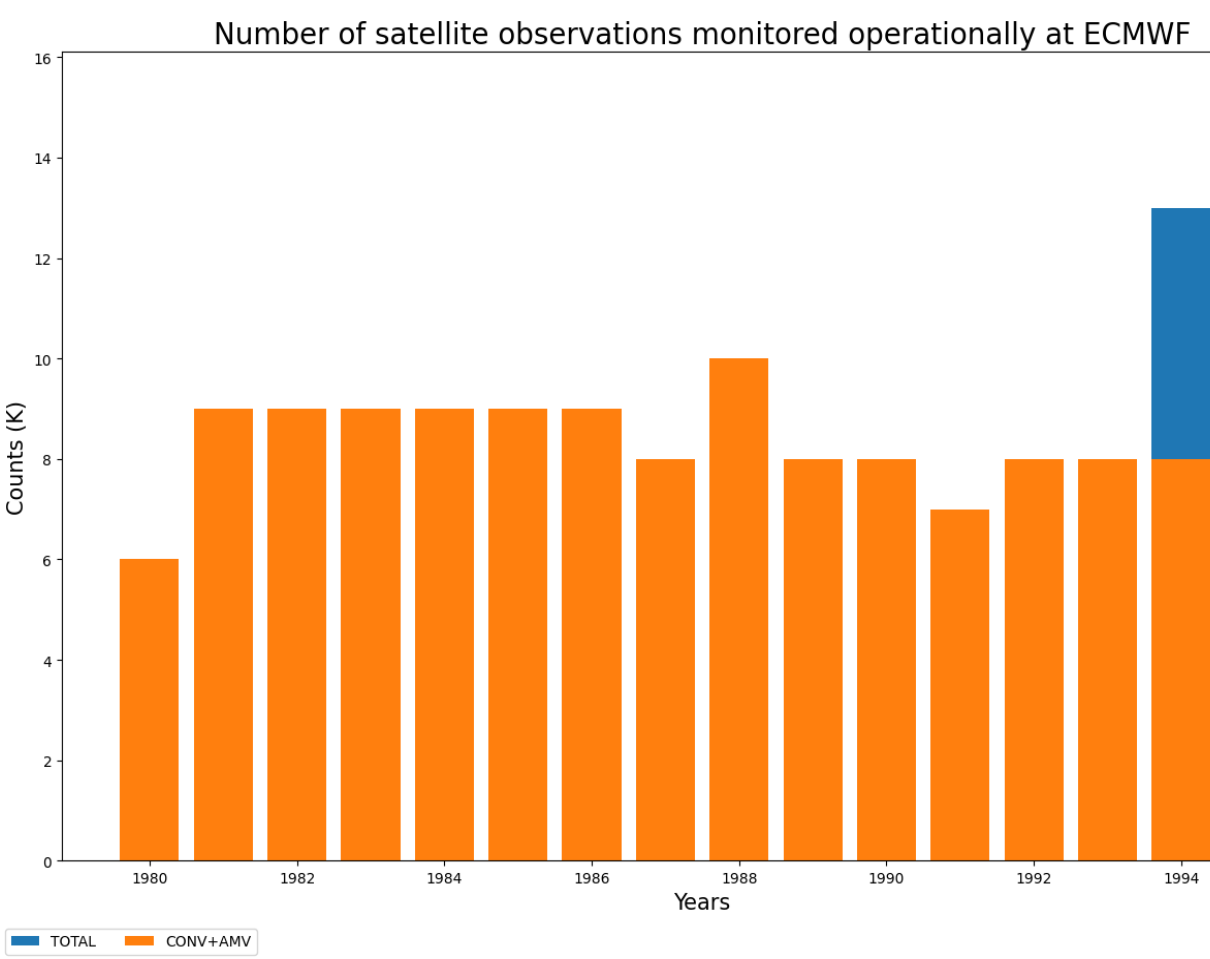


Fig 2: Evolution of data counts operationally monitored at ECMWF pre 1996 in thousands (left) and after 1996 in millions (right)

Impact of assimilating observations

Over the past decades, the skill of weather forecasts has continued to increase. A large part of this improvement is driven by the enhanced use of observations in both data assimilation and forecast verification. The impact of observations on analyses and forecasts depends on the availability of datasets, their intrinsic quality, and the data assimilation methods employed. The incremental inclusion of new datasets, together with continuous optimisation of the assimilation framework, has led to steady improvements in forecast quality across all time ranges. A striking example is the combined implementation of four-dimensional variational assimilation (4D-VAR) and the direct use of satellite radiances, which sharply reduced the forecast skill gap over the Southern Hemisphere (Fig. 3).

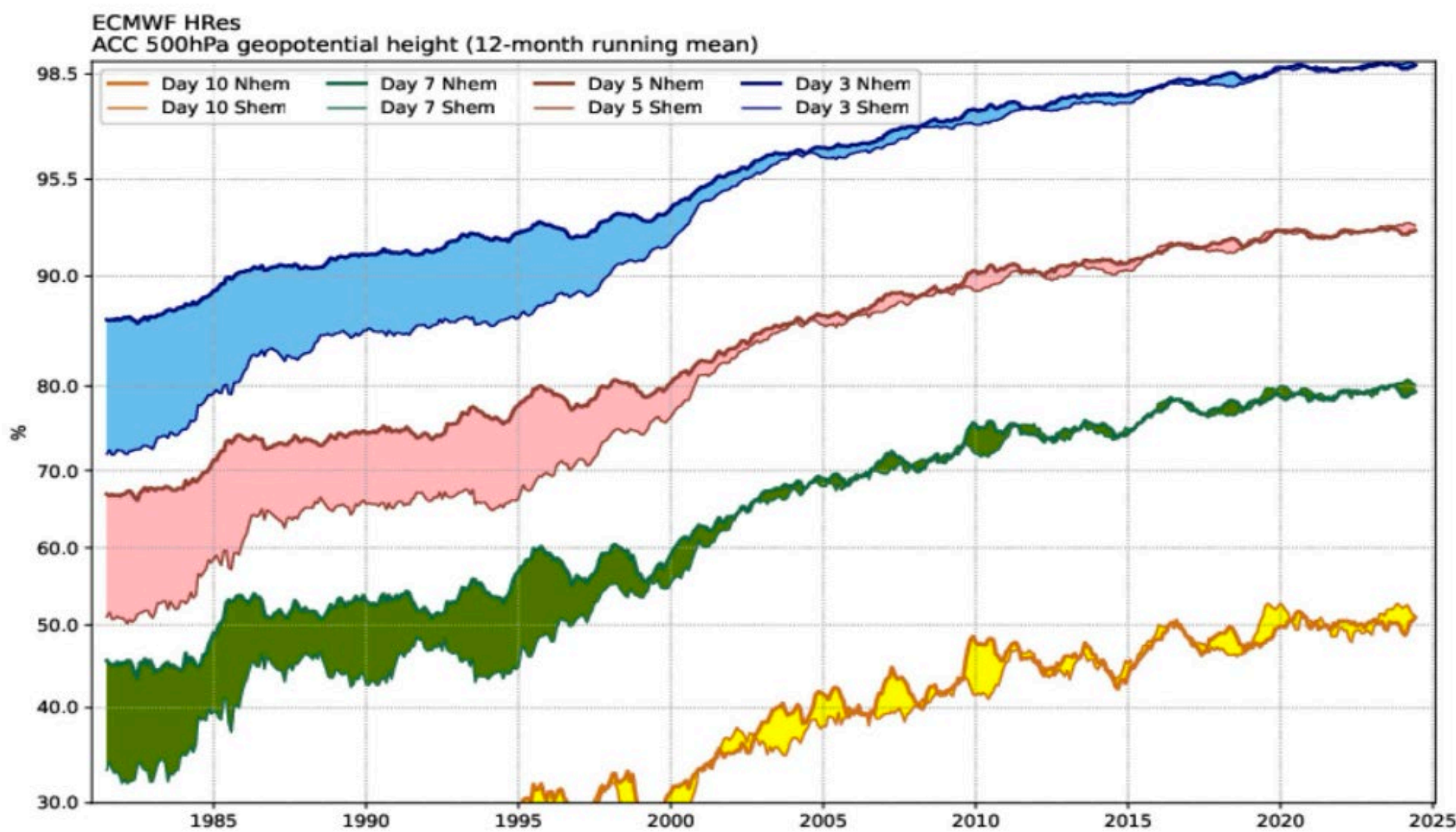


Fig 3: Evolution of ECMWF HRES Anomaly correlation scores for both Hemispheres

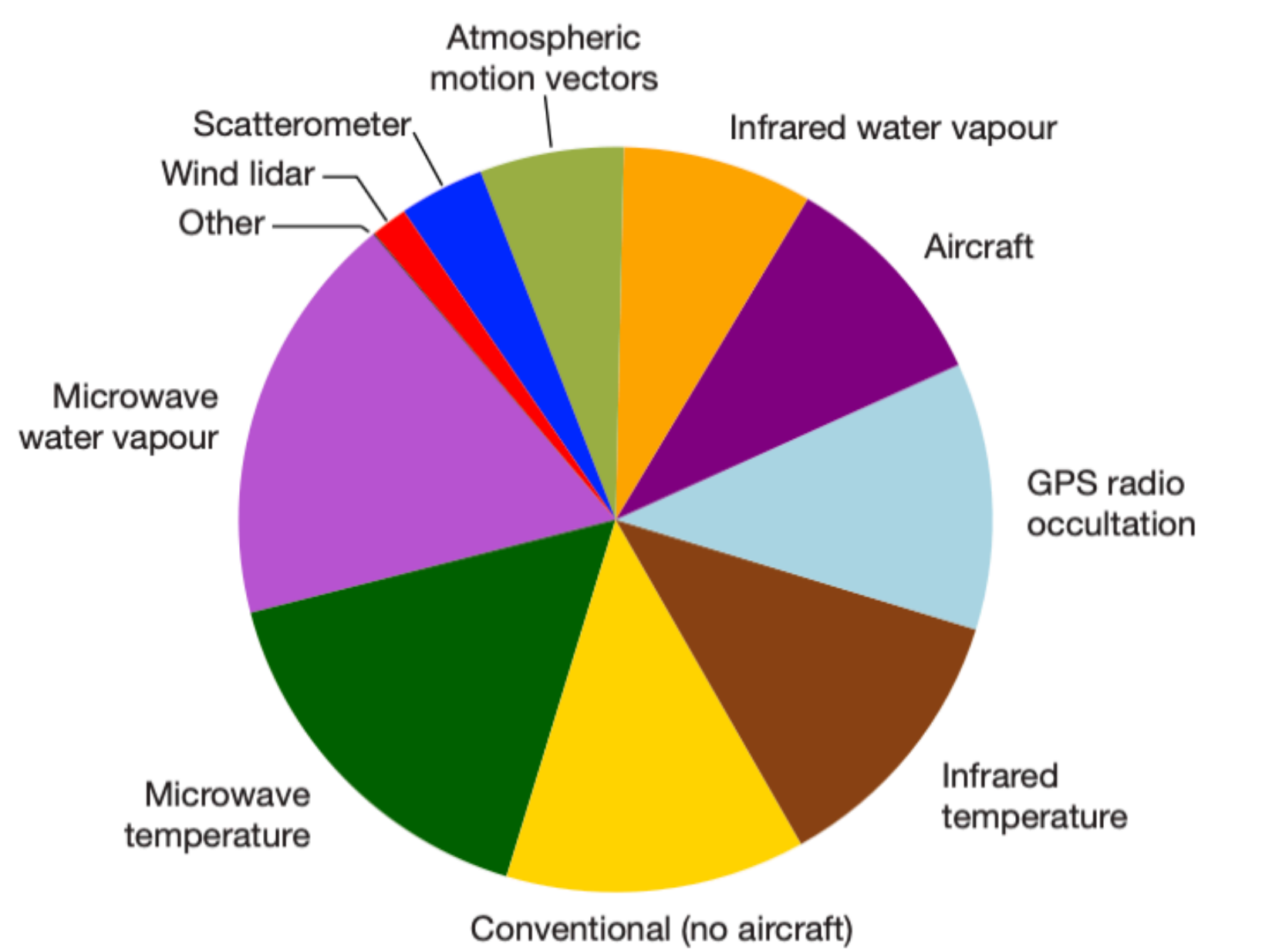


Fig 4: Relative FSOI contribution from observation types assimilated at ECMWF

Monitoring of observations

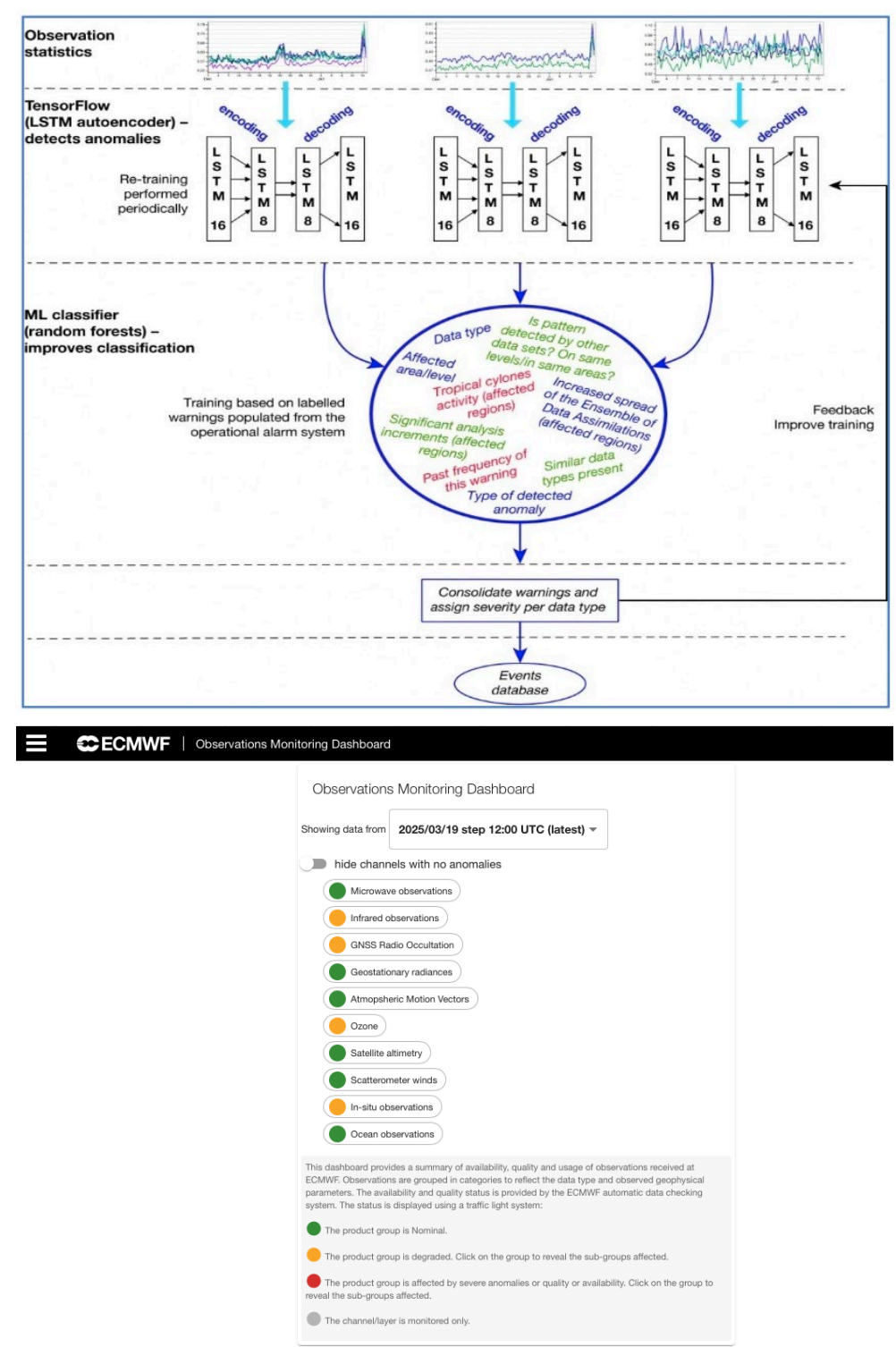
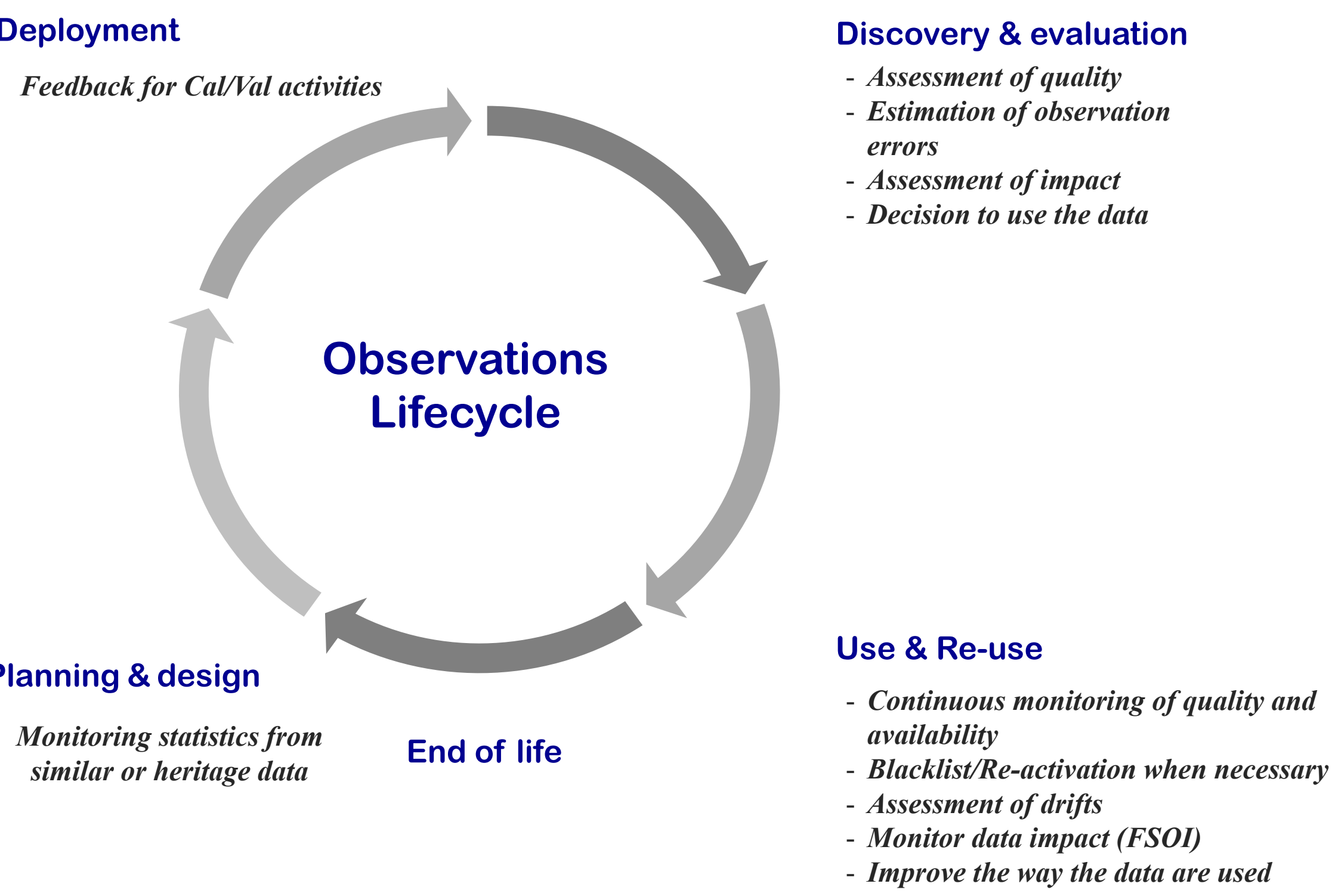


Fig 5: Snapshot of the ML anomaly detection and the observing system dashboard

Future evolution of observations and their handling

The global observing system is expected to expand significantly over the coming years, driven by a large set of already-committed operational and research satellite missions from major space agencies. The geostationary ring (apart from the Indian Ocean region) is expected to be fully populated with hyperspectral infrared sounders, offering high spectral, spatial, and temporal coverage. The first MTG and EPS-SG satellites are already in orbit, and testing and evaluation activities are well under way. The Sterna constellation will boost the microwave coverage and provide access to more orbital planes. China will continue to develop its successful FY-3 and HY polar-orbiting series alongside the FY-4 geostationary program. From NOAA, we anticipate continued JPSS missions and the introduction of a new geostationary system that includes a hyperspectral IR sounder. Japan is also preparing the next generation of Himawari satellites, which will feature both an advanced imager and a hyperspectral sounder. The involvement of the private sector is increasing, both for in-situ observations (e.g. Windborne, Saildrone) and for space-based missions such as GNSS-RO constellations and small microwave satellites. Interest is also growing in IoT-based observations, with parallel work underway on governance, data sourcing, and the technical infrastructure required for pre-processing and quality control.

Data assimilation techniques are expected to continue advancing, with more focus on extracting more information in challenging regions and conditions. Progress will likely come from hybrid methods that combine machine-learning components with established legacy schemes, as well as from more fully end-to-end machine-learning approaches such as GRAPH-DOP.

Timeline of key observation changes

1979 >

- 3D Optimal Interpolation (OI) and non-linear normal mode initialisation

1980 >

- SYNOP, SHIP, Radiosondes, AIREP, PILOT

1981 >

- SATEM (Satellite derived profiles of temperature and humidity) from 1980s

1982 >

- Satellite derived winds (geostationary satellites)

1983 >

1984 >

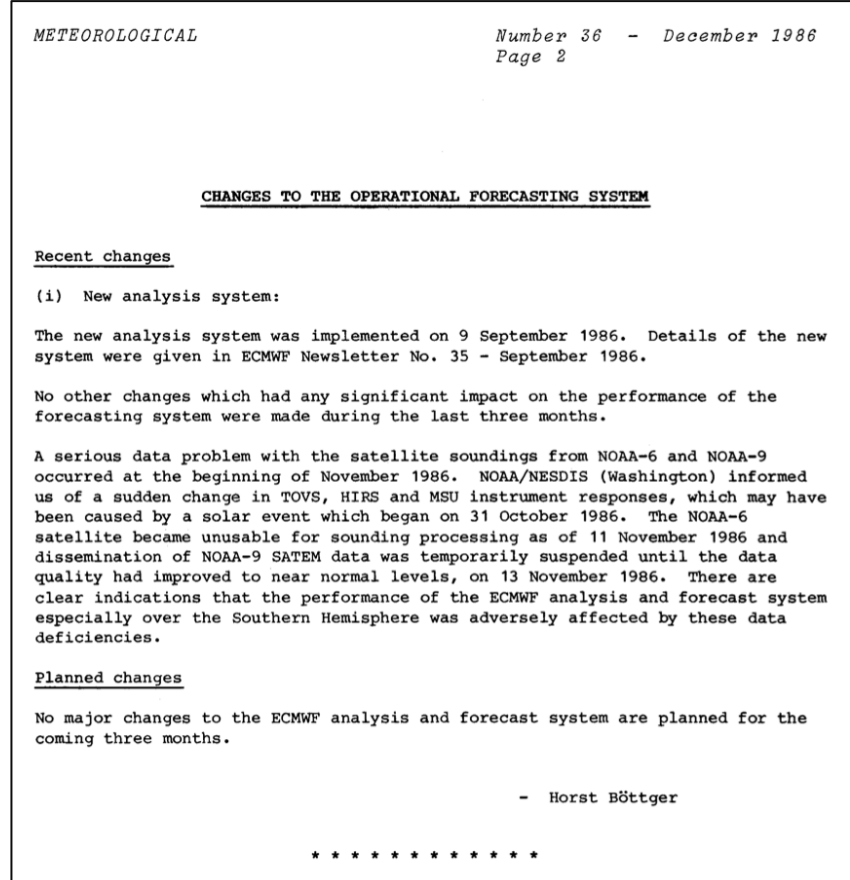


Fig 8: Extract of operational changes in 1986

1985 >

1986 >

1987 >

1988 >

1989 >

1990 >

1991 >

- Scatterometer (ERS)

1992 >

1993 >

1994 >

1995 >

1996 >

- 3D-VAR assimilation
- 4D-VAR assimilation

1997 >

1998 >

- Multiple Aircraft data sources
- Cloud cleared TOVS radiances
- METEOSAT-7 (AMVs)
- Direct assimilation of raw satellite radiances (TOVS/ATOVS)

1999 >

2000 >

2001 >

2002 >

- Geostationary radiances

2003 >

2004 >

- 1st Hyperspectral IR (AIRS)

2005 >

- SSMIS, AMSR-1, MET-8

2006 >

- Assimilation of GNSS-RO
- Metop-A (AMSUA, MHS, ASCAT, HIRS, GRAS)
- TMI
- Metop-A/IASI
- Jason-1, Jason-2

2007 >

2008 >

- METEOSAT-9
- MW in all-sky
- MTSAT-2, GOES-13, GOES-15
- EDA implementation

2009 >

- METEOSAT-10

2010 >

2011 >

- NPP/ATMS, Metop-B (IASI,AMSUA,MHS,ASCAT,GRAS)

2012 >

- AMSR2, FY-3B/MWHS

2013 >

- NPP/CrIS, GPM

2014 >

- FY-3CMWHS-2, HIMAWARI-8, GOES-16, Jason-3, MEGHA-TROPIQUE/SAPHIR
- BUFR migration started for SYNOP and radiosondes

2015 >

- MET-11, NOAA-20 (ATMS, CrIS, VIIRS AMVs)

2016 >

- Metop-C (AMSUA, MHS, ASCAT, GRAS, IASI), GOES-17

2017 >

- Aeolus, MODE-S, Commercial GNSS-RO, FY-3D/MWHS2

2018 >

- HY-2B

2019 >

- HIMAWARI-9

2020 >

- GOES-18

2021 >

- NOAA-21 (ATMS, CrIS)

2022 >

- AWS, MTG/FCI, Global MODE-S, GOES-19

2023 >

- EarthCare, MTG-S1, METOP-SG-A1
- Visible reflectances

2024 >

2025 >

2026 >

2027 >

2028 >

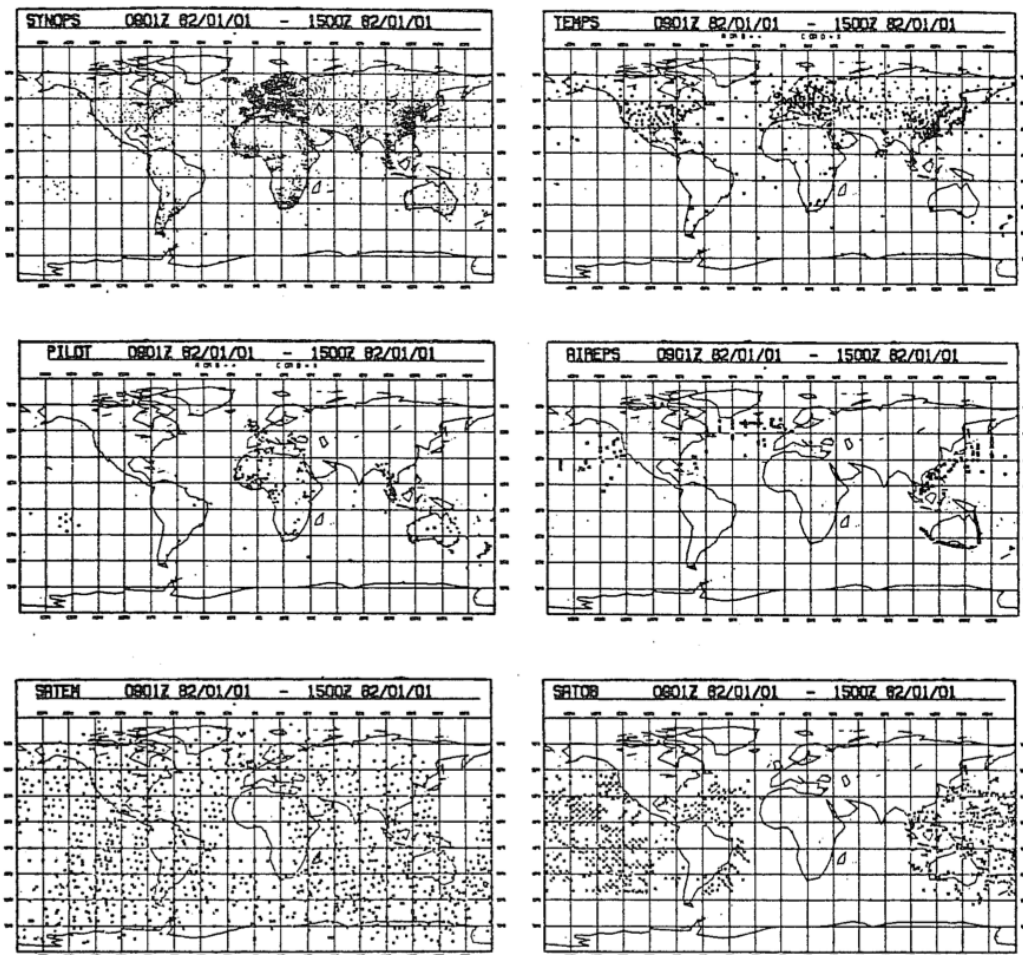


Fig 6: Observing system Jan 1980. A. Mohr
ECMWF Annual Seminar Sep 1984

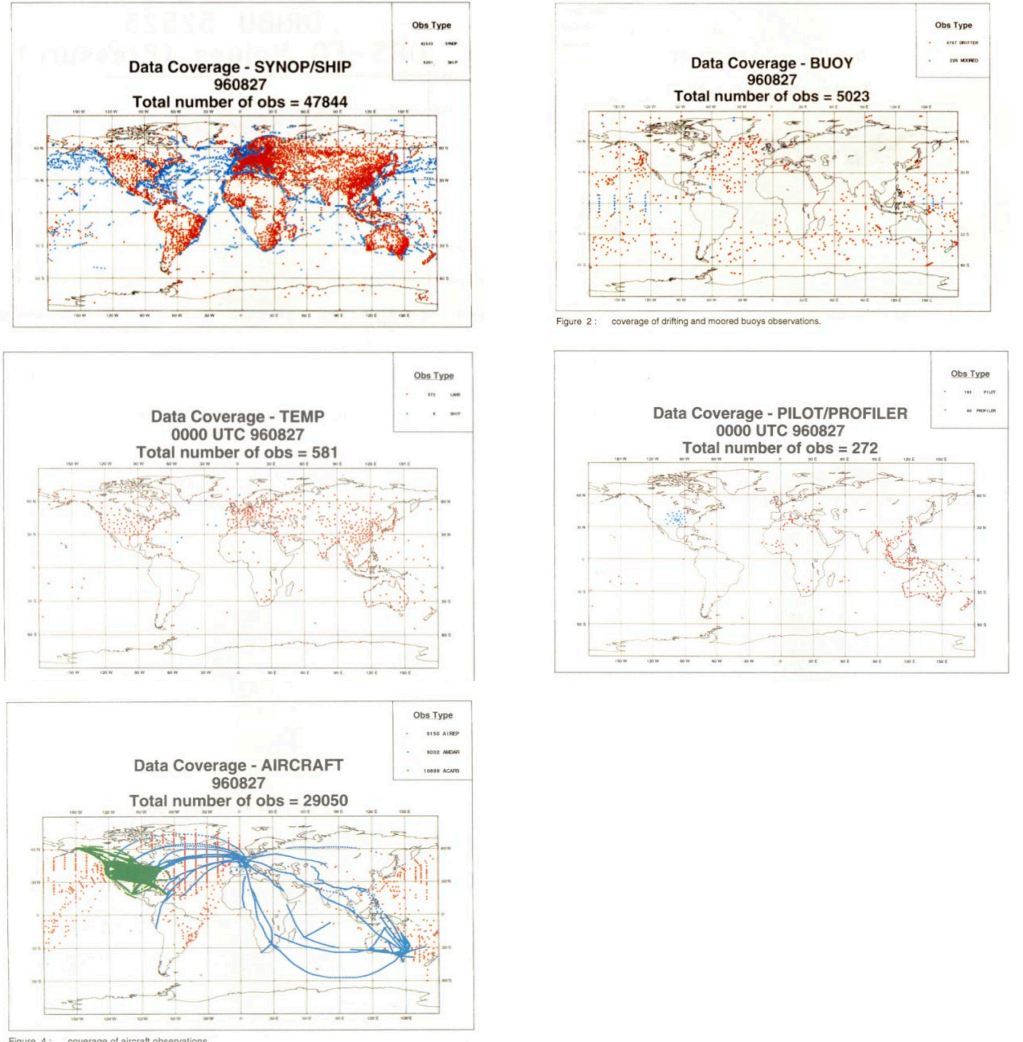


Fig 7: Observing system Aug 1996. B. Strauss
ECMWF Annual Seminar Sep 1996

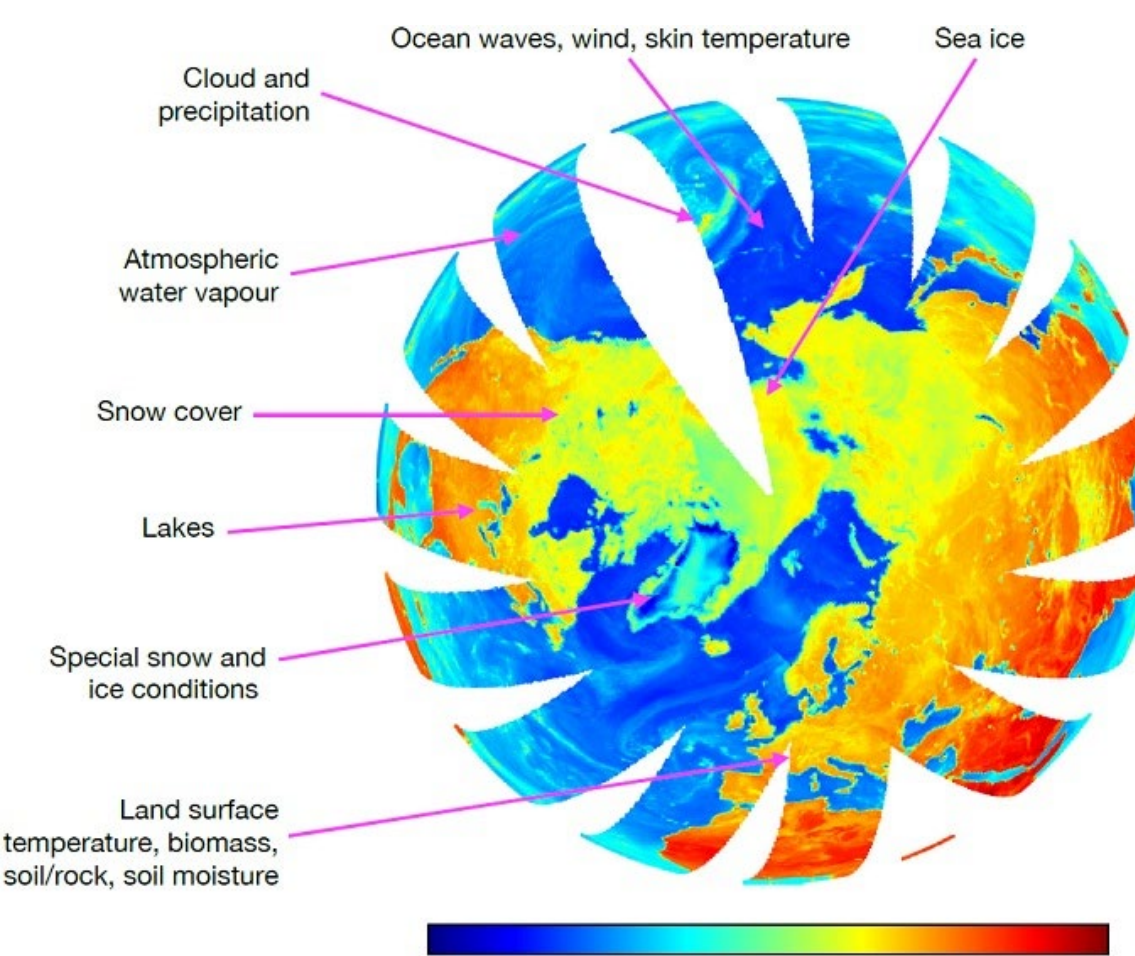


Fig 9: Assimilating MW in All-sky enabled access to new information especially in the surface

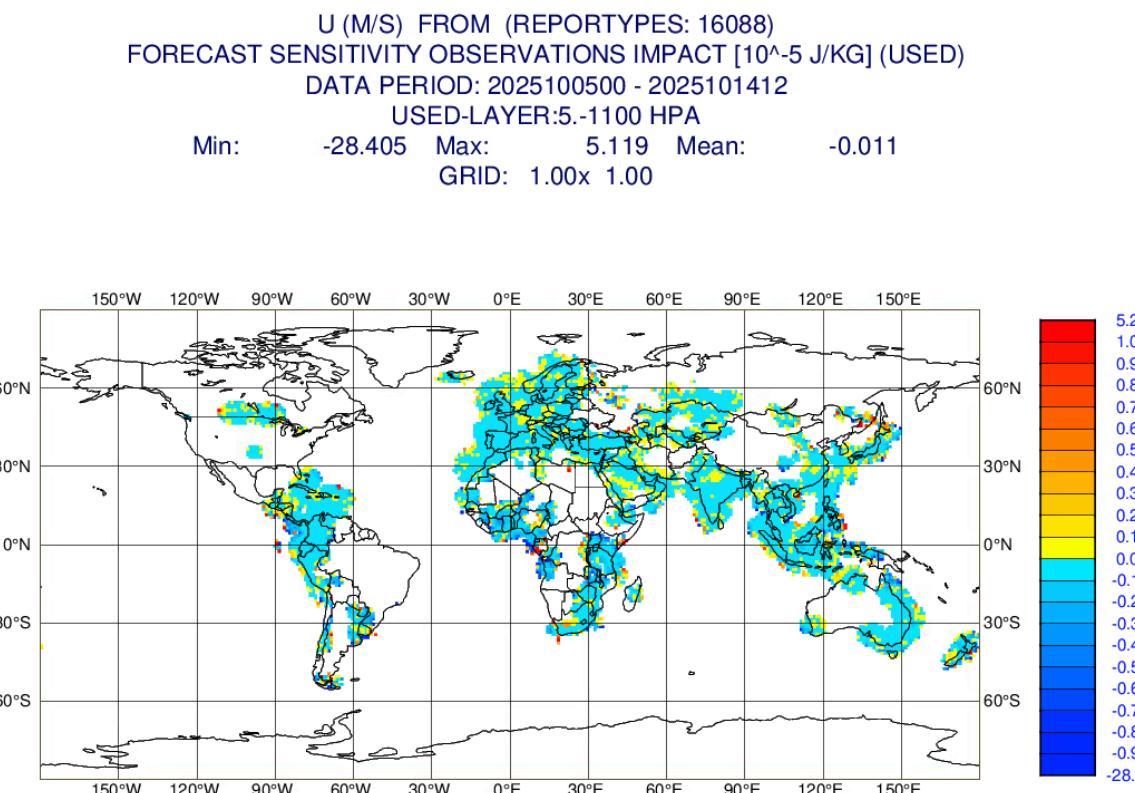


Fig 10: Positive impact (measured by FSOI and OSEs) from assimilating Global MODE-S

<https://confluence.ecmwf.int/display/FCST/Observations+data+events>

Acknowledgments

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